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# Seismic collapse of self-centering steel MRFs with different column base structural properties

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#### 15

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#### ABSTRACT

16 The effect of the strength and stiffness characteristics of a previously proposed novel column 17 base on the seismic performance and collapse capacity of steel self-centering moment-18 resisting frames is evaluated in this paper. This is done through three normalised parameters 19 that represent the initial stiffness, post-yield stiffness, and strength of the column base, which 20 can be independently adjusted. For these evaluations, a prototype steel building, which serves 21 as a case study, is designed with sixteen different cases of a self-centering moment-resisting 22 frame with different column base stiffness and strength characteristics (SC-MRF-CBs). A 23 self-centering moment-resisting frame with conventional column bases and the same 24 members and beam-column connections as those of the SC-MRF-CBs, named SC-MRF, 25 serves as a benchmark frame. A set of 44 ground motions was used to conduct non-linear 26 dynamic analyses and evaluate the seismic performance of the frames. Incremental dynamic 27 analyses were also performed with the same ground motions set to evaluate the collapse 28 capacity of the frames. Collapse capacity fragility curves and adjusted collapse margin ratios 29 of the frames were derived and used for the comparison of the seismic risk of the frames. The

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30 results show that the new self-centering column base significantly improves the seismic 31 performance of the SC-MRF, demonstrating the potential of the SC-MRF-CBs to be 32 redesigned with smaller member sections. Moreover, the SC-MRF-CBs achieve significant 33 reduction in collapse risk compared to the SC-MRF. Finally, the results show that increasing 34 the base strength and stiffness improves the seismic performance and collapse capacity of the 35 SC-MRF-CBs.

#### 36 KEYWORDS

37 Column base; Self-centering; Collapse risk; Interstorey drifts and floor accelerations;
38 Parametric investigation; Seismic resilience

#### 39 1 INTRODUCTION

40 Column bases have a very important role in the seismic response of steel moment-resisting 41 frames (MRFs) [1–5]. Eurocode 8 (EC8) [6] assumes that plastic hinges at the column base 42 connection will offer increased rotational ductility compared to other plasticity mechanisms 43 therein [7], such as column member plastic hinging. This strength-related code presumption 44 has been questioned by Lignos and Krawinkler [8], who showed that the ductility of the 45 column base plastic hinges may be compromised by local instabilities, leading to premature 46 column failure. Moreover, Aviram et al. [5] and Ruiz-García and Kanvinde [3] showed that 47 decreasing the initial stiffness of the base connections in low-rise buildings can change the height-wise drift distribution, leading to drift and damage concertation and eventually to 48 49 collapse. Zareian and Kanvinde [2] showed that reducing the base fixity in low- to high-rise 50 buildings can increase the members' force demands, alter the global plastic mechanism, and 51 significantly reduce ductility, strength and collapse resistance. Torres-Rodas et al. [4] showed 52 that increasing the base flexibility of three-dimensional framed buildings, increases their 53 transient drifts and probabilities of collapse, while appreciably decreases their overstrength 54 and ductility.

55 To address the deficiencies of MRFs under earthquakes, the self-centering MRFs (SC-MRFs) 56 were developed, such as those, for example, proposed in [9–16]. The main practice for SC-57 MRFs is to use post-tensioned (PT) beam-column connections that utilise high-strength steel 58 tendons to clamp the beams to the columns and, thus, provide a re-centering mechanism that 59 can restore the initial geometry of the building up to a targeted seismic intensity. High-60 strength steel is used to ensure that the tendons remain elastic up to the targeted frame 61 response. Therefore, in these SC-MRFs, the self-centering mechanism is provided through 62 attaining a targeted elastic elongation capacity for their PT tendons. Other researchers [17,18] 63 have provided self-centering mechanisms for their seismic-resilient MRFs by relying on fully 64 recoverable plastic deformations for the self-centering components of their systems up to as 65 targeted response level to eliminate the need for repair, i.e., by utilising superelastic shape 66 memory alloys (SMAs) for their self-centering components. The SC-MRFs with high-67 strength PT tendons, which are of interest in this work, utilise energy dissipating devices 68 (EDs) in their PT beam-column connections to dissipate seismic energy and reduce the 69 seismic forces and accelerations [9]. These EDs can be easily removed or replaced, if 70 damaged, which can improve building's resilience [19,20]. Combining these techniques, SC-71 MRFs can minimize damage and residual drifts [10] and reduce peak drifts and floor 72 accelerations [9,21].

Self-centering systems can offer an option of tuning the structural properties that fully define their seismic hysteretic response. These properties are the initial stiffness, post-yield stiffness, strength and energy dissipation. Different researchers have evaluated the effect of these properties on the seismic response of different types of self-centering systems. Christopoulos et al. [22,23] concluded that if adequate energy dissipation is provided in SDOF flag-shaped response systems, these could have similar or improved peak drift response compared to that of elastoplastic systems of the same initial stiffness and strength. It was highlighted, though, 80 that systems with self-centering response are prone to increased resonance vibration amplitudes when their post-yield stiffness ratio,  $\alpha$  (i.e., the ratio of the post-yield stiffness 81 82 over the initial stiffness), is increased [23]. Subsequently, Christopoulos et al. [24] found that 83 the maximum drift response of SDOF systems with self-centering response under the design 84 basis earthquake (DBE) [6] slightly decreases for increasing values of their post-yield 85 stiffness. Interestingly, this effect was reversed for the collapse prevention seismic performance level - a finding fundamentally opposite to what applies in elastoplastic 86 87 systems. Karavasilis and Seo [25] concluded that increasing the strength and adding damping 88 in self-centering SDOF systems, generally decreases their peak total accelerations and 89 displacements. In contrast, Cimellaro [26] suggested that the drift response of a structure may 90 be improved by adopting lower lateral strength combined with higher damping ratios. Chou 91 and Chen [27] investigated the performance of SC-MRFs with either fixed or self-centering 92 column bases under the DBE and maximum considered earthquake (MCE) [28]. However, 93 they did not assess the effect of the base strength, stiffness and energy dissipation on the 94 seismic response of their investigated systems.

95 SC-MRFs with conventional column bases still cannot fully avoid structural damage and 96 residual drifts because of the plastic hinges developed at their column bases [9,10,27,29]. To 97 address this issue, SC-MRFs with self-centering column bases with replaceable/repairable 98 EDs (SC-MRF-CBs) were developed [27,29-33]. SC-MRF-CBs can eliminate damage at 99 their column bases and, thus, exhibit negligible residual drifts. Kamperidis et al. [29] have 100 shown that these systems significantly reduce the peak drifts compared to their correspondent 101 SC-MRFs, i.e., the frame with the same PT beam-column connections and same members 102 with the SC-MRF-CB, but with conventional rigid and full-strength column bases. In 103 addition, the design procedure proposed in [29] has the ability to fine-tune in a controlled 104 manner the strength, stiffness and hysteretic behaviour of a SC-MRF-CB, keeping these

parameters uncoupled. Thus, one can design an SC-MRF-CB adjusting these parameters in
such a way that its seismic response can be enhanced. However, an extensive and thorough
parametric study on the effects of these parameters to the seismic response of the SC-MRFCBs is still missing.

109 Moreover, the performance-based design approach of modern structural codes [28,34] mandates that buildings should be assessed against collapse as an extra measure of safety for 110 111 human life, on the top of satisfying the traditional force and displacement requirements of the 112 structural codes (e.g., EC8 [6]). This triggered research towards the collapse assessment of 113 self-centering systems. In line with this, Tzimas et al. [35] found that the collapse capacity of 114 SC-MRFs subjected to both far- and near-fault earthquakes, can be significantly improved by 115 adding viscous dampers. However, the collapse risk of the SC-MRF-CBs and their potential 116 to improve the collapse capacity of seismic-resistant steel buildings has never been evaluated. 117 This paper investigates the potential of SC-MRF-CBs equipped with the novel column base 118 proposed in the work of Kamperidis et al. [29] to further improve the seismic performance 119 and reduce the collapse risk of earthquake-resilient steel buildings equipped with SC-MRFs. 120 The collapse risk of these new systems has never been assessed before and, so, it is of 121 particular importance to investigate whether they attain a better or worse collapse behaviour 122 compared to the SC-MRF. By comparing both the seismic performance and collapse risk of 123 the SC-MRF-CBs with those of the SC-MRF, the performance of the former can be evaluated 124 against all the performance criteria modern structural codes demand. As such, it can be

125 concluded whether the SC-MRF-CBs can provide the potential to be designed for smaller 126 steel members as compared to those of the SC-MRF. However, the explicit consideration of 127 an SC-MRF-CB system with smaller cross-section than those of the SC-MRF is out of the 128 scope of this work. Moreover, the mainstream approach for the SC-MRFs is to be designed 129 for similar strength and initial stiffness with their correspondent conventional MRF [10,36], 130 referred to as correspondent MRF. Besides, due to the specific configuration of their PT 131 beam-column connections, SC-MRFs do not allow for flexible stiffness and strength frame 132 adjustments. For that reason, SC-MRFs are rather restricted to adhere to the above design 133 approach. In contrast, the self-centering column bases allow for the controlled adjustment of 134 all the structural properties that are necessary to fully determine their hysteretic behaviour to 135 targeted predefined levels through mathematical formulas [29]. This base structural 136 properties' control mechanism enables the adjustment of the stiffness and strength of the SC-137 MRF-CBs. An enhanced design procedure (compared to that in [29]) for the self-centering 138 column bases is also proposed. This work thoroughly and methodologically investigates for 139 the first time the effects of all the aforementioned base structural properties on the seismic 140 performance and collapse capacity of the SC-MRF-CBs for a given level of energy 141 dissipation in their bases. The base structural properties in question are the initial stiffness, 142 post-yield stiffness, and strength, represented through three normalised factors, which are 143 described next (Section 3.1). For this scope, a prototype steel building was designed that 144 comprises different seismic-resistant frames: i.e., an SC-MRF and sixteen SC-MRF-CBs with 145 different base stiffness and strength characteristics. The frames were modelled in OpenSees, 146 where material and geometrical nonlinearities were taken into account, along with strength 147 and stiffness degradation. A set of 44 ground motions, scaled to three code-prescribed 148 seismic intensity levels [6,28], was used to conduct dynamic analyses and evaluate the 149 seismic performance of the frames. In addition, incremental dynamic analyses (IDAs) were 150 performed with the same set of ground motions to evaluate the collapse capacity of the frames. The collapse capacity fragility curves and the adjusted collapse margin ratio of the 151 152 frames were derived and used for the comparison of the seismic risk of the frames.

