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Contribution of retinal motion toward the impulse control of target-directed aiming

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RUNNING HEAD: Moving background perturbation

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1 **Abstract**

2 Contemporary models of sensorimotor control contend that visually-regulated movement
3 adjustments may unfold early during a target-directed limb movement courtesy of an impulse
4 control process that makes use of anticipatory forward models. To-date, evidence surrounding
5 impulse control involves adjustments to a purported misperception in limb velocity following the
6 unexpected onset of a moving background. That is, the limb is perceived to move faster and
7 undershoots more whenever there is an incongruent moving background, and vice-versa.
8 However, it can be argued that this particular behaviour may alternatively manifest from an
9 independent oculo-manual-following response. The present study aimed to deconstruct these
10 proposals, and with it, the processes that underlie impulse control. Participants had to rapidly
11 reach upward to land their index finger accurately on a target. On 33% of trials, the background,
12 over which the movement was made, moved in either the upward, downward, rightward, or
13 leftward directions. Displacements within the primary and perpendicular directions of the
14 movement showed spatial trajectories that were consistent with the directions of the moving
15 backgrounds. This behaviour was most prevalent in measurements taken at the movements' peak
16 negative acceleration and endpoints. Moreover, the analysis of standardized displacements in the
17 moving background conditions indicated no significant differences in the extent of the
18 movements toward each of the moving backgrounds. These findings indicate that movement
19 adjustments can manifest from an oculo-manual-following response rather than a misperception
20 in limb velocity. We suggest that the anticipatory forward model that comprises impulse control
21 may incorporate features of the environment that surround the vicinity of the limb.

1 **Introduction**

2 One role of the visuomotor system is to facilitate control of timely and accurate upper
3 limb movements. Given that the need to move our hands quickly and accurately to specific
4 locations is a ubiquitous feature of the everyday human experience, there has been much
5 research devoted to the understanding of the processes that moderate the inherent trade-off
6 between speed and accuracy. Collectively, this work has established that we address this
7 challenge through organising our target-directed movements into two distinct phases; an *initial*
8 *impulse* phase that carries the limb most of the distance to the target, and a *current control* phase
9 that uses visual feedback during the movement in order to amend any error and successfully land
10 on the target (Woodworth, 1899; see also, Beggs & Howarth, 1972; Elliott, Helsen, & Chua,
11 2001; Keele & Posner, 1968; Meyer, Abrams, Kornblum, Wright, & Smith, 1988).

12 While the characteristics of target-directed movements are generally consistent with this
13 concept, recent evidence has highlighted how visually-regulated limb adjustments may take
14 place even earlier than previously thought. Thus, the original concept has been adapted by more
15 contemporary theoretical models including the Multiple Process Model (MPM; Elliott, Hansen et
16 al., 2010; Elliott, Lyons et al., 2017), which broadly states that there are multiple forms of
17 visuomotor control that are capable of making online limb adjustments (see also, Cluff,
18 Crevecoeur, & Scott, 2015; Desmurget & Grafton, 2000; Smeets, Wijdenes, & Brenner, 2016).

19 Specifically, the limb velocity and/or direction of the moving limb may be adjusted
20 within the early portion of the trajectory (<100 ms) during a process known as *impulse control*
21 (Hansen, Tremblay, & Elliott, 2008; Grierson & Elliott, 2008; Tremblay, Hansen, Kennedy, &
22 Cheng, 2013). In this regard, an unexpected perturbation to the limb would be adjusted almost
23 immediately by reinstating a trajectory path that could later enable the limb to land on the target.

1 Because this control process unfolds rapidly and relies upon response-produced feedback, it may
2 be explained by a pre-response forward model that anticipates the upcoming sensory
3 consequences of the movement in order to compare it with the actual sensory consequences
4 (Gallivan, Chapman, Wolpert, & Flanagan, 2018; Wolpert & Ghahramani, 2000; Wolpert, Miall,
5 & Kawato, 1998).

6 On the other hand, the difference between the spatial locations of the moving limb and
7 target may be adjusted within the late portion of the trajectory during a process known as *limb-*
8 *target control* (Elliott et al., 2014; Grierson & Elliott, 2008; Heath, Hodges, Chua, & Elliott,
9 1998). Thus, in the event that the target position is suddenly shifted, then the performer would
10 realign the spatial locations of the limb and target in order to minimize any distance between
11 them just prior to reaching the end of the trajectory. Because this control process is
12 comparatively slow and alternatively relies upon external visual feedback, it is not necessarily
13 determined by a pre-response forward model, but a more traditional closed-loop model (e.g.,
14 Keele & Posner, 1968; Woodworth, 1899).

