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Trigger-When-Charged: A technique for directly measuring RTN and BTI-induced threshold voltage fluctuation under use-Vdd

A. Manut, R. Gao, J. F. Zhang, Z. Ji, M. Mehedi, W. Zhang, D. Vigar, A. Asenov, and B. Kaczer

Abstract — Low power circuits are important for many applications, such as IoT. Device variations and fluctuations are challenging their design. Random telegraph noise (RTN) is an important source of fluctuation. To verify a design by simulation, one needs assessing the impact of fluctuation in both driving current, ΔI_d , and threshold voltage, ΔV_{th} . Many early works, however, only measured RTN-induced ΔI_d . ΔV_{th} was not directly measured because of two difficulties: its average value is low and it is highly dynamic. Early works often estimated ΔV_{th} from $\Delta I_d/g_m(V_g=V_{dd})$, where g_m is trans-conductance, without giving its accuracy. The objective of this work is to develop a new Trigger-When-Charged (TWC) technique for directly measuring the RTN-induced ΔV_{th} . By triggering the measurement only when a trap is charged, measurement accuracy is substantially improved. It is found that there is a poor correlation between $\Delta I_d/g_m(V_g=V_{dd})$ and the directly measured $\Delta V_{th}(V_g=V_{th})$. The former is twice of the latter on average. The origin for this difference is analyzed. For the first time, the TWC is applied to evaluate device-to-device variations of the directly measured RTN-induced ΔV_{th} without selecting devices.

Index terms: Random telegraph noise (RTN), Fluctuations, Yield, Within-a-device-fluctuation, Jitters, Positive charges, NBTI.

I. INTRODUCTION

As CMOS nodes scale down, the fluctuations induced by random charge-discharge of traps scale up. Smaller devices have larger statistical spread because of fewer traps per device and the larger impact of a single charge on them [1,2]. The increased number of devices per chip also leads to larger statistical spread [1,2] and high data transmission rate requires tight control of fluctuations [3]. Fluctuations have become a major concern for circuit design and have attracted many attentions recently [4-20]. It has been reported that current fluctuation in some fresh devices can be over the typical device lifetime criterion of 10% [5].

Fluctuations are commonly observed as the random telegraph noise (RTN) in the drain current, ΔI_d , under a given

gate bias, V_g , and early works [5-13] have focused on them. ΔI_d allows probing individual traps and an analysis of their mean capture and emission time dependence on V_g gives the trap energy and spatial locations [5, 6, 8, 10]. This has improved our understanding substantially. There are, however, little direct measurements of the RTN-induced fluctuation in threshold voltage, ΔV_{th} . This is because its measurement is difficult: the charge-discharge of traps for RTN is highly dynamic and the average ΔV_{th} is typically low. As a result, the RTN-induced ΔV_{th} often was either not given [5,11] or estimated from dividing ΔI_d by trans-conductance, i.e. $\Delta V_{th} \approx \Delta I_d/g_m(V_{dd})$ [6-10]. The accuracy of the ΔV_{th} evaluated in this way was not given in these works [6-10].

To model the impact of RTN on the margin of SRAM [15] and the timing error [14], one needs both ΔI_d and ΔV_{th} . For example, RTN in the pass transistor 1 in Fig. 1a can reduce the driving current by ΔI_d and slow down the V_g rise of transistor 2 in reaching its threshold voltage, V_{th0} , by $\Delta t(\Delta I_d)$. RTN in the transistor 2 can increase its V_{th} by ΔV_{th} and results in a further delay, $\Delta t(\Delta V_{th})$. There is a need to obtain both accurate ΔI_d and ΔV_{th} , therefore.

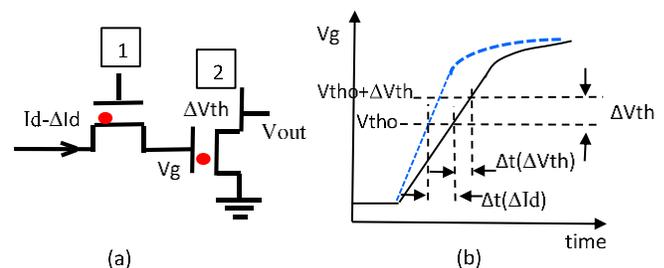


Fig. 1. A schematic illustration of the impact of ΔI_d and ΔV_{th} on timing: (a) circuits and (b) waveform. V_{out} switches when $V_g \approx V_{th}$, which is delayed by a lower charging current, $I_d - \Delta I_d$, supplied through the transistor 1 and a higher $V_{th} = V_{th0} + \Delta V_{th}$ of the transistor 2.