#### 153 2 PROTOTYPE BUILDING

The 5- by 3-bay, five-storey prototype steel building of [29], depicted in Figure 1, is utilised in this work. Figure 1 shows the two identical braced frames in the *Y* direction and two identical seismic-resistant frames in the *X* direction the building has at its perimeter. The building has ductile non-structural elements and thus, the maximum interstorey drift ratio,  $\theta_{s,max}$ , must be less than 0.75% under the frequent occurred earthquake (FOE) in accordance with EC8 [6]. The design spectrum of EC8 [6] with peak ground acceleration equal to 0.35g and ground type B was used for the design of the frame under the DBE.



161 162

#### Figure 1 (a) Plan view; and (b) Elevation A of the prototype building.

163 Only the seismic-resistant frame of Elevation A of the prototype building, shown in Figure 164 1(b), is studied in this work. The frame of interest was designed as: (a) an SC-MRF, following the design procedure of [10], to serve as the benchmark frame of this work; and (b) 165 166 sixteen different SC-MRF-CBs with the self-centering column bases proposed in [29], having 167 different base stiffness and strength characteristics but the same energy dissipation. The SC-MRF and all SC-MRF-CBs have the same beams, columns and PT beam-column 168 169 connections. The design characteristics of the members and PT beam-column connections of 170 the SC-MRF are those described in [35]. Figure 2(a) illustrates the bottom-left part of an SC-171 MRF-CB in Elevation A of the prototype building. The configurations of an external and internal (central) PT beam-column connection of the frames are depicted in Figure 2(a). 172 Figure 2(b) shows a close-up view and the notation of these connections. The design 173

#### 174 procedure proposed in [29] was used for the design of the self-centering column bases of the

#### 175 SC-MRF-CBs.



Figure 2 Close-up view of: (a) the bottom-left part of the SC-MRF-CB in Elevation A of the prototype
building (Detail 1 in Figure 1(b)); and (b) PT beam-column connection at an external column with its
notation (Detail 2 in Figure 2(a)).

180 The web hourglass pins (WHPs) described in [13] were utilised as EDs in the column bases 181 of the SC-MRF-CBs. The material of the WHPs was duplex stainless steel and its properties 182 were as follows, as per [14]: yield stress equal to 543 MPa; ultimate stress equal to 778 MPa; 183 elongation at fracture 34.25%; and Young's modulus equal to 227.848 GPa. The material for 184 the multi-wire tendons of the self-centering column bases was the low-relaxation Grade 270 steel material of ASTM A416 [37] with yield strength of 1676 MPa; ultimate tensile strength 185 186 of 1860 MPa; Young's modulus equal to 195 GPa; and ultimate elongation 3.5%. This 187 material, used in [38] and [39], is utilised in Section Error! Reference source not found. for 188 the fracture modelling of the tendons.

189 **3 DESIGN CASES** 

190 Sixteen SC-MRF-CB design cases with different values for the strength, initial stiffness, and 191 post-yield stiffness of their self-centering column bases are employed for the parametric 192 study of this work. Thus, each self-centering column base employs a unique combination of 193 values for these three base structural properties. There are three values of strength, three 194 values of initial stiffness and five values of post-yield stiffness that are combined to form 195 these sixteen combinations in the self-centering column bases. These values cover the whole 196 range of feasible values that can be achieved each base structural property when designing 197 the self-centering column utilising the design procedure proposed in [29]. The three ranges of 198 feasible values of the base structural properties are delimited by the given column cross-199 section and column design loads, which serve as input for the aforementioned design 200 procedure [29]. The column and its design loads are derived from the elastic analysis and 201 design of the correspondent MRF, from which the SC-MRF-CBs' designs stem [29]; this will 202 be further explained next (Section 3.2). By examining self-centering column bases with base 203 structural properties that span the whole range of their feasible values, the limits of the 204 distinct effect of each one of these properties on the seismic response and collapse capacity of 205 the SC-MRF-CBs can effectively be determined. The notation of the self-centering column 206 bases can be seen in Figure 3(a). Each self-centering column base is considered to be a 207 cantilevered assembly that comprises the self-centering low-damage column base connection, 208 proposed in [29], and the steel column member of the first storey of the frame (Figure 3(a)). 209 The self-centering column base connections are determined by the height of the concrete-210 filled tube (CFT) (seen in Figure 3(a)),  $L_{CFT}$ . The steel columns extend from the top of their 211 self-centering base connections up to the lower limit of the panel zones of the first-storey PT 212 beam-column connections. This limit is the level of the bottom flanges of the first-storey PT 213 beams, as indicated by the red dashed line in Figure 3(a). The steel columns are determined 214 by their length,  $L_c$ , as it is shown in Figure 3(a).



Figure 3 Self-centering column base: (a) configuration (Detail 3 in Figure 2(a)) and notation; and (b)
 theoretical moment (*M*)-rotation (θ) behaviour for an assumed clockwise bending moment and axial
 force.

The rationale for considering this specific cantilevered assembly configuration as the means 219 220 of assessing the base stiffness and strength of the SC-MRF-CBs is that it exclusively includes 221 the only two elements that change in the whole configuration of the SC-MRF-CBs, i.e., the 222 base connection and its connecting steel first-storey column. All the other parts of the frames 223 are the same as those of the SC-MRF. Similar approaches have been adopted in previous 224 relevant research [40]. Such an approach facilitates the large computational demands of this 225 work. The theoretical moment (M)-rotation ( $\theta$ ) behaviour of the self-centering column bases can be seen in Figure 3(b). In this figure,  $\theta$  is the chord rotation of the self-centering column 226 227 bases, defined as the lateral displacement at the top of the column divided by the total height of the column bases,  $h_{base}$ . Thus,  $h_{base}$  is related with the geometry of the frame through the following relation:

230 
$$h_{base} = h_{1storey} - h_{1storeyBeam}$$
(1)

where  $h_{1storey}$  is the total height of the first storey and  $h_{1storeyBeam}$  is the cross-sectional depth of the beams of the first floor.

#### 233 3.1 Investigated base structural properties

234 The investigated structural properties of the self-centering column bases (or simply base 235 structural properties) that are studied in this work are their strength,  $M_{IGO}$ , initial stiffness, 236  $K_{in,sc-cb}$ , and post-yield stiffness,  $K_{pl,sc-cb}$ , which are described in Figure 3(b).  $M_{IGO}$  is the 237 moment at the first yielding of the WHPs of the self-centering column base connection 238 (Figure 3(b)).  $M_{IGO}$  is considered to represent the flexural strength of the self-centering 239 column bases because the strength of a system with metallic fuses should correspond to the 240 point where the first yielding of its structural fuses occurs [41]. The self-centering column 241 base allows the controlled adjustment of these base structural properties by utilising the analytical expressions that are presented next. To uncouple the research findings of this work 242 243 from the specific design characteristics of the frames studied herein (e.g., the size of the first-244 storey columns, the cross-sectional depth of which, denoted as  $h_c$  (see Figure 3(a)), and its plastic moment of resistance,  $M_{N,pl,Rd,c}$  (described in Eq. (3), below), are of interest in this 245 246 study), the base structural properties are represented by the following normalised parameters: 247 (a) the strength ratio,  $\eta$ ; (b) the normalised initial base stiffness factor,  $\beta_{base}$ ; and (c) the postyield stiffness ratio, a. Thus, the findings of this work can be extended to any SC-MRF-CB 248 249 that is designed as per the design procedure proposed in [29].

Likewise previous research [25,42], the energy dissipation factor,  $\beta_E$ , is utilised to control the energy dissipation in all sixteen self-centering column bases.  $\beta_E$  was selected to take the 252 same, near-maximum allowable value to allow the self-centering behaviour of the column 253 bases and maximise their seismic energy dissipation. Thus,  $\beta_E$  was not included in the 254 parametric study. Based on previous relevant research [22,23,43], it was hypothesized that by 255 maximising the energy dissipation at the column bases, the seismic response and collapse capacity of the SC-MRF-CBs would be optimally improved. Because the upper bound of  $\beta_E$ 256 257 equals 0.5 [25,42],  $\beta_E$  was conservatively taken equal to 0.48 in all self-centering column 258 bases. The energy dissipation in each self-centering column base is due to the energy 259 dissipated by the WHPs up to the target base rotation,  $\theta_t$  (Figure 3(b)); the steel columns were 260 intended to remain elastic and not contribute to the energy dissipation of the self-centering column bases. For this research,  $\theta_t$  was conservatively chosen to be equal to the rotation 261 262 capacity limit of EC8 for ductility class high MRFs, i.e., 0.035 radians [6]. This implies that no strength and stiffness deterioration was expected to take place up to  $\theta_t$ .  $\beta_E$  was defined as: 263

$$\beta_{\rm E} = \frac{M_{\rm Y} - M_{\rm D}}{M_{\rm Y}} \tag{2}$$

where  $M_Y$  is the moment of the self-centering column bases when all WHPs have reached their elastic limit; and  $M_D$  is the decompression moment of the self-centering connection, i.e., the moment at which the gap at the rocking interface of the column base opens [10,29]. These characteristic moments, along with their corresponding rotations, can be seen in Figure 3(b).

269 The strength factor,  $\eta$ , was defined as:

270 
$$\eta = \frac{M_{IGO}}{M_{N,pl,Rd,c}}$$
(3)

where  $M_{IGO}$  is the moment at the first yielding of the WHPs of the self-centering column base connection;  $M_{N,pl,Rd,c}$  is the plastic moment of resistance of the column.  $M_{N,pl,Rd,c}$  accounts for interaction with the design axial force,  $N_{Ed}$ , and the overstrength of the connections materials and for other material effects, in accordance with EC8 [6] and Eurocode 3 (EC3) [44] 275 provisions.  $N_{Ed}$  is the axial force derived from the analysis of the correspondent MRF for the gravity loads combination of actions [29]. The strength factor  $\eta$  consists a measure of the 276 277 strength of the base connection but can represent the strength of the whole self-centering 278 column base because the former is the only part of the latter that is expected to yield up to  $\theta_t$ . The concept that the strength factor  $\eta$  consists a measure of the column bases' strength was 279 280 adopted on the basis that it relates the yield strength of the base connections with that of the 281 column member. This is in line with the relevant provisions of Eurocode 3 [45] that classify 282 moment-resisting connections with respect to their strength by comparing the strength of the 283 connections with the strength of their connecting members. Previous research on PT beam-284 column connections [10] has set out an upper limit for  $\eta$  equal to unity. The parametric 285 investigation of this work shown that to achieve self-centering and damage-control behaviour 286 up to  $\theta_t$ , only values of  $\eta$  below 0.45 were capable of yielding self-centering column base 287 designs with initial and post-yield stiffness within their feasible range of values; these latter two base structural properties were controlled through their normalised factors,  $\beta_{base}$  and  $\alpha$ , 288 289 respectively, described next. For that reason, the three values of  $\eta$  this work examined were 290 0.30, 0.35 and 0.40.