15 Although the MPM has proven valuable in explaining movement behaviour across a
16 number of highly relevant performance contexts (Deuble, Connick, Beckman, Abernethy, &
17 Tweedy, 2016; Trejos, Patel, Maltaner, & Schlachta, 2014; Elliott, Grierson, Hayes, & Lyons,
18 2011), and pathological conditions (Niechwiej-Szwedo, Goltz, Colpa, Chandrakumar, & Wong,
19 2017; Pardhan, Scarfe, Bourne, & Timmis, 2017; Foster et al., 2020; Vimercati, Galli, Rigoldi,
20 Ancillao, & Albertini, 2013; for a review, see Elliott et al., 2020), there is still some debate
21 specifically about the processes underpinning impulse control. To-date, much of the evidence
22 surrounding impulse control comes from the analysis of movement adjustments that performers
23 make following illusory perturbations to the perceived velocity of the moving limb (Grierson &

1 Elliott, 2009; Grierson, Lyons, & Elliott, 2011; Proteau & Masson, 1997; Roberts & Grierson,
2 2019). These studies have been designed to introduce an unexpected translation in the
3 background over which the movement is executed. Specifically, a moving background that
4 moves in a direction that is incongruent with the direction of the moving limb is thought to create
5 the misperception that the limb is moving faster than expected. The consequence of this
6 misperception is that performers decelerate and undershoot the target more than they would
7 under normal conditions with an unperturbed background. Alternatively, a congruent moving
8 background may create the misperception that the limb is moving slower than expected, which
9 yields an inverse pattern of less deceleration and target undershooting (i.e., closer to target-
10 centre).¹

11 While the velocity misperception explanation of these findings is highly appealing, these
12 studies have typically isolated the moving background manipulation only to influence perception
13 of the primary movement direction. Yet, there is a growing body of research which indicates that
14 a perturbation to the surrounding environment can cause movement adjustments that are
15 independent of any limb velocity information. For example, the onset of a moving background
16 that is perpendicular to the aiming direction—no longer influencing the perceived velocity—can
17 cause the limb to move in the corresponding direction (Gomi, Abekawa, & Nishida, 2006;
18 Zhang, Brenner, Duysens, Vershueren, & Smeets, 2018; 2019). This movement occurs even in
19 cases where performers try to actively oppose the direction of the moving background, which
20 suggests this form of adjustment is highly automatized (Saijo, Murakami, Nishida, & Gomi,
21 2005). These particular adjustments have been attributed to an oculo-manual-following response,
22 which is driven by the direction of retinal motion and akin to the ocular-following response that
23 accompanies reflexive optokinetic control (Gomi, 2008; Whitney, Westwood, & Goodale, 2003).

1 These sets of findings challenge the viability and sufficiency of the velocity misperception
2 explanation (Grierson & Elliott, 2009; Proteau & Masson, 1997). That is, it must be acknowledged
3 that adjustments to movements that follow the onset of a moving background perturbation may
4 result from an oculo-manual-following response wherein the direction of the limb adjustments is
5 simply coincident with that of the moving background. Accordingly, the present study aimed to
6 more closely examine the responses that occur following the onset of a moving background
7 perturbation with a view to resolving the relative influence of these two proposed visuomotor
8 processes.

9 Participants executed rapid aiming movements in the upward direction with their
10 dominant limb.² The aiming movements were executed in front of a textured background, which
11 was static for the majority of trials. However, on a portion of the trials, the background would
12 unexpectedly move in one of four directions: upward, downward, rightward, and leftward.
13 Notably, the upward and downward moving backgrounds were parallel with the direction of the
14 moving limb, while the rightward and leftward moving backgrounds were perpendicular to the
15 direction of the moving limb. Consistent with the MPM framework (Elliott et al., 2017), we
16 examined the influence of these moving backgrounds across the entire trajectory, including peak
17 acceleration, peak velocity, peak negative acceleration, and movement end. These kinematic
18 landmarks are highly informative with the regards the nature of the adjustments to the moving
19 background because impulse control primarily comprises of the early landmarks, while limb-
20 target control is indicated only at the end of the movement.