The objective of this work is to develop a new Trigger-When-Charged (TWC) technique for directly measuring the RTN-induced ΔV_{th} . By ensuring that the measurement is taken when traps are charged, the accuracy is substantially improved. It is found that the $\Delta I_d/g_m(V_{dd})$ correlates poorly with the directly measured ΔV_{th} and the former doubles the latter on

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average. The discrepancy originates partly from the device-to-device variation (DDV) of relative local current density beneath a trap at $V_g=V_{th}$ [16-19] and partly from the charge-induced mobility degradation [20].

Some deeply scaled devices have analyzable RTN signals in terms of extracting mean capture/emission time [11], while others can have a complex within-a-device-fluctuation [12]. The latter was deselected in some early works [10,13,16,17], making the real DDV of fluctuation unobtainable. The TWC developed in this work is applicable to devices with or without analyzable RTN signals and it will be used to evaluate the DDV.

II. DEVICES AND MEASUREMENT TECHNIQUE

A. Devices

The MOSFETs used in this work were fabricated by a 28 nm commercial CMOS process with a use V_{dd} of 0.9 V. They have a metal gate and a high-k dielectric stack with an equivalent oxide thickness of 1.2 nm. The channel width and length are 135 nm and 27 nm, respectively. For comparison purpose, large devices of $3 \times 1 \mu\text{m}$ were also used, which has insignificant DDV. All tests were performed at 125 °C.

B. TWC technique

Difficulties with standard measure-stress-measure methods: For ageing-induced ΔV_{th} under stresses such as negative bias temperature instability (NBTI) [21,22] and hot carriers [23,24], the degradation is commonly measured at preset time. This is acceptable, as the V_g -acceleration used in the stress generally leads to a large-enough ΔV_{th} that is measurable and deterministic at a preset time. There are, however, two difficulties in applying this method to deeply scaled devices under use- V_{dd} , where ΔV_{th} mainly exhibits as Random Telegraph Noise (RTN). First, there are only a few active traps and the average ΔV_{th} is typically low. Second, charge-discharge of these traps are highly dynamic: they are often neutral at the preset time for measurement, as shown by the red circle symbols in Fig. 2, and would be missed by the measurement.

One way to avoid these difficulties is selecting devices that only have one trap, which induces a high enough ΔV_{th} (e.g. 20 mV) and its emission time is long enough (e.g. >1 sec) for completing the measurement [16,17]. This has improved our understanding of the interaction between a trap and the current. Such devices, however, are rare (e.g. ~10% [16]) and the required device selection precludes obtaining real DDV. The present work develops a new technique that removes the device selection and is applicable to all devices, so that the real DDV can be extracted.

Test procedure of TWC technique: Fig. 2a gives the V_g waveform. After recording the reference I_d - V_g on a fresh device, the test starts by a ‘stabilization’ period of 40 sec under $V_g=V_{dd}=-0.9$ V. If there are any traps at deep energy level in a device, they will be filled during this period [25]. ΔI_d under

$V_g=-0.9$ V is then monitored for a period, e.g. 100 sec, as marked by ‘Id monitor’ in Fig. 2a. A sampling rate of 1 M/sec was used [26]. The trapping-induced up-envelope (UE) of ΔI_d is obtained.

To measure the trapping-induced ΔV_{th} , one must ensure that the measurement was taken when the traps are charged. This is achieved by setting the trigger level of the oscilloscope and the pulse generator for V_g just below the UE, as shown in Figs. 2a&b. Once triggered, the pulse I_d - V_g (p-IV) is recorded in 3 μs to minimize discharge [25,26].

Although a sampling rate of 1 M/sec can be used to monitor ΔI_d under a fixed $V_g=-0.9$ V, it only gives 3 points in 3 μs and is too slow for the p-IV. To have sufficient number of points for p-IV, a higher rate of 100 M/sec is used. The p-IV was repeatedly measured for 50 times and their average is used to reduce the system noise to ~1 mV.