291 The normalised initial base stiffness factor,  $\beta_{base}$ , was defined as:

292 
$$\beta_{base} = \frac{K_{in,sc-cb}}{K_{in,conv}}$$
(4)

where  $K_{in,conv}$  is the initial (elastic) flexural stiffness of a cantilever-fixed steel column of total height equal to  $h_{base}$ ; and  $K_{in,sc-cb}$  the initial stiffness of a self-centering column base, assumed equal to the elastic flexural stiffness of the steel cantilevered column on the top of the selfcentering column base connection,  $K_{el,col}$ , since the initial stiffness of the latter connection is taken as infinite [29]. Thus,  $K_{el,col}$  is calculated for a column height of  $L_c$ . For the self298 centering column bases under investigation, the three  $\beta_{base}$  values examined were 133%, 299 167% and 200%.

300 The post-yield stiffness ratio,  $\alpha$ , was defined according to the following relation:

$$\alpha = \frac{K_{pl,sc-cb}}{K_{in,sc-cb}}$$
(5)

302 where  $K_{pl,sc-cb}$  is the post-yield stiffness of the self-centering column base, defined as:

$$K_{pl,Sc-Bc} = \frac{K_{pl,sc-cb} \cdot K_{el,col}}{K_{pl,sc-cb} + K_{el,col}}$$
(6)

304 where  $K_{pl,sc-cb}$  is the post-yield stiffness of the self-centering column base connection, which 305 was determined by the following relation [29]:

$$306 \qquad K_{pl,sc-cb} = K_{fe} \cdot \left(\lambda \cdot n_{WHPu} \cdot z_u^2 + \lambda \cdot n_{WHPc} \cdot z_c^2 + \lambda \cdot n_{WHPd} \cdot z_d^2\right) + K_{ER} \cdot \left(n_{ERu} \cdot z_{ERu}^2 + n_{ERd} \cdot z_{ERd}^2\right)$$
(7)

307 where  $k_{fe}$  is the elastic stiffness of a single WHP [29];  $\lambda$  equals 2% according to [29];  $n_{WHPu}$ 308 and  $n_{WHPd}$  are the numbers of the WHPs at the gap-opening and rocking-toe side of the self-309 centering column base connections (the rocking toe coincides with the centre of rotation of 310 the connection (COR), as it is seen in Figure 3(a) for an assumed clockwise moment);  $n_{WHPc}$ 311 the number of the central WHPs;  $z_u$ ,  $z_d$  and  $z_c$ , the lever arms of the WHPs at the gap-opening 312 side, rocking-toe side and that of the central WHPs, respectively;  $K_{ER}$  is the elastic axial 313 stiffness of each tendon, equal to  $E_{ER} \cdot A_{ER}/L_{ER}$ , with  $E_{ER}$ ,  $A_{ER}$  and  $L_{ER}$  the tendon's material 314 Young's modulus, cross-sectional area and length, respectively; and  $n_{ERu}$  and  $n_{ERd}$ , and  $z_{ERu}$ 315 and  $z_{ERd}$  the number and lever arms of the PT tendons at the gap-opening and rocking-toe side 316 of the self-centering column base, respectively. The lever arms  $z_d$  and  $z_{ERd}$ , are defined in 317 Figure 3(a). The lever arms  $z_u$  and  $z_{ERu}$  were derived by adding to  $z_d$  and  $z_{ERd}$  the cross-318 sectional depth of the CFT,  $h_{CFT}$ , respectively.  $z_c$  equals  $h_{CFT}/2$ . Five different values of  $\alpha$ were examined in this work, i.e., 5%, 10%, 15%, 20% and 24.5%. The value of 24.5% was 319

320 the maximum value of  $\alpha$  obtained for the given level of strength and initial stiffness of the 321 relevant self-centering column base. This is in agreement with the maximum achievable limit 322 of  $\alpha$  for real flag-shaped response systems, determined to about 25%, proposed by Wiebe and 323 Christopoulos [46].

#### 324 3.2 Self-centering column base design procedure

This section presents the design procedure utilised to derive the sixteen self-centering column 325 326 base designs that are investigated in this work. The design procedure is that described in the 327 work of Kamperidis et al. [29], with the only difference being that – in this work – the 328 investigated base structural properties are given pre-selected values utilising Eq. (2) through 329 (7) of Section 3.1. Pre-selecting these values, reduces the number of unknowns to be 330 determined (as compared to the approach adopted in [29]), significantly facilitating the 331 design process. To minimize repetition since the design procedure in [29] has been presented 332 therein in detail, the design approach adopted in this work presents only limited mathematical 333 formulas from [29].

334 To initiate the design procedure, the following input quantities are required: the column axial force,  $N_{Ed}$ ; the column cross-section, so that its cross-sectional depth,  $h_c$ , and plastic moment 335 of resistance,  $M_{N,plRd,c}$ , are determined; and the target base rotation,  $\theta_t$ . The design procedure 336 337 comprises the following steps:

338 Step 1: Design the tendons

339

(a) Select a value for  $\beta_{base}$  and calculate  $K_{in,sc-cb}$  from Eq. (4). From  $K_{in,sc-cb}$ ,  $L_c$  is derived 340 utilising the relevant elastic flexural stiffness formula from mechanics (Section 3.1). 341 From Figure 3(a) and given the resulted  $L_c$  value,  $h_{CFT}$  can be derived.

342 (b) Select a value for the strength factor,  $\eta$ . From Eq. (3)  $M_{IGO}$  can then be derived.

- 343 (c) Select a value for the ratio  $M_D/M_{IGO}$  so that is it larger than 0.5, but as closer as it gets 344 to that latter value. This is to ensure self-centering capability but also to maximize 345 energy dissipation. Thus,  $M_D$  is derived.
- 346 (d) Select a number,  $n_{ERu}=n_{ERd}$ , and a lever arm for the tendons, e.g.,  $z_{ERd}$  ( $z_{ERu}$  can be 347 determined as per Section 3.1). It is suggested that four tendons are placed at the 348 corners of the anchor stand, which is the elevated stiff plate welded on the top of the 349 CFT (see Figure 3(a)); i.e.,  $n_{ERu}=n_{ERd}=2$ . Then, calculate the initial post-tensioning 350 force at each tendon, *T*, as per Eq. (2) of Kamperidis et al. [29].
- (e) Select an appropriate high-strength steel grade material for the tendons, e.g., Grade 270 steel material of ASTM A416, to ensure a high yield strength,  $f_{y,ER}$ , for the tendons, and assume a diameter for them,  $D_{ER}$  (this determines  $A_{ER}$ ). Then, utilize Eq. (3) of [29] to calculate  $L_{ER}$ . Also, approximate the moment contribution of the tendons for the characteristic rotation,  $\theta_2$ , denoted as  $M_{ER}(\theta_2)$ , as per Eq. (7) of [29].  $\theta_2$  is the rotation at which the first WHP of the self-centering column base yields.  $M_{ER}(\theta_2)$  is to be used next.

358 Step 2: Design the WHPs

359 (a) Select a number for the WHPs at each side of the self-centering column base (e.g., 360  $n_{WHPd}$ ). It is suggested that two WHPs are placed at all sides of the column base; this 361 is for construction practicality and to ensure that the column base control its structural 362 properties over both of its main axes [29]; i.e.,  $n_{WHPd} = n_{WHPu} = 2$ . Also, select a lever arm for the WHPs, e.g.,  $z_d$  ( $z_u$  and  $z_c$  can be determined as per Section 3.1). 363 364 Then, calculate the yield strength of a single WHP,  $F_{y,WHPi}$ , as per Eq. (5) of [29], 365 utilising  $M_{ER}(\theta_2)$  from Step 1(e). The internal diameter of the WHPs,  $D_i$  (described in 366 Detail 1 of Figure 3(a)), can then be calculated from the following relation as per 367 [10,29]:

$$D_i = \sqrt{\frac{2 \cdot F_{y,WHP,i} \cdot \sqrt{3}}{\pi \cdot f_{y,WHP}}}$$
(8)

369 where  $f_{y,WHP}$  is the yield strength of the material of the WHPs.

370 (b) Select a value for  $\alpha$ , and based on Eq. (5) and the value of  $K_{in,sc-cb}$  derived from Step 371 1(a), calculate  $K_{pl,sc-cb}$ . Based on the  $K_{pl,sc-cb}$  value, calculate the WHPs' elastic 372 stiffness  $K_{fe}$  from Eq. (7). Moreover, to derive a relationship between the length of the 373 tapered part of half a WHP,  $L_{WHP}$ , and the external diameter of the WHP,  $D_e$ , 374 substitute  $D_i$  from Eq. (8) into the following relationship [29,47]:

375 
$$L_{WHP} = \frac{2.566 \cdot D_e^3}{\pi \cdot D_l^2}$$
(9)

Both  $L_{WHP}$  and  $D_e$  are described in Detail 1 of Figure 3(a). A second relationship between  $L_{WHP}$  and  $D_e$ , can be derived by substituting  $K_{fe}$  from above and  $D_i$  from Eq. (8) into the following relationship [13,29]:

379 
$$K_{fe} = 2 \cdot \frac{9 \cdot \pi \cdot D_e^3 \cdot D_i \cdot E_{WHP} \cdot G_{WHP}}{40 \cdot E_{WHP} \cdot D_e^2 \cdot L_{WHP} + 48 \cdot G_{WHP} \cdot L_{WHP}^3}$$
(10)

380 where  $E_{WHP}$  and  $G_{WHP}$  are the elastic and shear moduli of the WHP material. Solving 381 the system of Eqs. (9) and (10), the values of  $D_e$  and  $L_{WHP}$  can be derived.