21 If the early-onset adjustments are specific to a misperceived limb velocity, then we may
22 observe a typical counter-acting adjustment for the parallel moving backgrounds (as indicated by
23 a shorter and longer displacement in the primary direction for the downward and upward moving

1 backgrounds, respectively), but no or minimal adjustment for the perpendicular moving
2 backgrounds. Alternatively, the potential of a retinal motion artefact may render the direction of
3 movements toward all of the moving backgrounds (parallel and perpendicular; e.g., rightward
4 aiming direction for the rightward moving background, leftward aiming direction for the
5 leftward moving background). As a further possibility, movement adjustments may unfold as a
6 result of a simultaneous interaction between the two forementioned visuomotor processes (for a
7 similar logic using reaction time measures, see Sternberg, 1969; Grierson & Elliott, 2008; 2009).
8 Thus, while the influence of retinal motion may cause the limb to move in the same direction as
9 each of the moving backgrounds, the additional misperception in limb velocity that is caused
10 only by the parallel moving backgrounds may elicit an even greater magnitude of adjustment.
11 Consistent with previous studies on the moving background perturbation, we predict that either
12 of these patterns of movement behaviour would begin to manifest at peak negative acceleration
13 (e.g., Grierson & Elliott, 2009; Grierson et al., 2011; Roberts & Grierson, 2019; for movement
14 adjustments ~100-200 ms, see Gomi et al., 2006; Whitney et al., 2003).

15

16 **Methods**

17 *Participants*

18 There were 17 participants (15 males, 2 females; age range = 20-24 years) recruited for the
19 study. All participants self-reported that they were right-handed and clear of any neurological
20 conditions, and provided informed consent according to the guidelines set out by the local research
21 ethics committee and the Declaration of Helsinki (2013).

22

23 *Apparatus and Task*

1 Stimuli were presented on an LCD computer monitor (47.5 cm x 27.0 cm; temporal
2 resolution = 75 Hz; spatial resolution = 1920 x 1080 pixels), which was covered by a thin acrylic
3 sheet. The monitor was desktop-mounted and rotated 90° such that the long-edge was oriented in
4 the vertical axis. The monitor was adjusted to a height that aligned the center of the screen with
5 the eye-level for each participant.

6 Stimuli were generated via Matlab (2018b) (The Mathworks Inc., Natick, MA, USA)
7 running Psychtoolbox (version 3.0.11) (Pelli, 1997). The stimuli consisted of a grey target square
8 (5 mm x 5 mm), which was located upward at 160 mm from a centrally located crosshair (2 x 10
9 mm intersecting lines). The crosshair represented the starting point, or ‘home position’, for each
10 aiming movement. The stimuli also included a texture of black and white squares (48 squares; 7
11 mm x 7 mm each), which comprised the ‘background’. On perturbed trials, this texture moved in
12 the prescribed direction at a rate of 0.21 m/s (~70°/s). The background texture was continually
13 shifted so that when the squares reached the edge of the screen, it appeared as though they wrapped
14 around to continue moving in the same direction from the opposite edge.

15 Participants wore an NO/NC button micro-switch (Saia Burgess Electronics, Murten,
16 Switzerland) on their index finger, which was connected to the computer via a serial port.
17 Participants also wore a retro-reflective marker on the index finger of the right limb. This marker
18 enabled high-resolution motion capture via an optoelectric camera system (Vicon Vantage, 16-
19 megapixel resolution). Marker locations were sampled at 200 Hz, and collected for a period of 4
20 seconds per trial.

21

22 *Procedure*

1 Prior to commencing the experimental trials, the screen display was calibrated with respect
2 to the external motion capture system by having participants precisely locate their index finger
3 with the attached marker near the centre of a crosshair, which represented the target location. The
4 end target location for each individual participant was taken as the mean position from two separate
5 recordings at the start and end of each data collection session.³

6 Participants completed a series of 60 trials in which they moved their right index finger
7 from the home position to the target as quickly and accurately as possible. Each trial began when
8 the participant made contact with the central home position by depressing the micro-switch. The
9 aiming movement was then pre-cued via a grey unfilled square (20 x 20 mm; 1-mm thick lines)
10 which appeared around the target for 1s. Following a variable foreperiod between 800-2300 ms,
11 the target would change colour from grey to yellow; which signalled the participant to make their
12 aiming movement. For 40 of the trials, the background texture remained stationary. However, on
13 a random set of 20 trials (33%), the background would move in the upward, downward, rightward
14 or leftward directions as soon as the micro-switch was released at the start of the movement (5
15 trials per background direction). Participants were instructed to continue aiming toward the target
16 as quickly and accurately as possible regardless of whether the background moved. The
17 background movement was stopped as soon as the micro-switch was depressed again at the end of
18 the movement. While participants received complete online and terminal visual feedback of each
19 movement, they were not provided with any further augmented feedback. Participants could
20 commence the next trial by returning the micro-switch to the home position in their own time.