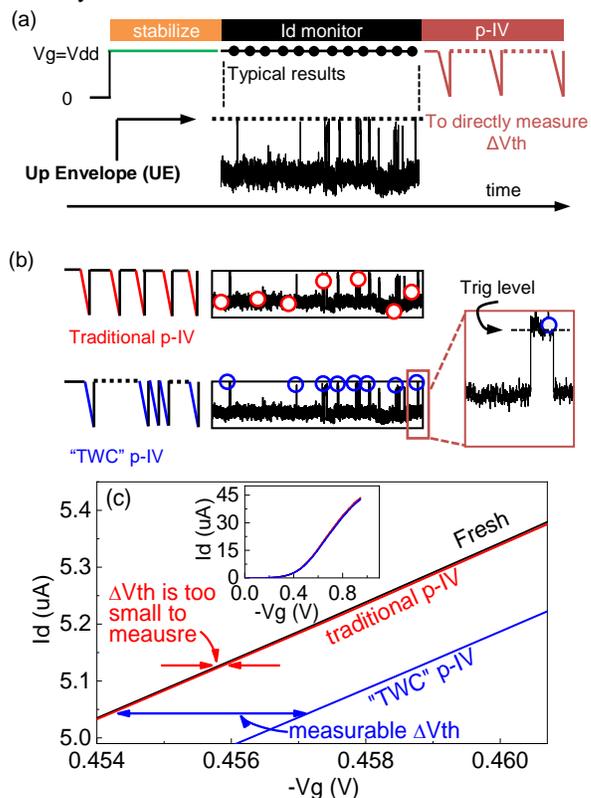


Fig. 2. The TWC technique. (a) Test procedure: After a stabilization period, the RTN-induced ΔI_d is monitored under $V_g=V_{dd}$ and the upper envelope (UE) is determined. The trigger-level for subsequent p-IV (3 μs) is then set just below UE to measure ΔV_{th} . 50 p-IVs were measured in (b) and their average is given in (c). The TWC p-IV captures the RTN-induced ΔV_{th} , while the traditional p-IV at pre-set time often misses the charge and is inapplicable. Both the TWC and traditional p-IVs were taken after the ‘stabilize’ period.

ΔV_{th} is evaluated from the difference between the TWC p-IV and the reference p-IV. The reference p-IV was obtained also from the average of 50 p-IV with the same sweep rate, performed on fresh devices before filling the energetically deep traps by applying the waveform in Fig. 2a. When measuring these 50 p-IV, it is possible that a trap can be filled during the measurement. These outlier p-IVs were excluded from the reference p-IV. This ensures capturing the ΔV_{th} induced by both RTN and energetically deep traps, if they are present. In

case that one is interested in capturing RTN-induced ΔV_{th} only, the reference p-IV should be taken after filling the energetically deep traps. Fig. 2c demonstrates that a single trap induced ΔV_{th} of ~ 2 mV is successfully captured by the TWC technique, which often would be missed by the traditional p-IV recorded at a preset time, as illustrated by the red circles in Fig. 2b. The measured $\Delta V_{th}/\Delta I_d$ ratio is used to convert ΔI_d to ΔV_{th} .

Measurement setup: As the main objective of this work is to develop a technique for measuring the RTN-induced ΔV_{th} under use V_{dd} , the detailed measurement setup is given in Fig. 3. I_d under $V_d=0.1$ V was converted to a voltage, V_{out} , by a home-made operational amplifier circuit. During the ‘ I_d monitor’ phase in Fig. 2a, V_{out} was monitored by both channels 2 and 3 of an oscilloscope and one example is given in Fig. 3b.

In the following ‘p-IV’ phase of Fig. 2a, when V_{out} is above the ‘trigger level’ in Fig. 3c, the oscilloscope triggers and simultaneously sends out a signal to trigger the pulse generator for V_g . Both the pulse applied to the gate and the corresponding V_{out} are captured, as shown in Fig. 3c. Two channels are needed here: channel 3 is at a fine scale to ensure capturing the small V_{out} fluctuation with good accuracy and channel 2 is switched to a coarse scale to capture the whole p-IV. As a comparison, Fig. 3d shows an example triggered at a preset time that missed the trapped charge.

The UE in Fig. 2a can be caused by either a single trap or multiple traps. In the latter case, the UE results from the combined charges of multiple traps. This removes the need for selecting devices of a single trap and makes the method applicable to all devices.

The differences of this work from the typical BTI tests are that the p-IVs are only triggered when traps being charged and V_g -acceleration is not used here.