382 Step 3: Check the self-centering capability of the column base and the column plastic hinge383 avoidance

- The self-centering capability of the column bases is checked by utilising Relationships (9)
  through (11) and Relationship (17) from [29]. There are two cases:
- (a) If self-centering behaviour is achieved, then proceed with checking whether a
  plastic hinge is formed at the bottom of the column member. This is done by
  utilising Relationship [20] of [29]. Two case are now identified:

- 3891. A plastic hinge is formed: in this case, decrease  $A_{ER}$  in Step 1(e) by be employing390a smaller tendon (smaller  $D_{ER}$ ), and repeat all steps up to this point until this check391is satisfied. Then finalize the procedure.
- 392 2. A plastic hinge is not formed: in this case, finalize the design process.
- 393 (b) If self-centering behaviour is not achieved, return to Step 1(c) and increase the ratio 394  $M_D/M_{IGO}$ . Then, repeat the design procedure up to Step 3(a) until self-centering is 395 achieved and plastic hinge is not formed at the column. When Step 3(a) is fully 396 satisfied, complete the design process.
- 397 The design steps are summarized in the flowchart of Figure 4.



Figure 4 Flowchart of the design approach of the self-centering column bases, based on the design procedure proposed in Kamperidis et al. [29].

#### 400 3.3 Self-centering column base designs

Table 1 lists the normalised base structural properties of the sixteen self-centering column base designs and Table 2 presents their key design characteristics. These design characteristics were derived utilising the design procedure presented in Section 3.2. The notation utilised in Table 2 is described in Figure 3(a) (and its Detail 1) and in Section 3.2.

405 Table 1. Normalised base structural properties of the sixteen self-centering colu							ımn bas	_						
	Frame			η			$\beta_{base}$ (%)				α(%)			
H40K133A5 H40K133A15 H40K167A15 H40K167A5 H40K133A10			0.4				133			5				
			0.4				133			15				
			0.4				167			15				
			0.4			167				5				
			0.4			133				10				
	H40K167A10 H40K133A24			0.4			167				10			
				0.4			133				24.5			
H35K133A5			0.35			133				5				
		H35K1	33A15		0.35			133				15		
		H35K1	67A15		0.35			167				15		
		H35K1	67A5		0.35			167				5		
		H35K1	33A10		0.35			133				10		
		H35K1	67A10		0.35			167				10		
		H35K2	00A10		0.35			200			10			
		H35K1	33A20			0.35			133			20		
10.5		H30K1	33A10			0.30			133			10		_
406 4 <u>07</u>		Table	e 2. Ke	y colun	nn base d	esign chara	cteristi	cs of th	ne sixte	en SC-	MRF-0	CBs.		
	Frame	$L_{WHP}$	$D_e$	$D_i$	$F_{y,WHP,i}$	$K_{fe}$	$L_{sp}$	$h_{wp}$	$L_{ER}$	$D_{ER}$	$Z_d$	$Z_{ER,d}$	$L_{CFT}$	Т
	Traine	(m)	(m)	(m)	(kN)	(MN/m)	(m)	(m)	(m)	(m)	(m)	(m)	(m)	(kN)
H	440K133A5	0.12	0.04	0.02	161.78	109.22	0.37	0.24	7.49	0.02	0.24	0.09	0.44	262.70
Η	40K133A15	0.07	0.03	0.02	156.39	260.19	0.33	0.21	7.47	0.02	0.26	0.16	0.44	271.41
Η	40K167A15	0.06	0.03	0.02	158.54	307.41	0.33	0.20	7.39	0.02	0.24	0.37	0.73	273.25
H	440K167A5	0.21	0.05	0.02	151.38	38.68	0.40	0.27	9.59	0.02	0.25	0.38	0.73	228.89
Η	40K133A10	0.06	0.04	0.02	166.28	357.10	0.33	0.20	8.50	0.02	0.21	0.15	0.44	274.02
Η	40K167A10	0.10	0.04	0.02	132.46	122.24	0.34	0.22	7.62	0.02	0.42	0.37	0.73	261.05
Η	40K133A24	0.06	0.03	0.02	163.63	396.73	0.32	0.20	5.52	0.03	0.19	0.10	0.44	281.83
H	H35K133A5	0.12	0.04	0.02	136.90	89.09	0.36	0.23	7.58	0.02	0.27	0.12	0.44	204.77
Н	35K133A15	0.06	0.04	0.02	142.89	264.52	0.32	0.20	6.64	0.02	0.22	0.16	0.44	212.16
Н	35K167A15	0.06	0.03	0.02	100.44	189.61	0.30	0.18	7.32	0.02	0.56	0.36	0.73	212.51
H	I35K167A5	0.19	0.04	0.02	125.10	34.27	0.38	0.26	8.73	0.02	0.27	0.38	0.73	171.44
Н	35K133A10	0.08	0.04	0.02	142.58	184.52	0.34	0.21	6.35	0.02	0.23	0.16	0.44	207.34
Н	35K167A10	0.05	0.04	0.02	88.76	184.92	0.30	0.17	8.65	0.02	0.70	0.36	0.73	215.25
Н	35K200A10	0.06	0.04	0.02	125.24	251.67	0.31	0.19	8.70	0.02	0.34	0.50	0.91	212.51
Н	35K133A20	0.06	0.03	0.02	113.55	252.32	0.31	0.18	7.64	0.03	0.44	0.13	0.44	212.51
н	30K133A10	0.06	0.03	0.02	104.64	212.41	0.30	0.18	5.99	0.03	0.37	0.15	0.44	151.00

408

#### 409 4 NON-LINEAR MODELS

410 The OpenSees platform [48] was used to model the prototype SC-MRF and SC-MRF-CBs. 411 The PT beam-column connections in all frames were modelled as in [35]. The columns and 412 the length of the beams that is reinforced were modelled with beam-column fiber elements 413 that exhibit bi-linear elastoplastic stress-strain behaviour. Force-based beam-column fiber 414 elements with end hinges [49] were used for the un-reinforced lengths of the beams. The 415 stress-strain cyclic behaviour of the fibers was modelled by utilising the modified Ibarra-416 Krawinkler model [50]. This model was used because it captures the strength and stiffness 417 degradation resulting from beam local buckling observed after the end of the beam flange 418 reinforcing plates. This type of modelling was used in [51] and results in hysteretic curves for 419 flexural members that are smooth and similar to the ones observed in experiments. The 420 Ibarra-Krawinkler model does not take into account the effect of a variable axial force on the 421 bending deterioration parameters [51]. The use of fiber elements results in reductions of the 422 bending strength of the beam-column elements due to the variable axial-moment interaction 423 [51]. Thus, this approach also captures the axial force (caused by the PT force at the tendons) 424 - bending moment interaction in the beams of the frames [35,51]. Panel zones are modelled 425 based on [52]. The OpenSees model developed in [29] is used for the column bases of the 426 SC-MRF-CBs. The gravity columns of the tributary area of the frames are modelled as three 427 lean-on columns to take into account P- $\Delta$  effects. Truss elements that connect the nodes of 428 the lean-on columns to nodes defined along the length of the beams at the points where the 429 secondary beams are placed are used to model diaphragm action of the composite slabs. The 430 diaphragm also helps to avoid the shortening of the PT beams (as these are seen in Figure 431 2(a)) due to the increase of the post-tensioning forces caused by to the connections' gap 432 opening and closing during seismic loads (the PT beams are only resist the constant axial force caused by the initial post-tensioning of their PT bars [10]). The stiffness of these trusses 433

434 is 100 times larger than that of the axial stiffness of the beam. By connecting separately each 435 bay's secondary beam nodes with the corresponding lean-on column node of the same storey, 436 these stiff truss elements help to model the discontinuity between the composite slabs that 437 correspond to each different bay of the self-centering system, as per the tributary area of the bay. Discontinuity between the composite slab and the flanges of the columns of the self-438 439 centering system is also assumed for the floor system utilised in this work [53]. The aim of 440 the above floor system discontinuities is to avoid that the PT beam be restrained by the 441 composite slab (minimizing the damage in the slab also); allow the free gap opening and 442 closing of the PT connection (thus, not affecting the connection's hysteretic behaviour) 443 [10,53]; and allow for the unobstructed self-centering frame expansion [10,36]. More details 444 on the adopted floor system can be found in [10,53,54]. The tendons of the column bases 445 were modelled to fracture to more accurately simulate the actual collapse limit of the frames 446 under investigation. To this purpose, the Fatigue material of OpenSees [48] was utilised in 447 conjunction with the parent material of the tendons. The parent material of the tendons is the 448 material around which the Fatigue material is wrapped [48], and which in this case is the 449 material steel01 of OpenSees [48]. The material steel01 has a bilinear elastoplastic hysteresis 450 with post-stiffness ratio equal to 0.03 [29]. The Fatigue material is wrapped around the 451 steel01 material without altering the stress-strain relationship of the latter [48]. The Fatigue 452 material utilises the Coffin-Manson relationship [55] and the Palmgren-Miner linear damage 453 accumulation rule [55] to model their low-cycle fatigue and fracture. The Coffin-Manson rule 454 is expressed by the relationship:

455 
$$\frac{\Delta \varepsilon_p}{2} = \varepsilon'_f \cdot \left(2 \cdot N_f\right)^m \tag{11}$$

456 where  $\frac{\Delta \varepsilon_p}{2}$  is the plastic strain amplitude;  $\varepsilon'_f$  the fatigue ductility coefficient, which represents 457 the intersect of the plastic asymptotic line of the Coffin-Manson curve in the log-log space,

i.e., the strain at which one cycle will cause failure (fracture) [55,56];  $N_f$  the number of the 458 459 full cycles to failure (or  $2 \cdot N_f$  the number of load reversals to failure); and m the fatigue 460 ductility exponent, which represents the sensitivity of the log of the strain amplitude to the 461 log of  $N_f$  [56], i.e., the slope of the Coffin-Manson curve in the log-log space. For the Fatigue material of the tendons,  $\varepsilon'_f$  was taken equal to 4%. This strain value is a conservative fracture 462 463 value as: (a) it represents the initial wire fracture of the strands of the tendons, ignoring the 464 appreciable strength reserve that remains at the tendons afterwards and through the fracture 465 of all their wires [38,39]; (b) it considers the premature fracture of the tendons due to excessive stress concentration at the vicinity of their anchors, as per the work of Bruce and 466 467 Eatherton [38], where the fracture value in question represents the average observed first-468 wire fracture limit (not the relevant proposed design limit) from their tested specimens, 469 considering both the tendon materials used therein, and also a newer multiple-use barrel and 470 wedge anchorage system that allowed for larger inelastic strains prior to initial wire fracture, 471 compared to the traditional barrel and wedge anchorage system that the authors also tested in 472 their work; (c) it represents the upper first-wire fracture limit attained from the tested 473 specimens in the work of Sideris et al. [39], given that their observed strain fracture values 474 ranged from 1.5% to 4%; and (d) it is a value much smaller than those provided by these 475 tendons manufacturers, i.e., 6-7% [57]. The fatigue ductility exponent, m, for the Fatigue 476 material of OpenSees, was taken equal to -0.458, as per the work of Uriz [56]. For the 477 maximum values of strain to be set out in the model of the material, the suggested minimum 478 and maximum values of -1e16 and 1e16, respectively, have been adopted [48]. To 479 accumulate damage in the material due to the random strain amplitude excursions during an 480 earthquake, the Fatigue material of OpenSees utilises a rainflow method [55] counting 481 algorithm to count the number of cycles at various strain amplitudes, in conjunction with the

Palmgren-Miner's linear damage accumulation Rule [55]. The Palmgren-Miner's Rule is
expressed by the damage index, *D*, which is given by the following mathematical formula:

484 
$$D = \sum_{i=1}^{j} \frac{n_i}{N_{f,i}}$$
(12)

where  $N_{f,i}$  is the number of cycles that can be resisted by the material until failure at the *i*th constant strain amplitude loading, in a total of *j* such loadings with constant strain amplitudes; and  $n_i$  is the number of loading cycles the material has undergone at the *i*th constant strain amplitude loading [55]. Once index *D* in the Fatigue material reaches the value of 1.0, the force (or stress) in the parent material becomes zero, signalling the failure of the parent material [48].