21

22 *Data Management and Analysis*

1 The data pertaining to the spatiotemporal location of the index finger were subjected to a
2 second-order, dual-pass Butterworth filter with a low-pass cut-off frequency of 10 Hz. Cartesian
3 coordinates from the primary direction of the movement (z-axis) were differentiated to obtain
4 velocity, which was differentiated again to obtain acceleration. Movement onset was identified as
5 the first frame that maintained a velocity greater than 20 mm/s for at least 40 ms (8 samples).
6 Movement offset was identified as the first frame following movement onset that reached a
7 velocity less than 20 mm/s and greater than -20 mm/s. Movement time was calculated as the time
8 difference between movement onset and movement offset. The displacement from the primary and
9 perpendicular directions of the aiming movements was calculated at each of the kinematic
10 landmarks of peak acceleration, peak velocity, peak negative acceleration and movement end.

11 For the analysis, we firstly wanted to ensure that any potential differences in the
12 displacement were not a result of a mere trade-off between speed and accuracy, and thus analysed
13 the participant mean movement times using a one-way repeated-measures analysis of variance
14 (ANOVA). For the main analyses, we conducted a multivariate analysis of variance (MANOVA)
15 (Wilks' Lambda) with moving background as a repeated-measures factor, and participant mean
16 displacement within the primary and perpendicular directions at each of the kinematic landmarks
17 as separate dependent variables.

18 Meanwhile, it is possible that any difference within each of the primary and perpendicular
19 directions of aiming could also be discriminated by an independent or combined influence of
20 multiple visuomotor processes. Specifically, there could be an additive contribution of both a
21 misperceived limb velocity and external retinal motion. In this regard, a simultaneous interaction
22 between each of these visuomotor processes would see an even greater movement adjustment for
23 the upward/downward perturbation compared to the leftward/rightward perturbation. Thus, we

1 undertook an additional analysis that focused on only those conditions where the moving
2 background perturbations were consistent with either the primary or perpendicular directions of
3 the movement (i.e., primary aiming direction for the upward and downward perturbations, and
4 perpendicular aiming direction for the leftward and rightward perturbations).

5 However, rarely is there a standard comparison of a common dependent variable between
6 the primary and perpendicular aiming directions (Khan et al., 2006). Indeed, any difference
7 between the raw data values of each of these aiming directions may also be attributed to their
8 inherent variability following mere differences in scale or magnitude (as indicated by the often
9 elliptical spatial variability profile, where variability is more heavily accumulated in the primary
10 compared to perpendicular aiming direction; Hansen, Elliott, & Khan, 2008; Gordon, Ghilardi, &
11 Ghez, 1994; Messier & Kalaska, 1999; see also Schmidt, Zelaznik, Hawkins, Frank, & Quinn,
12 1979). This difference is often taken as evidence of the primary and perpendicular aiming
13 directions being planned and controlled in separate, but simultaneous, fashion (Bard, Paillard,
14 Fleury, Hay, & Larue, 1990).

15 In order to avoid any such contamination, while more clearly isolating the influence of the
16 moving background perturbation, we initially standardized the mean displacements for the primary
17 and perpendicular aiming directions by separately converting them into absolute Z -scores ($|Z| =$
18 $\text{within-participant condition mean} - \text{within-participant grand mean of aiming direction} / \text{within-}$
19 $\text{participant standard deviation of aiming direction}$) (for a similar logic, see Lohse, Jones, Healy, &
20 Sherwood, 2014). Thus, if there was a simultaneous interaction between visuomotor processes that
21 sees a combination of influences from a misperceived limb velocity and external retinal motion,
22 then we should observe higher Z -scores for the upward/downward perturbation within the primary
23 aiming direction compared to the rightward/leftward perturbation within the perpendicular aiming

1 direction. In a similar vein to the previous analysis, a MANOVA was conducted with moving
2 background as a repeated-measures factor, and Z-scores at each of the kinematic landmarks being
3 the separate dependent variables.