III. RESULTS AND DISCUSSIONS

A. A comparison between $\Delta I_d/gm(V_{dd})$ and $\Delta V_{th}(V_{th})$

As mentioned in the introduction, early works [6-10] often estimated ΔV_{th} by $\Delta I_d/gm(V_{dd})$, where both ΔI_d and gm were obtained under $V_g=V_{dd}$. This is effectively measuring the shift of IV at $V_g=V_{dd}$, as marked by the point ‘B’ in Fig. 4a and the corresponding inset. The real ΔV_{th} , however, should be evaluated from $V_g=V_{th}$ at the point ‘A’ in Fig. 4a. In this work, V_{th} is extracted by extrapolating from the maximum gm point and $V_{th}=-0.45$ V in Fig. 4a. The shift in V_{th} , ΔV_{th} , at a given sensing V_g is evaluated from $\Delta I_d/gm(V_{gsense})$. We now compare the ΔV_{th} evaluated at $V_{gsense}=V_{th}$ (‘A’ in Fig. 4a) with that at $V_{gsense}=V_{dd}$ (‘B’ in Fig. 4a).

Fig. 4b plots $\Delta V_{th}(V_{th})$ against $\Delta V_{th}(V_{dd})=\Delta I_d/gm(V_{dd})$ measured on 63 devices. Both of them have a large DDV, but the correlation between them is poor. For similar $\Delta I_d/gm(V_{dd})$, ΔV_{th} can spread from its minimum to its maximum approximately. As a result, errors are large if $\Delta I_d/gm(V_{dd})$ is used as ΔV_{th} , so that it is essential to measure ΔV_{th} directly at $V_g=V_{th}$. Although both of them have maximum close to the typical device lifetime definition of 30~50 mV, the average $\Delta I_d/gm(V_{dd})$ doubles that of ΔV_{th} , as shown by the two dashed lines in Fig. 4b. This is because many devices have $\Delta V_{th}(V_{th})$

close to zero, but $\Delta I_d/gm(V_{dd})$ are above 10 mV. The origin of the differences between these two will be analyzed next.

B. Effects of sensing V_g on ΔV_{th}

In Fig. 4a, the sensing V_g for ΔV_{th} is -0.9 V for the point B and $V_{th}=-0.45$ V for the point A. Since the whole $I_d\sim V_g$ was measured, one can also extract the ‘‘apparent ΔV_{th} ’’ at other sensing V_g by using $\Delta I_d/gm(V_{gsense})$. The ‘‘apparent ΔV_{th} ’’ here is referred to the ΔV_{th} evaluated in this way under $V_{gsense}\neq V_{th}$. Typical examples obtained from different devices are given in Figs. 5a-e.