The fracture of the WHPs was not modelled in this study, as, based on previous experimental and numerical studies [14,54,58], their geometry and position around the column bases can be selected to avoid fracture before the building's seismic collapse due to second order effects [51].

#### 495 **5**

#### **5 NON-LINEAR DYNAMIC ANALYSES**

The set of the far-fault ground motions of FEMA P695 [59] was used for the non-linear dynamic analyses of this study. This set comprises 22 record pairs, each with two horizontal components for a total of 44 records. The ground motions of the above set were recorded on stiff soil and at sites with distance larger than or equal to 10 km from fault rupture. The magnitudes of the earthquakes range from *M* 6.5 to *M* 7.6 with an average magnitude of *M* 7.0. The records were scaled to DBE and MCE, using as intensity measure (IM) the 5% spectral acceleration at fundamental period  $T_1$  of the frame models,  $S_a(T_1)$ .

#### 503 5.1 Assessment of the seismic performance of the frames

504 The results of the 44 non-linear dynamic analyses for the SC-MRF and sixteen SC-MRF-CBs 505 were post-processed and the median maximum values of  $\theta_{s,max}$  of all the storeys and peak

506	floor acceleration (PFA) from all the floors are shown in Table 3. The results in Table 3
507	indicate that the $\theta_{s,max}$ of all SC-MRF-CBs is lower than that of the SC-MRF under the FOE,
508	DBE and MCE seismic intensity levels. In particular, for the FOE intensity level, the relative
509	reduction of the $\theta_{s,max}$ of the SC-MRF-CBs compared to that of the SC-MRF ranges from
510	3.03% for the H35K167A5 to 23.65% for the H35K167A10. Under the DBE, the relevant
511	minimum reduction of $\theta_{s,max}$ is 1.42% and achieved for the H35K133A5 and the maximum is
512	24.13% and achieved for the H40K167A15. Under the MCE, the H35K133A5 achieves the
513	minimum reduction of $\theta_{s,max}$ equal to 0.95% and the H35K167A10 the maximum equal to
514	18.55%. Moreover, all the SC-MRF-CBs achieve $\theta_{s,max}$ lower than the "life safety" and
515	"collapse prevention" limits of EC8 [6] and ASCE/SEI 41-06 [60]. As it can be seen from
516	Table 3, the SC-MRF-CBs achieve as much as a 24.05% overall $\theta_{s,max}$ reduction (minimum
517	reduction between all seismic intensity levels for the H35K167A10). These results
518	demonstrate that the new column base configuration is very effective in reducing $\theta_{s,max}$ , and
519	that is done by only adjusting its base stiffness and strength characteristics.

Table 3. Median maximum values of  $\theta_{s,max}$  of all the storeys and PFA from all the floors of the SC-MRF and SC-MRF-CB design cases.

Enomo	Fundamental		$\theta_{s,max}$ (%)	<u>U</u>		PFA (g)	
Frame	Period $T_1$ (s)	FOE	DBE	MCE	FOE	DBE	MCE
SC-MRF	0.94	0.655	1.814	2.623	0.499	1.043	1.487
H40K133A5	0.95	0.547	1.667	2.416	0.506	0.980	1.481
H40K133A15	0.95	0.530	1.529	2.336	0.534	0.932	1.385
H40K167A15	0.93	0.519	1.376	2.170	0.521	0.932	1.362
H40K167A5	0.93	0.621	1.671	2.494	0.520	1.036	1.462
H40K133A10	0.95	0.530	1.510	2.319	0.526	0.918	1.356
H40K167A10	0.93	0.531	1.433	2.264	0.542	0.954	1.316
H40K133A24	0.95	0.530	1.448	2.294	0.519	0.919	1.508
H35K133A5	0.95	0.576	1.788	2.598	0.509	0.911	1.428
H35K133A15	0.95	0.542	1.655	2.353	0.506	0.918	1.341
H35K167A15	0.93	0.501	1.384	2.147	0.489	0.903	1.416
H35K167A5	0.93	0.635	1.745	2.538	0.556	0.966	1.418
H35K133A10	0.95	0.546	1.683	2.379	0.495	0.910	1.392
H35K167A10	0.93	0.500	1.396	2.136	0.494	0.899	1.400
H35K200A10	0.91	0.506	1.534	2.140	0.504	0.887	1.367
H35K133A20	0.95	0.522	1.542	2.299	0.515	0.914	1.364
H30K133A10	0.95	0.543	1.667	2.299	0.470	0.864	1.364

523 The maximum values of PFA from all the floors of all the SC-MRF-CBs are lower than that 524 of the SC-MRF under the DBE. Under the FOE and MCE, all the values of PFA of the SC-525 MRF-CBs are lower than that of the SC-MRF, with the exception of H35K167A5 and 526 H40K133A24 for the FOE and MCE, respectively. The PFA reduction observed in the SC-MRF-CBs ranges from 5.81% to 23.65%, from 0.73% to 17.19% and from 0.42% to 11.46%, 527 528 under the FOE, DBE and MCE, respectively. Thus, the new self-centering column bases can 529 be very effective in reducing the PFA of an SC-MRF that will be equipped with these column 530 bases.

These results show that the SC-MRF-CBs have in general better seismic performance than the SC-MRF in terms of the above two engineering demand parameters examined. Low values of  $\theta_{s,max}$  and PFA are associated with low non-structural and equipment damage. Thus, non-structural elements and equipment installed to SC-MRF-CBs may exhibit less damage. In addition, since  $\theta_{s,max}$  dictates the design of columns in the serviceability limit state, there is a potential of reducing the cross-sections of the members of the SC-MRF-CBs because they exhibit very low values of  $\theta_{s,max}$ .

Figure 5 depicts the comparison of the height-wise distribution of  $\theta_{s,max}$  of all the frames 538 539 studied herein under the FOE, DBE and MCE. Under the FOE, the H40K167A15, 540 H40K167A10, H40K133A24, H35K167A15, H35K167A10 and H35K200A10 have lower values of  $\theta_{s,max}$  for all the storeys. The rest of the SC-MRF-CBs have lower values of  $\theta_{s,max}$ . 541 542 for all the storeys, with the exception of the first storey. It is also observed that the SC-MRF-CBs have lower values of  $\theta_{s,max}$  for all the storeys, with the exception of the first storey under 543 544 the DBE level. The same trend is observed for all the frames at the MCE level, with the 545 exception of H35K200A10, H35K167A15, H35A167A10 and H40K167A15, which have lower values of  $\theta_{s,max}$  for all the storeys. The reason for the increased first-storey  $\theta_{s,max}$ 546

547 demands of most of the SC-MRF-CBs is attributed to the gap openings of their self-centering





549 Figure 5 Comparison of the median height-wise distribution of the  $\theta_{s,max}$  of the SC-MRF and 550 SC-MRF-CB designs under the: (a) FOE; (b) DBE; and (c) MCE intensity levels. 551 Figure 6 shows the comparison of the height-wise distribution of PFA under the FOE, DBE

553 and MCE. Under the FOE, apart from the H35K200A10, all the other SC-MRF-CBs have 554 higher PFAs compared to that of the SC-MRF. In the second storey, all the SC-MRF-CBs have higher PFAs compared to that of the SAC-MRF. In the third storey, there is a shift in 555 556 this trend; H30K133A10, H35K133A10, H40K133A24 and H35K133A15 have lower PFAs than that of the SC-MRF. In the fourth storey, only H35K133A5, H40K133A5, H35K167A5 557 558 and H40K167A5 have higher PFAs than that of the SC-MRF. Finally, in the fifth storey, 559 apart from H40K167A5, all the other SC-MRF-CBs have lower PFAs compared to that of the 560 SC-MRF. Under the DBE, the SC-MRF has PFAs lower than those of all the SC-MRF-CBs 561 in both the first and second storey. However, in the third storey, apart from H35K167A4 and H40K176A5 which have higher PFAs, and H40K167A10 which has similar PFA, all the 562

other SC-MRF-CBs have lower PFAs compared to that of the SC-MRF. Finally, in both the fourth and fifth storeys, all the SC-MRF-CBs have lower PFAs comparted to that of the SC-MRF. Under the MCE, apart from H35K133A15 that has lower PFA in its second storey, all the other SC-MRF-CBs have higher PFAs in all their three first storeys as compared to those of the SC-MRF. In the fourth storey, H40K167A15, H35K167A10 and H35K167A15 have lower PFAs as compared to the SC-MRF. Lastly, in the fifth storey, all the SC-MRF-CBs have lower PFAs compared to that of the SC-MRF.



570 571 572

MRF-CBs under the: (a) FOE; (b) DBE; and (c) MCE intensity levels.

573 The PFA distribution of Figure 6 can be explained by recent studies in self-centering MRFs 574 with connections similar to those of the SC-MRF-CBs. These suggest that the magnitudes of 575 the PFAs and their distribution is influenced by the interactions between the beams and 576 columns of these systems. These member interactions are due to the discontinuity of their 577 connections and the asymmetry in member restraints due to the presence of the rocking in the 578 column bases [61].

#### 579 5.2 Effect of base strength and stiffness on the seismic performance of the frames

In this section, the effect of base strength and stiffness on the seismic performance of the frames examined herein is evaluated in terms of  $\theta_{s,max}$  and PFA. The parameters  $\eta$ ,  $\beta_{base}$  and  $\alpha$ , that are associated with the base strength and stiffness of the frames, were used for this evaluation.