4 In the case of each MANOVA, statistical significance was followed up by univariate
5 ANOVAs on each of the kinematic dependent variables with reference to the Greenhouse-Geisser
6 adjusted value (original or Sphericity-assumed degrees-of-freedom are reported). Further
7 significant effects were decomposed using the Tukey HSD post hoc procedure. Significance was
8 declared at $p < .05$, and effect sizes were indicated by using partial eta-squared (η^2).

9

10 **Results**

11 One participant was removed from the analyses due to excess target error (omitted
12 participant range of mean absolute constant error = 15.41-21.51 mm; remaining participant range
13 of mean absolute constant error = .05-8.75 mm). Aiming movements were executed at an average
14 time of 521 ms ($SE = 15$), and did not significantly differ across the moving background directions,
15 $F(4, 60) = .89, p = .45, partial \eta^2 = .06$. Consequently, any differences between the spatial limb
16 trajectories as a result of the moving backgrounds could not be attributed to any differences in the
17 available visual feedback processing time. The average movement trajectories for each of the
18 moving background directions are presented in Figure 1.

19

20 [Insert Figure 1 here]

21

22 MANOVA revealed a significant main effect of moving background perturbation, $F(32,$
23 $197) = 3.87, p = .00, partial \eta^2 = .36$. Subsequent univariate ANOVAs on the primary direction of

1 aiming at each kinematic landmark revealed no significant effect of moving background
2 perturbation at peak acceleration, $F(4, 60) = .61$, $p = .61$, $partial \eta^2 = .04$, or peak velocity, $F(4,$
3 $60) < .73$, $p = .53$, $partial \eta^2 = .05$. However, the analysis yielded a significant effect of moving
4 background perturbation at peak negative acceleration, $F(4, 60) = 3.94$, $p = .03$, $partial \eta^2 = .21$,
5 which indicated a significantly greater displacement when the background was perturbed in the
6 upward compared to downward direction ($ps < .05$, HSD = 11.59) (Table 1). There were no other
7 significant differences at peak negative acceleration ($ps > .05$). In a similar vein, there was a
8 significant effect of moving background perturbation at movement end, $F(4, 60) = 10.81$, $p = .00$,
9 $partial \eta^2 = .42$. The post hoc analysis revealed that there was a significantly greater displacement
10 when the background was perturbed in the upward compared to stationary, downward, and
11 leftward directions, while it was also significantly greater for the rightward compared to leftward
12 direction ($ps < .05$, HSD = 1.09). In addition, there was a significantly shorter displacement when
13 the background was perturbed in the downward compared to stationary, rightward, and leftward
14 directions ($ps < .05$).

15

16 [Insert Table 1 about here]

17

18 For the perpendicular direction of aiming, there was no significant effect of moving
19 background perturbation at peak acceleration, $F(4, 60) = .48$, $p = .68$, $partial \eta^2 = .03$, or peak
20 velocity, $F(4, 60) = 1.49$, $p = .23$, $partial \eta^2 = .09$. However, there was a significant effect of
21 moving background perturbation at peak negative acceleration, $F(4, 60) = 5.27$, $p = .005$, $partial$
22 $\eta^2 = .26$, which indicated a significantly greater rightward limb movement when the background
23 was perturbed in the rightward compared to all the other background directions ($ps < .05$, HSD =

1 1.50) (Table 2). Meanwhile, there was also a significant effect of moving background perturbation
2 at movement end, $F(4, 60) = 15.66, p = .00, partial \eta^2 = .51$. The post hoc analysis revealed that
3 there was a significantly greater rightward and leftward limb movement when the background was
4 perturbed in the rightward and leftward directions respectively as compared to all other
5 background directions ($ps < .05, HSD = .92$).

6

7

[Insert Table 2 about here]

8

9 *Velocity misperception vs. manual-following response*

10 Standardized Z-scores revealed no significant main effect of moving background
11 perturbation, $F(12, 111) = 1.52, p = .13, partial \eta^2 = .13$ (Table 3). Consequently, it is likely that
12 the previously cited influence on each of the primary and perpendicular directions of aiming did
13 not necessarily involve separate sets of visuomotor processes.