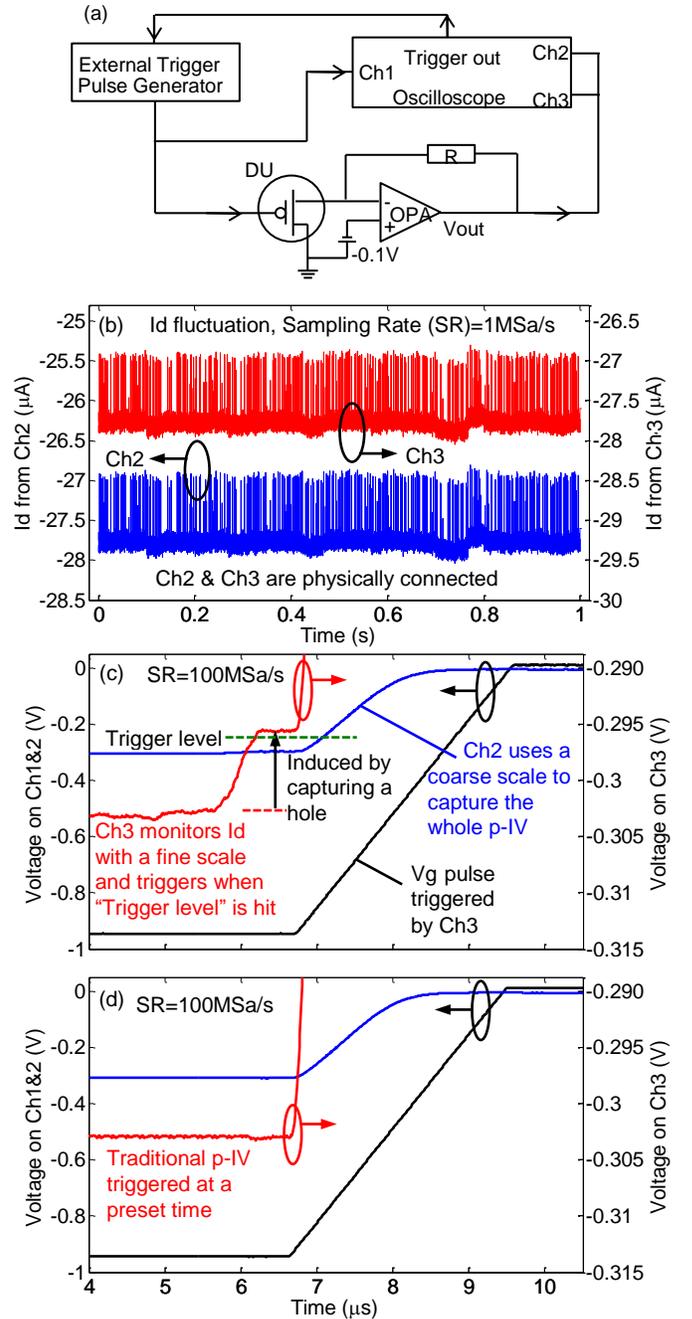


Fig. 3. (a) Test configuration for the TWC measurement technique. A high-speed operational amplifier based circuit is used to convert I_d to V_{out} that is connected to both channels 2 and 3. The ‘‘Trigger out’’ of the oscilloscope is

connected to the “External trigger in” of the pulse generator. (b) The V_{out} fluctuation is captured by both channels 2 and 3, as they are physically connected. (c) A screen-shot of the TWC p-IV measurement waveform. Channel 3 keeps its fine scale for accurate triggering, while channel 2 is switched to a coarse scale to capture the whole “TWC” p-IV. (d) A screen-shot of the traditional p-IV measurement at a preset time, where the trapped charge is missed.

The dependence of the apparent ΔV_{th} on the sensing V_g has strong DDV, agreeing with that observed for single traps [16,17]. On one hand, Fig. 5a corresponds to Fig. 4a, where ΔV_{th} increases monotonically with $|V_g|$ and ΔV_{th} at $|V_g|=0.9$ V is 6 times of the real $\Delta V_{th}(V_{th})$. On the other hand, ΔV_{th} can also reduce by almost half over the same voltage range, as shown in Fig. 5b. There are also cases where (i) ΔV_{th} is almost a constant (Fig. 5c); (ii) ΔV_{th} increases initially and then reduces (Fig. 5d); and (iii) ΔV_{th} decreases initially and then increases (Fig. 5e).

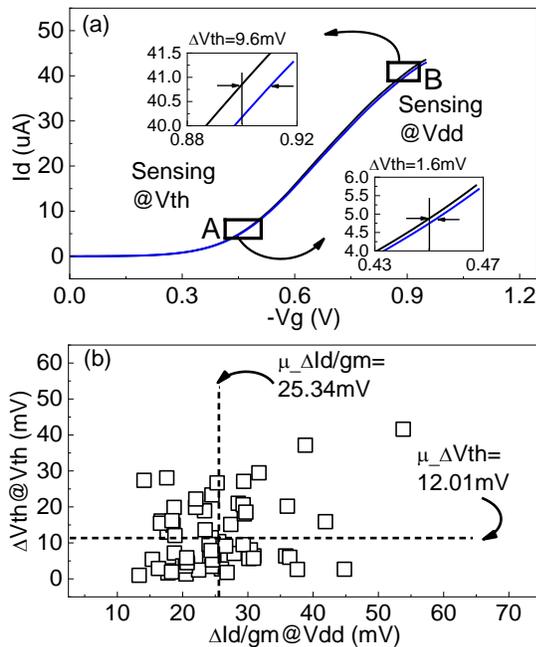


Fig. 4. (a) Early works estimated RTN-induced ΔV_{th} from $\Delta I_d/gm$ at $V_{dd}=0.9$ V (Point ‘B’), rather than directly measuring it at $V_g=V_{th}$ (Point ‘A’). The two insets are enlarged p-IV around the two points. The black p-IV is reference and the blue p-IV is the TWC p-IV. (b) The poor correlation between $\Delta I_d/gm$ at V_{dd} and ΔV_{th} at $V_g=V_{th}$. Each point was taken from a different device. The dotted lines mark the mean values.

It is known that channel current can have a narrow percolation path near V_{th} and the impact of a charged trap on a deeply scaled device depends on the relative local current density beneath the trap [16-19]. This can explain the device-specific dependence observed in Fig. 5. As schematically illustrated in Fig. 6, for the device in Fig. 5a, the trap is located far away from the current percolation path at V_{th} , so that it has little impact and $\Delta V_{th}(V_{th})$ is low. The many close-to-zero $\Delta V_{th}(V_{th})$ points in Fig. 4b indicates that this is often the case. As V_g increases, the current becomes more evenly spread and its relative density under this trap rises, leading to the increase of ΔV_{th} with V_g . As there is current flowing beneath each trap

at V_{dd} , there is no close-to-zero apparent ΔV_{th} in Fig. 4b, when evaluated by $\Delta I_d/gm(V_{dd})$.