584 In order to evaluate the effect of base strength of the frames to the response parameters  $\theta_{s,max}$ and PFA, the parameter  $\eta$  is examined. Thus, the design cases H40K133A10, H35K133A10 585 586 and H30K133A10, with  $\eta$  equals 0.40, 0.35 and 0.30, respectively, were compared. Figures 7(a) and 7(b) show  $\theta_{s,max}$  and PFA versus  $\eta$ , respectively, for the three seismic intensities 587 588 examined. As indicated in Figure 7(a), when  $\eta$  increases from 0.30 to 0.35,  $\theta_{s,max}$  also 589 increases for all the seismic intensity levels. The increase observed is 0.65%, 0.93% and 590 3.36% under the FOE, DBE and MCE, respectively. A further increase of  $\eta$  to 0.40 results in a reduction of  $\theta_{s,max}$  for all the seismic intensity levels. The reduction of  $\theta_{s,max}$  is 2.98%, 591 592 10.27% and 2.52% under the FOE, DBE and MCE, respectively. The same trend is observed 593 for the PFA but only for the MCE intensity level. Under FOE and DBE, an increase of  $\eta$ 594 results in an increase of PFA. More specifically, when  $\eta$  increases from 0.30 to 0.35, PFA 595 values increase by 5.07% and 5.02%, under the FOE and DBE, respectively. A further 596 increase of  $\eta$  to 0.40 results in an increase of PFA equal to 6% and 0.94%, under the FOE and 597 DBE, respectively.



600 601

602 The design cases examined herein were compared in terms of the parameters  $\beta_{base}$  and  $\alpha$  to 603 evaluate the effect of base stiffness on their seismic response. For the frames with  $\eta=0.40$ , the 604 following design cases were compared to evaluate the effect of  $\beta_{base}$ , i.e.: H40K133A5 605  $(\beta_{base}=133\%)$  and H40K167A5  $(\beta_{base}=167\%)$ , which have a value of  $\alpha=5\%$ ; H40K133A10 606  $(\beta_{base}=133\%)$  and H40K167A10  $(\beta_{base}=167\%)$ , with  $\alpha = 10\%$ ; and H40K133A15 ( $\beta_{base}$ =133%) and H40K167A15, with  $\alpha$ =15%. For the frames with  $\eta$ =0.35, the following 607 608 frames were compared: H35K133A5 ( $\beta_{base}$ =133%) and H35K167A5 ( $\beta_{base}$ =167%), with 609  $\alpha$ =5%; H35K133A10 ( $\beta_{base}$ =133%), H35K167A10 ( $\beta_{base}$ =167%) and H35K200A10 610  $(\beta_{base}=200\%)$ , with  $\alpha=10\%$ ; and H35K133A15 ( $\beta_{base}=133\%$ ) and H35K167A15  $\beta_{base}=167\%$ ), 611 with  $\alpha$ =15%. Figure 8 shows the effect of  $\beta_{base}$  to the seismic response, in terms of the  $\theta_{s,max}$ 612 and PFA, of the aforementioned design cases.

613 For the frames with  $\eta$ =0.40 and  $\alpha$ =5%, the results in Table 3 show that an increase of  $\beta_{base}$ from 133% to 167% results to higher values of  $\theta_{s,max}$ , for all the intensity levels. Thus, the 614 increase of  $\theta_{s,max}$  observed, due to the increase of  $\beta_{base}$ , is 11.91%, 0.25% and 3.11%, for the 615 616 FOE, DBE and MCE seismic intensity levels, respectively. The same increase of  $\beta_{base}$ , leads to a reduction of  $\theta_{s,max}$  for all the seismic intensity levels for the frames with  $\eta=0.40$  and 617 618  $\alpha$ =10%. The reduction observed equals 2.09%, 10.01% and 7.09%, under the FOE, DBE and MCE, respectively. Finally, an increase of  $\beta_{base}$  from 133% to 167% results to lower  $\theta_{s,max}$  for 619 620 the frames with  $\eta$ =0.40 and  $\alpha$ =15%, under the DBE and MCE. This trend is reversed under 621 the FOE. In addition, the increase of  $\beta_{base}$  from 133% to 167 results to higher values of PFA

622 under the FOE and DBE, for the frames with  $\eta$ =0.40 and  $\alpha$ =5% and  $\alpha$ =10%. In contrary, the 623 same increase of  $\beta_{base}$  leads to a reduction of PFA under all the seismic intensity levels for the 624 frames with  $\eta$ =0.40 and  $\alpha$ =15%.

625 For the frames with  $\eta$ =0.35 and  $\alpha$ =10% and  $\alpha$ =15%, results in Table 3 show that an increase 626 of  $\beta_{base}$  from 133% to 167% results to lower values of  $\theta_{s,max}$ , for all the seismic intensity 627 levels. For the frames with  $\alpha = 10\%$ , the reduction of  $\theta_{s,max}$ , due to the increase of  $\beta_{base}$ , is 628 8.46%, 17.09% and 10.21%, under the FOE, DBE and MCE, respectively. For the frames 629 with  $\alpha$ =10%, this reduction equals 7.56%, 16.40% and 8.76% under the FOE, DBE and 630 MCE. In the frames with  $\eta$ =0.35 and  $\alpha$ =5%, an increase of  $\beta_{base}$  from 133% to 167% results 631 to 2.43% and 2.31% lower values of  $\theta_{s,max}$ , under the DBE and MCE, respectively. An opposite trend is observed under the FOE. For the frames with  $\eta$ =0.35 and  $\alpha$ =5%, results 632 633 show that an increase of  $\beta_{base}$  from 133% to 167% results to 8.46% and 5.63% higher values 634 of PFA under the FOE and DBE, respectively. Under the MCE, the PFA of the frame with 635  $\beta_{base}$ =133% is 0.68% larger than that of with  $\beta_{base}$ =167%. For the frames with  $\eta$ =0.35 and  $\alpha$ =10%, results show that an increase of  $\beta_{base}$  from 133% to 167% results to 0.08% and 1.14% 636 637 lower values of PFA under the FOE and DBE, respectively. Under the MCE, the PFA of the 638 frame with  $\beta_{base}=167\%$  is 0.56% larger than that of with  $\beta_{base}=133\%$ . A similar trend is 639 observed for the frames with  $\eta$ =0.35 and  $\alpha$ =15%.





642 643 644 Figure 8 Effect of  $\beta_{base}$  to (a)  $\theta_{s,max}$  ( $\eta = 0.40$ ); (b) PFA ( $\eta = 0.40$ ); (c)  $\theta_{s,max}$  ( $\eta = 0.35$ ); and (d) (b) PFA 645  $(\eta = 0.35).$ 

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647 For the design cases with  $\eta$ =0.40, the following frames were compared to evaluate the effect of  $\alpha$  on  $\theta_{s,max}$  and PFA: H40K133A5 ( $\alpha$ =5%), H40K133A10 ( $\alpha$ =10%), H40K133A15 648 649  $(\alpha = 15\%)$  and H40K133A24 ( $\alpha = 24.5\%$ ), with  $\beta_{base} = 133\%$ ; and H40K167A5 ( $\alpha = 5\%$ ), 650 H40K167A10 ( $\alpha$ =10%) and H40K167A15 ( $\alpha$ =15%), with  $\beta_{base}$ =167%. This effect is shown in Figures 9(a)-(d) for these design cases. It is observed that the highest value of  $\theta_{s,max}$  is 651 652 achieved by H40K133A5 ( $\alpha$ =5%) for the frames with  $\beta_{base}$ =133%, under the FOE, DBE and MCE. The lowest values of  $\theta_{s,max}$  are achieved for the frame H40K133A24 ( $\alpha$ =24.5%) for 653 654 both the DBE and MCE. Frame H40K133A5 with  $\alpha$ =5% has the best PFA performance, 655 achieving the lowest value of PFA under the FOE. In addition, the frame with  $\alpha$ =10% has the best PFA performance under the DBE and MCE. For the frames with  $\beta_{base}$ =167%, increasing 656 657 the value of  $\alpha$  from 5% to 10%, results in a reduction of  $\theta_{s,max}$  for all the seismic intensity 658 levels. This reduction equals 14.48%, 14.22% and 9.21%, under the FOE, DBE and MCE, respectively. A further increase of  $\alpha$  from 10% to 15%, leads to a reduction of  $\theta_{s,max}$ , which 659 660 equals 2.31%, 3.98% and 4.23%, under the FOE, DBE and MCE, respectively. Increasing the 661 value of  $\alpha$  from 5% to 10%, leads to a 3.95% increase, and 7.94% and 9.93% reduction of PFA under the FOE, DBE and MCE, respectively. Finally, a further increase of  $\alpha$  from 10% 662

to 15%, leads to a 3.76% and 2.29% reduction and 3.32% increase of PFA, under the FOE,
DBE and MCE, respectively.

For the design cases with  $\eta=0.35$ , the following frames were compared: H35K133A5 665  $(\alpha=5\%)$ , H35K133A10 ( $\alpha=10\%$ ), H35K133A15 ( $\alpha=15\%$ ) and H35K133A20 ( $\alpha=20\%$ ), with 666 667  $\beta_{base}$ =133%; and H35K167A5 ( $\alpha$ =5%), H35K167A10 ( $\alpha$ =10%) and H35K167A15 ( $\alpha$ =15%), with  $\beta_{base}$ =167% (Figures 9(e)-(h)). For the frames with  $\beta_{base}$ =133%, the lowest values of 668  $\theta_{s,max}$  is achieved for the frame with the higher value of  $\alpha$ , i.e., 20% (H35K133A20), for all 669 670 the seismic intensity levels. The frame with  $\alpha$ =5% (H35K133A10) has the best PFA 671 performance, achieving the lowest value of PFA under DBA and MCE. In addition, the frame  $\alpha$ =15% has the best PFA performance under the MCE. For the frames with  $\beta_{base}$ =167%, 672 increasing the value of  $\alpha$  from 5% to 10%, results in a reduction of  $\theta_{s,max}$  for all the seismic 673 674 intensity levels. This reduction equals 21.26%, 20.02% and 15.83%, under the FOE, DBE 675 and MCE, respectively. A further increase of  $\alpha$  from 10% to 15%, leads to a 0.23% increase, 676 0.83% reduction and 0.49% increase of  $\theta_{s,max}$ , under the FOE, DBE and MCE, respectively. 677 Increasing the value of  $\alpha$  from 5% to 10%, leads to a 11.14%, 6.89% and 1.30% reduction of 678 PFA under the FOE, DBE and MCE, respectively. Finally, a further increase of  $\alpha$  from 10% to 15%, results to a 1.14% reduction, and 0.38% and 1.14% increase of PFA, under the FOE, 679 680 DBE and MCE, respectively.