For the device in Fig. 5b, however, the trapped charge is on top of the current percolation path at V_{th} , resulting in a large ΔV_{th} at V_{th} . As V_g increases, the current path is widened, so that the impact of the same charge on the device reduces and the ΔV_{th} decreases with $|V_g|$ in Fig. 5b. Similarly, the relative current density under the trap in Fig. 5c changes little with V_g and ΔV_{th} is insensitive to V_g . The dependence of relative current density under a trap on V_g may not be monotonic, which can explain the behavior in Figs. 5d&e. For instance, in Fig. 5d, it may increase initially and then decrease. Alternatively, when there are multiple traps, some can behave like Fig. 5a and some like Fig. 5b. A combination of them can give the complex dependence in Figs. 5d&e.

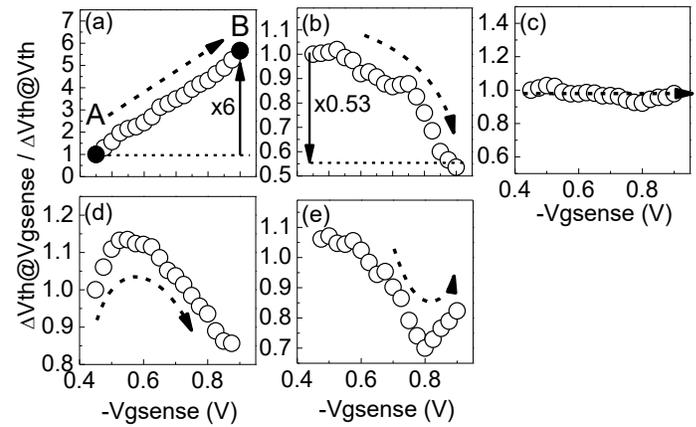


Fig. 5. Examples of the device specific dependence of the apparent ΔV_{th} on the sensing V_g . (a)-(e) were obtained from five different devices. The apparent ΔV_{th} at a V_{gsense} was obtained from the shift of TWC p-IV from the reference at $V_{gsense}=V_{th}$. The ΔV_{th} is normalized against its value at $V_{gsense}=V_{th}$. As the lowest $|V_{gsense}|$ is close to V_{th} , the data starts from ~ 1 in all devices.

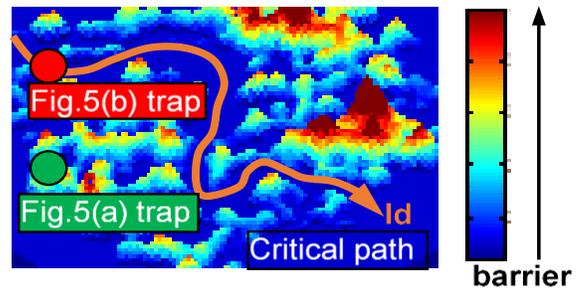


Fig. 6. A schematic illustration of different impacts of traps at different locations on a device at threshold condition. The current can follow a percolation path under $V_g=V_{th}$. The trap in green corresponds to the device in Fig. 5a: it is away from the critical current path, so that it only has a small effect on the device at V_{th} . The trap in red corresponds to the device in Fig. 5b: it is on top of the current critical path and has a large effect on the device at V_{th} .

Although the deeply scaled device-specific dependence of ΔV_{th} on sensing V_g can be explained by the interaction between the trap and the relative local current density beneath it, there is also a device independent ΔV_{th} dependence on the sensing V_g . For a large $3 \times 1 \mu m$ device where DDV is insignificant, Fig. 7a shows that ΔV_{th} also increases with

$|V_{gsense}|$. On one hand, a more evenly distributed I_d at higher $|V_{gsense}|$ allows more traps making an effective impact. On the other hand, the charge induced Coulombic scattering causes mobility degradation [27,28], which lead to $\Delta I_d(\text{mobility})$. When the apparent ΔV_{th} is evaluated from $\Delta I_d(\text{measured})/g_m$, the $\Delta I_d(\text{mobility})$ is treated as if it was caused by ΔV_{th} . In other words, the apparent $\Delta V_{th} = \Delta I_d(\text{measured})/g_m$ includes the contribution from mobility degradation to ΔI_d . As the effect of mobility degradation increases with $|V_{gsense}|$, it contributes to the increase in the apparent ΔV_{th} for higher $|V_{gsense}|$.

C. Statistics

As there is hardly any information on the statistical properties of the directly measured RTN-induced ΔV_{th} , especially in terms of its dependence on V_{gsense} , we report the DDV of this dependence here. Each line in Fig. 7b represents one device and the first impression is that the apparent ΔV_{th} broadly increases for higher $|V_{gsense}|$. Although the ΔV_{th} for some devices can reduce for higher $|V_{gsense}|$ as shown in Fig. 5b, it is rare for a trap to be above a localized percolation path. As a result, the average (symbols in Fig. 7b) increases monotonically for higher $|V_{gsense}|$, which is partly driven by the mobility degradation.

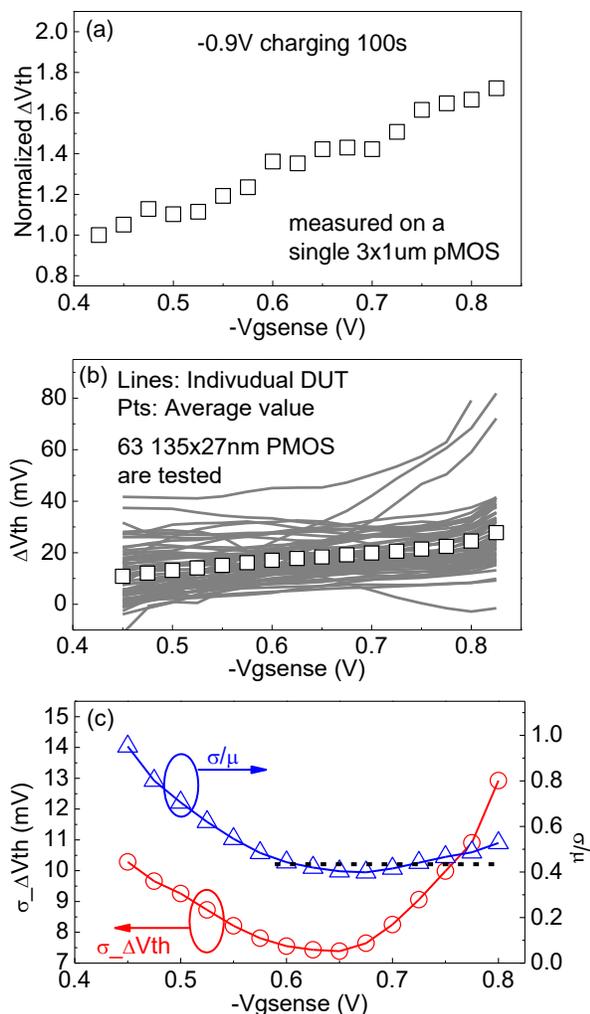


Fig. 7. (a) The impact of sensing V_g on the apparent ΔV_{th} of a large device of $3 \times 1 \mu\text{m}$. The deep level traps were filled under $V_g = -0.9$ V for 100 sec before

the measurement. ΔV_{th} is normalized against its value at $V_g = V_{th}$. (b) The stochastic variation of 135×27 nm devices. Each line is from one device. The symbols are the average. (c) Dependence of σ and σ/μ on the sensing V_g .

The standard deviation, σ , is plotted against V_{gsense} in Fig. 7c. It can be divided into two regions: as $|V_{gsense}|$ increases, σ decreases first and then increases. The minimum point is around 0.65 V. To explore this further, the relative variation, σ/μ , is also plotted in Fig. 7c. When $|V_{gsense}| > 0.65$ V, σ/μ only rises modestly, so that the higher σ is mainly caused by the higher μ , as shown by the symbols in Fig. 7b. Below 0.65 V, however, σ increases and μ decreases for lower $|V_{gsense}|$, resulting in a rising σ/μ . When $|V_{gsense}|$ lowers towards $|V_{th}|$, the current path becomes increasingly localized, leading to higher statistical variations, even though the trapped charges remain the same.