681 Figure 9 Effect of  $\alpha$  to (a)  $\theta_{s,max}$  ( $\eta = 0.40, \beta_{base} = 133\%$ ); (b) PFA ( $\eta = 0.40, \beta_{base} = 133\%$ ); (c)  $\theta_{s,max}$  ( $\eta = 0.40, \beta_{base} = 167\%$ ); (d) PFA ( $\eta = 0.40, \beta_{base} = 167\%$ ); (e)  $\theta_{s,max}$  ( $\eta = 0.35, \beta_{base} = 133\%$ ); (f) PFA ( $\eta = 0.35, \beta_{base} = 133\%$ ); (g)  $\theta_{s,max}$  ( $\eta = 0.35, \beta_{base} = 167\%$ ); and (h) PFA ( $\eta = 0.35, \beta_{base} = 167\%$ ). 684

#### 685 5.3 Residual drift performance of the frames

Figure 10 shows the height-wise distribution of the median residual drifts ( $\theta_{s,res}$ ) of the SC-686 687 MRF, H35K133A5 and H35K200A10 under the MCE, together with a maximum allowable limit for residual drifts. This limit was proposed by McCormick et al. [62] and utilised to 688 characterise repairability in such buildings. The rationale for presenting only these two SC-689 690 MRF-CBs is that they are those that exhibit the lowest and highest  $\theta_{s,res}$  values among the investigated frames. Residual drifts are recognised as an important index of the seismic 691 692 performance and resilience of structures since they are directly linked to probability of 693 demolition of a building [34,62]. It is observed that all the frames have values of  $\theta_{s,res}$  lower 694 than the proposed limit in [62] and that both H35K133A5 and H35K200A10 have lower  $\theta_{s,res}$ values for all their storeys than those of the SC-MRF. These values are almost negligible. 695



696 697 H35K200A10 under the MCE, plotted against the maximum allowable limit for residual interstorey 698 drifts proposed by McCormick et al. [62]. 699 700 Figure 11 shows the stress-strain hysteresis loops in the flanges of the first-storey columns 701 (Figure 3(a)) of the H35K133A5 and H35K200A10 under the 1992 Landers earthquake 702 scaled to the MCE. It is observed, that the two SC-MRF-CBs do not exhibit any plastic deformation in their first-storey columns since the developed maximum stress at the extreme 703 704 fibers of their flanges is well below the yield stress limit of 355 MPa. Thus, damage is avoided at their self-centering column bases. This shows that the values of  $\theta_{s,res}$  observed in 705 706 SC-MRF-CBs (Figure 10) mainly result from permanent deformations that occur at PT beam-707 column connections. Similar results are observed for the rest of the SC-MRF-CBs and ground 708 motions but are not shown herein due to lack of space.



Figure 11 Stress strain hysteresis loops of a flange of a first storey column of: (a) H35K133A5; and
(b) H35K200A10 under the 1992 Landers earthquake scaled to MCE.

#### 712 6 COLLAPSE ASSESSMENT

713 The collapse resistance of the frames is determined by the use of IDA [63].  $S_a(T_1)$  is the IM 714 used herein and  $\theta_{s,max}$  was the response parameter monitored. The set of ground motions used 715 for the non-linear dynamic analyses in Section 5 were used also for the IDAs. For each design case and ground motion, the collapse  $S_a(T_1)$  value at which  $\theta_{s,max}$  increases without 716 717 bound was obtained. To determine the limit of collapse, the criterion adopted by Seo et al. 718 [64] was used. Thus, the incremental slopes were calculated by drawing straight lines 719 between the consecutive data points in the IDA curve. The lowest  $S_a(T_1)$  value corresponding to the  $i^{\text{th}}$  data point with the slope between the  $i^{\text{th}}$  and  $i+I^{\text{th}}$  points being less than 10% of the 720 721 initial slope on the IDA curve was defined as the collapse  $S_a(T_1)$ . The initial slope was determined from the straight line from the origin of axis to the first data point of the IDA 722 723 curve. A collapse fragility curve was generated by fitting a lognormal cumulative distribution 724 function to the collapse  $S_a(T_1)$  values determined for each frame. The median value,  $S_{CT}$ , and 725 the lognormal standard deviation,  $\beta$ , of collapse  $S_a(T_1)$  values define this distribution. The 726 value of  $S_{CT}$  was amplified to take into account the effect of the distinct spectral shape of rare 727 ground motions, characterised by the parameter  $\varepsilon$  [65]. In this work, the simplified 728 methodology proposed by FEMA P695 [59] is adopted, where the influence of the spectral shape is taken into account by the use of a spectral shape factor (SSF). Thus, the values of  $S_{CT}$ 729 730 of all the frames of this study were multiplied by SSF to estimate their true collapse capacity.

The parameter  $\beta$  affects the shape of the fragility curve and is a measure of the level of uncertainty in the analysis results. The system-level and the record-to-record uncertainty were used for the construction of the fragility curves. The FEMA P695 [59] regulations were used for the calculation of the total uncertainty, where additional system-level uncertainty were added from three categories [43]. The total uncertainty of the system,  $\beta_{Total}$ , is given by:

$$\beta_{Total} = \sqrt{\beta_{RTR}^2 + \beta_{DR}^2 + \beta_{TD}^2 + \beta_{MDL}^2}$$
(13)

737 where  $\beta_{RTR}$  is the record-to-record uncertainty,  $\beta_{DR}$ ,  $\beta_{TD}$  and  $\beta_{MDL}$  are the additional 738 uncertainty because of the robustness of the design requirements, the accuracy of the test data 739 and the accuracy of the numerical model, respectively. The values of  $\beta_{RTR}$  were taken from 740 the results of the IDA, while values of the rest uncertainties were based on P695 741 recommendations [59]. Thus, the uncertainties  $\beta_{DR}$ ,  $\beta_{TD}$  and  $\beta_{MDL}$  can be subjectively 742 classified as 'superior', 'good', 'fair', or 'poor' [59]. The uncertainty due to the robustness of the design requirements, accuracy of the test data and numerical model were assigned each 743 rating of 'superior', 'good', 'fair' and 'poor' together to construct four different collapse 744 fragility curves. The values of uncertainty for 'superior', 'good', 'fair' and 'poor' uncertainty 745 746 rating were 0.1, 0.2, 0.35 and 0.5, respectively. Figure 12 shows the IDA curves of the 747 H35K200A10 together with the collapse fragility curves, for different uncertainty ratings as 748 per the aforementioned procedure.





Figure 12 (a) IDA curves; and (b) corresponding collapse fragility curves of the H35K200A10.
Finally, the constructed collapse fragility curves were used for the evaluation of the collapse
risk of the frames through the adjusted collapse margin ratio (*ACMR*), defined as:

$$ACMR = \frac{S_{CT}}{S_{MT}} \cdot SSF$$
(14)

where  $S_{\text{CT}}$ , is the median collapse intensity of the frames,  $S_{\text{MT}}$  is intensity demand to the MCE-level intensity.

## 756 7 EFFECT OF BASE STRENGTH AND STIFFNESS ON THE COLLAPSE RISK 757 OF THE FRAMES

Table 4 shows the collapse capacity results of all the investigated frames. The SC-MRF-CBs
have larger value of collapse capacity and *ACMR*, compared to the SC-MRF. The maximum
increase in collapse capacity and *ACMR* is achieved by the H35K200A10 compared to SCMRF, whereas the minimum increase of these parameters is achieved by the H35K133A5.
Collapse capacity and *ACMR* of the SC-MRF-CBs design cases are 25.08-33.23% and 23.0227.95% higher, respectively, than that of the SC-MRF. Thus, there is a significant

improvement of the collapse capacity and *ACMR*, by adopting the self-centering column
bases and appropriately tuning their base stiffness and strength characteristics.

Figure 13 shows the collapse fragility curves of the SC-MRF, H35K133A5 and H35K200A10 for different uncertainty ratings. These two SC-MRF-CBs were selected because they achieve the lower and higher increase of *ACMR*, compared to the SC-MRF. It is observed that the H35K133A5 and H35K200A10 are exhibiting, in general, the lowest probabilities of collapse. This trend is inverted for low values of  $S_a(T_1)$ , for superior, good and fair uncertainty ratings, and for poor uncertainty ratings the probabilities of collapse are similar for all the frames.

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Table 4. Collapse capacity results.

			<u> </u>		
Frame	$S_{\rm MT}\left({ m g} ight)$	$S_{\rm CT}(g)$	CMR	SSF	ACMR
SC-MRF	0.90	3.70	4.10	1.23	5.06
H40K133A5	0.93	5.04	5.44	1.23	6.72
H40K133A15	0.93	5.17	5.57	1.23	6.88
H40K167A15	0.95	5.39	5.67	1.23	6.97
H40K167A5	0.95	5.28	5.56	1.23	6.83
H40K133A10	0.93	5.19	5.60	1.23	6.92
H40K167A10	0.95	5.38	5.66	1.23	6.95
H40K133A24	0.92	5.04	5.45	1.24	6.74
H35K133A5	0.93	4.94	5.32	1.23	6.57
H35K133A15	0.93	5.18	5.59	1.23	6.87
H35K167A15	0.95	5.32	5.60	1.23	6.89
H35K167A5	0.95	5.27	5.54	1.23	6.80
H35K133A10	0.93	5.19	5.60	1.23	6.91
H35K167A10	0.95	5.35	5.64	1.23	6.92
H35K200A10	0.97	5.54	5.74	1.22	7.02
H35K133A20	0.93	5.04	5.43	1.23	6.70
H30K133A10	0.93	5.11	5.51	1.23	6.81

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To evaluate the effect of base strength on the collapse risk of the frames, the base strength factor  $\eta$  was utilised. To this end, the design cases H40K133A10, H35K133A10 and H30K133A10, with  $\eta$  equals 0.40, 0.35 and 0.30, respectively, were compared. The H40K133A10 has the largest value of *ACMR* among the frames compared, indicating that the frame with the largest value of  $\eta$  has the lowest collapse risk. When the value of  $\eta$  is increased from 0.30 to 0.35, the *ACMR* is increased by 1.5%. In addition, the value of *ACMR* for the H40K133A10 with  $\eta = 0.40$  is 1.61% higher than that of the H30K133A10 with  $\eta =$ 0.30. Thus, the collapse risk of the frames is reduced for higher values of  $\eta$ .