The cumulative distribution probability of ΔV_{th} is given in Fig. 8a and σ is plotted against μ in Fig. 8b for $V_{gsense} = V_{th}$. The RTN of nMOSFETs is smaller than that of pMOSFETs. σ follows μ by a power law with an exponent of ~ 0.5 , agreeing with the prediction of Defect-Centric model [2, 16, 29]. According to this model, the average ΔV_{th} induced by a trap, η , is,

$$\eta = \frac{\sigma^2}{2\mu}$$

Using the fitted line in Fig. 8b, $\eta \sim 3.2$ mV is obtained for pMOSFETs. This η is $\sim 2 \times q/C_{ox}$ approximately, where q is one electron charge and C_{ox} the gate oxide capacitance. This agrees well with the value reported for the recoverable component of NBTI of pFinFETs [16], although the test samples used here are planar pMOSFETs from a different supplier. The average number of traps, N , per device is,

$$N = \frac{\mu}{\eta}$$

For pMOSFETs, a $\mu \sim 12$ mV in Fig. 4b gives $N \sim 4$.

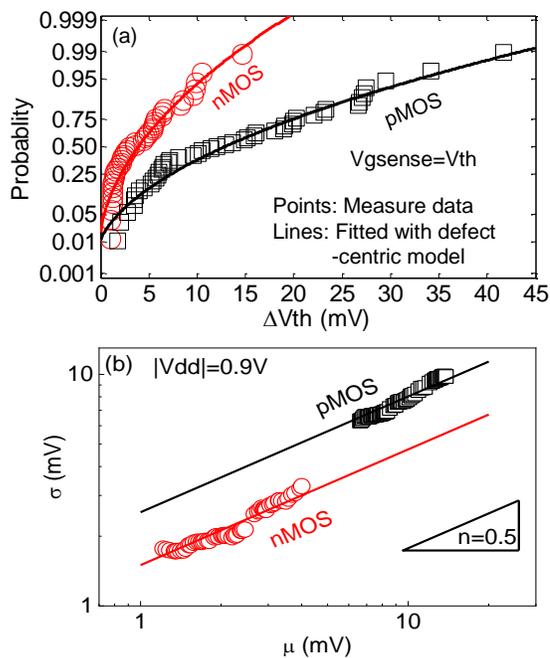


Fig. 8. (a) The cumulative distribution of ΔV_{th} . The symbols are test data and the lines are fitted with the Defect-Centric model that assumes the number of traps per device following the Poisson's distribution and the ΔV_{th} induced by a trap following

exponential distribution. (b) Standard deviation versus mean. Lines show that the data follow the prediction of Defect-Centric model well with a power exponent of 0.5. The different pairs of (μ, σ) are obtained by varying the time window of “Id monitor” from 10 μ s to 100 sec in Fig. 2a.

For nMOSFETs, the corresponding values are $\mu \sim 6.5$ mV, $\eta \sim 1.1$ mV, and $N \sim 6$. When compared with pMOSFETs, the lower RTN in nMOSFETs is caused by smaller η . Although there are more traps in nMOSFETs, they are in the high-k layer and further away from the conduction channel and induce a smaller ΔV_{th} [30].

IV. CONCLUSIONS

The conventional method of ‘Measure-Stress-Measure’ at preset time is inapplicable for the RTN-induced ΔV_{th} , since the trap can be neutral when pulse IVs are taken. Early works estimate the RTN-induced ΔV_{th} by $\Delta I_d/g_m$ at $V_g=V_{dd}$ and its accuracy is not known. In this paper, we propose a new TWC method for directly measuring the real ΔV_{th} at $V_g=V_{th}$. By setting the trigger level close to the upper envelope of trapping-induced ΔI_d , it ensures that the pulse IV is taken when traps are charged.

Results show that there is no unique relationship between $\Delta I_d/g_m$ at $V_g=V_{dd}$ and the directly measured ΔV_{th} and their correlation is poor. The device-specific dependence of the apparent ΔV_{th} on the sensing V_g originates from the DDV of relative local current density under a trap at V_{th} . Moreover, on average, $\Delta I_d/g_m(V_{dd})$ doubles $\Delta V_{th}(V_{th})$ and the charge-induced mobility degradation through Coulombic scattering plays a role.

The TWC is applicable to devices with or without analyzable RTN signals. For the first time, it is used for assessing the statistical properties of the directly measured RTN-induced ΔV_{th} . For the same trapped charges, it is found that σ has a minimum around $|V_{gsense}|=0.65$ V. The increase in σ when $|V_g|$ lowers toward $|V_{th}|$ is explained by an increased localization of current path. The DDV follows the Defect-Centric model. For the 135×27 nm devices used in this work, the average ΔV_{th} induced per trap is ~ 3.2 mV for pMOSFETs and ~ 1.1 mV for nMOSFETs.

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