The frames examined here were compared in terms of their base factors  $\beta_{base}$  and  $\alpha$  to assess 783 784 the effect of base stiffness on their collapse risk. For the frames with  $\eta=0.40$ , the following 785 frames were compared to evaluate the effect of  $\beta_{base}$ , i.e.: H40K133A5 ( $\beta_{base}$ =133%) and H40K167A5 ( $\beta_{base}$ =167%), which have a value of  $\alpha$ =5%; H40K133A10 ( $\beta_{base}$ =133%) and 786 787 H40K167A10 ( $\beta_{base}$ =167%), with  $\alpha$ =10%; and H40K133A15 ( $\beta_{base}$ =133%) and 788 H40K167A15, with  $\alpha$ =15%. For the frames with  $\eta$ =0.35, the following frames were compared: H35K133A5 ( $\beta_{base}$ =133%) and H35K167A5 ( $\beta_{base}$ =167%), with  $\alpha$ =5%; 789 790 H35K133A10 ( $\beta_{base}$ =133%), H35K167A10 ( $\beta_{base}$ =167%) and H35K200A10 ( $\beta_{base}$ =200%), 791 with  $\alpha = 10\%$ ; and H35K133A15 ( $\beta_{base} = 133\%$ ) and H35K167A15 ( $\beta_{base} = 167\%$ ), with  $\alpha = 15\%$ .

792 The results in Table 4 indicate that an increase of  $\beta_{base}$  from 133% to 167% results to higher 793 values of ACMR for the frames with  $\eta$ =0.40. Thus, the increase of ACMR observed, due to 794 the increase of  $\beta_{base}$ , is 1.63%, 0.46% and 1.21% for the design cases with  $\alpha$  equals 5%, 10% 795 and 15%, respectively. Similar results are obtained for the frames with  $\eta$ =0.35. The values of 796 ACMR of the frames with  $\beta_{base}$  equal to 167% are 3.40%, 0.12% and 0.29% higher than those 797 of the frames with  $\beta_{base}$  equal to 133%, when  $\alpha$  equals 5%, 10% and 15%, respectively. In 798 addition, the frame H35K200A10 ( $\beta_{base}$ =200%) has 1.46% and 1.58% higher values of 799 ACMR than those of the H35K167A10 ( $\beta_{base}$ =167%) and H35K133A10 ( $\beta_{base}$ =133%), 800 respectively. Thus, it can be concluded that the collapse resistance of the frames is increased 801 for frames with higher values of  $\beta_{base}$ , representing the initial base stiffness.



Figure 13 Collapse fragility curves of SC-MRF, H35K133A5 and H35K200A10 for: (a) superior; (b) good; (c) fair; and (d) poor uncertainty rating.

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809 For the design cases with  $\eta$ =0.40, the following frames were compared to evaluate the effect 810 of  $\alpha$ : H40K133A5 ( $\alpha$ =5%), H40K133A10 ( $\alpha$ =10%), H40K133A15 ( $\alpha$ =15%) and 811 H40K133A24 ( $\alpha$ =24.5%), with  $\beta_{base}$ =133%; and H40K167A5 ( $\alpha$ =5%), H40K167A10 812 ( $\alpha$ =10%) and H40K167A15 ( $\alpha$ =15%), with  $\beta_{base}$ =167%. The results indicate that the higher value of ACMR is achieved by H40K133A10 ( $\alpha$ =10%), for the frames with  $\beta_{base}$ =133%. 813 814 Thus, collapse resistance of the frames is increased by 2.89% when  $\alpha$  increases from 5% to 815 10%, and is then reduced for further increase of  $\alpha$ . For the frames with  $\beta_{base}=167\%$  a different 816 trend is observed, with ACMR having higher values when  $\alpha$  increases. Thus, the frame 817 H40K167A15 ( $\alpha$ =15%) has 0.22% and 1.96% higher values of ACMR than those of 818 H40K167A10 ( $\alpha$ =10%) and H40K167A5 ( $\alpha$ =5%), respectively.

For the design cases with  $\eta$ =0.35 the following frames were compared: H35K133A5 ( $\alpha$ =5%), H35K133A10 ( $\alpha$ =10%), H35K133A15 ( $\alpha$ =15%), and H35K133A20 ( $\alpha$ =20%), with  $\beta_{base}$ =133%; and H35K167A5 ( $\alpha$ =5%), H35K167A10 ( $\alpha$ =10%) and H35K167A15 ( $\alpha$ =15%), with  $\beta_{base}$ =167%. The results of the frames with  $\beta_{base}$ =133% demonstrate that the *ACMR* is increased when  $\alpha$  is increased from 5% to 15% and is then reduced for further increase of  $\alpha$ . A similar trend is observed for the frames with  $\beta_{base}$ =167%.

#### 825 8 CONCLUSIONS

826 The potential of the SC-MRF-CBs to improve the seismic performance and reduce the 827 collapse risk of earthquake-resilient steel buildings with SC-MRFs was examined. The effect of strength and stiffness characteristics of the novel self-centering column base to improve 828 829 the seismic performance and collapse capacity of the SC-MRF-CBs was also investigated. 830 The parameters through which these effects were taken into consideration were three 831 normalised factors that represent the initial stiffness, post-yield stiffness and strength of the 832 self-centering column bases. These structural properties of the self-centering column bases 833 can be independently adjusted by utilising the analytical expressions that are presented in this 834 research, thereby changing also the initial stiffness, post-yield stiffness and strength of the 835 whole SC-MRF-CBs. A design procedure for the self-centering column bases, which is 836 enhanced compared to that in [29], is also proposed to that purpose. The evaluation of the 837 seismic performance and collapse risk of the SC-MRF-CBs was based on a prototype steel 838 building designed to incorporate different seismic-resistant frames, i.e., one SC-MRF and 839 sixteen SC-MRF-CBs' designs with different base stiffness and strength characteristics. A set 840 of 44 ground motions that were scaled to three seismic intensity levels was utilised to 841 perform non-linear dynamic analyses and evaluate the seismic performance of the frames. Moreover, IDA was used with the same set of ground motions to evaluate the collapse 842

capacity of the frames. Finally, fragility curves and the *ACMR* of the frames were derived tocompare their seismic risk.

845 On the basis of the findings of this paper, the following conclusions can be drawn:

- 846 1. The SC-MRF-CBs have in general better seismic performance than the SC-MRF in 847 terms of  $\theta_{s,max}$  and PFA. The results demonstrate that the self-centering column base 848 is very effective in reducing  $\theta_{s,max}$  and PFA, by only tuning its base stiffness and 849 strength characteristics. Thus, non-structural elements and equipment installed to SC-850 MRF-CBs will potentially exhibit less damage. A potential of reducing the cross-851 sections of the members of the SC-MRF-CBs can be also concluded. That is because the SC-MRF-CBs exhibit  $\theta_{s,max}$  values lower than the relevant limits of EC8 under the 852 853 FOE, DBE and MCE. This reduction reaches an appreciable 24.05%.
- The H35K133A5 and H35K200A10 (i.e., the two frames that exhibit the lowest and highest values of  $\theta_{s,res}$  among the investigated SC-MRF-CBs) have lower values of  $\theta_{s,res}$  in all their storeys, compared to those of the SC-MRF. These values are almost negligible and are solely due to permanent deformations in the PT beam-column connections since the self-centering column bases behave elastically up to their targeted rotations.
- 3. The SC-MRF-CBs have superior collapse capacity compared to the SC-MRF. The
  collapse capacity and *ACMR* of the SC-MRF-CBs are increased by up to 33.23% and
  27.95%, respectively, compared to the SC-MRF.
- 863 4. The collapse risk of the SC-MRF-CBs is reduced for higher values of  $\eta$ . The 864 H40K133A10 with  $\eta$ =0.40 has the largest value of *ACMR* and thus the lowest 865 collapse risk compared to the frames with  $\eta$  equal to 0.35 and 0.30.
- 866 5. It is concluded that collapse capacity of the frames is increased for frames with higher 867 values of  $\beta_{base}$ . The SC-MRF-CBs with  $\beta_{base}$ =167% have superior collapse resistance

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868 than the ones with  $\beta_{base}=133\%$ , when  $\eta=0.40$ . The maximum increase of ACMR observed, due to the increase of  $\beta_{base}$ , is 1.63% for the design cases with  $\alpha$ =5%. 869 Similar results are obtained for the frames with  $\eta$ =0.35. The values of ACMR of the 870 871 frames with  $\beta_{base}$ =167% are 3.40%, 0.12% and 0.29% higher than those of the frames with  $\beta_{base}$ =133%, when  $\alpha$  equals 5%, 10% and 15%, respectively. In addition, the 872 873 frame H35K200A10 ( $\beta_{base}$ =200%) has 1.46% and 1.58% higher values of ACMR than 874 those of the H35K167A10 ( $\beta_{base}$ =167%) and H35K133A10 ( $\beta_{base}$ =133%), 875 respectively.

6. The results for the SC-MRF-CBs with  $\eta$ =0.40 indicate that the higher value of *ACMR* is achieved by the frame with  $\alpha$ =10%, for the frames with  $\beta_{base}$ =133%. Thus, the collapse capacity of the frames increases by 2.89% when  $\alpha$  increases from 5% to 10% and is then reduced for further increase of  $\alpha$ . For the frames with  $\beta_{base}$ =167%, a different trend is observed, with *ACMR* having higher values when  $\alpha$  is increased up to 15%.

882 7. For the SC-MRF-CBs with  $\eta$ =0.35 and  $\beta_{base}$ =133%, it is observed that the *ACMR* is 883 increased when  $\alpha$  is increased from 5% to 15% and is then reduced for further 884 increase of  $\alpha$ . A similar trend is observed for the frames with  $\beta_{base}$ =167%. Thus, an 885 increase of  $\alpha$  up to a certain value leads to an increase of the collapse capacity of the 886 frames. It is also concluded that  $\alpha$  is more effective in increasing the collapse capacity 887 of the frames compared to  $\beta_{base}$ , because a similar increase of the collapse capacity is 888 achieved by increasing both parameters, but for a larger increase of  $\beta_{base}$ .

889 8. It is concluded that the best seismic performance and highest collapse capacity among 890 the SC-MRF-CBs examined is achieved for a combination of the strength factor,  $\eta$ , 891 equal to 0.35; initial stiffness factor,  $\beta_{base}$ , equal to 200%; and post-yield stiffness 892 ratio,  $\alpha$ , equal to 10%.

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