14

15

[Insert Table 3 about here]

16

17 **Discussion**

18 One of the emerging concepts from the sensorimotor literature is the discovery that
19 movement adjustments may unfold much earlier (i.e., $< 100ms$) than originally thought. This
20 feature has been heavily incorporated into the MPM (Elliott et al., 2017), where it is possible for
21 visually-regulated limb adjustments to be directed by early impulse and late limb-target control
22 processes. Because much of this framework has been adapted from evidence of early-onset
23 adjustments following moving backgrounds (Grierson & Elliott, 2009; Grierson et al., 2011;

1 Proteau & Masson, 1997; Roberts & Grierson, 2019), we aimed to elaborate upon this line of
2 research by incorporating moving backgrounds that continue to generate retinal motion without
3 necessarily perturbing the perceived velocity. That is, we introduced perpendicular moving
4 backgrounds that were independent of any manipulation on the perceived limb velocity.
5 Provided misperceived limb velocities underlie the early movement adjustments of target-
6 directed aiming, then we predicted that a counter-acting adjustment would solely manifest for the
7 parallel moving backgrounds (upward, downward), while there would be minimal adjustments
8 for the perpendicular moving backgrounds (rightward, leftward).

9 However, the findings generally indicated that the movement adjustments unfolded in the
10 same direction as the moving backgrounds regardless of its direction. What's more, the similarity
11 in the Z-scores for displacements that were consistent with the direction of the moving
12 background suggests that the adjustments to each of these directions did not necessarily manifest
13 from any different visuomotor processes. Thus, these data indicate that the movement
14 adjustments within target-directed aiming following a moving background perturbation may not
15 manifest from a misperceived limb velocity, but perhaps an oculo-manual-following response.

16 The possibility for illusory perturbations to the perceived velocity has long been known
17 (e.g., Duncker, 1929). Thus, the present findings should not be seen to contest such a
18 phenomenon, although it is debatable whether discrete target-directed aiming presents an optimal
19 setting for such a misperception to unfold. Indeed, previous examples of misperceived object
20 velocities typically require the ocular pursuit of the object in question (Raymond, Shapiro, &
21 Rose, 1984). When a moving background coincides with the object being tracked, then there is a
22 reflexive optokinetic response that causes retinal slip (Masson, Proteau, & Mestre, 1995). Thus,
23 it appears this illusion requires a combination of both extra-retinal (efferent) and retinal

1 (afferent) sources of information. However, the extra-retinal signals that contribute to this
2 misperception may be lost during target-directed aiming because it involves early fixation on the
3 target, while the parafoveal or peripheral visual field capture movement of the limb (Helsen,
4 Elliott, Starkes, & Ricker, 1998). While it is possible that a misperceived velocity may be
5 alternatively generated by combining the motor efference from the limb and retinal information,
6 it is highly unlikely that there is sufficient neurotransmission time for this to occur (Saijo et al.,
7 2005).

8 Alternatively, the present findings may be explained by evidence of a manual-following
9 response that is akin to the ocular-following response from reflexive optokinetic control (Gomi
10 et al., 2006; Gomi, 2008). This process typically underlies the inference of self-motion (i.e.,
11 displaced surroundings relative to one self within an otherwise stable world; von Helmholtz,
12 1867; for examples, see Tarita-Nistor, González, Markowitz, Lillakas, & Steinbach, 2006;
13 Tarita-Nistor, Hadavi, Steinbach, Markowitz, & González, 2014), and may be attributed to the
14 middle temporal/medial superior temporal (MT/MST) neural area (Whitney et al., 2007). At the
15 same time, there is an increasing argument that this manual-following response may not be
16 attributed to inferred self-motion, per se. Indeed, it has been shown that the manual-following
17 response only occurs when the moving background occupies the immediate vicinity of the target
18 location as opposed to a large-field or global display (Brenner & Smeets, 2015), while it fails to
19 manifest even when self-motion is directly induced by galvanic vestibular stimulation (Zhang et
20 al., 2019).

21 Of further relevance to the present study was the distinct kinematic landmark where the
22 movement adjustments could begin to take place. Indeed, the kinematic landmarks of peak
23 acceleration, peak velocity and peak negative acceleration are synonymous with impulse control,

1 where pre-response predictions surrounding the sensory consequences are formed for subsequent
2 comparison with the actual sensory consequences (Elliott et al., 2017). Meanwhile, the end of the
3 movement may be additionally attributed to limb-target control, which is concerned with the
4 relative spatial location of the moving limb and target. Consistent with previous findings on
5 target-directed aiming with a moving background perturbation (Grierson & Elliott, 2009;
6 Grierson et al., 2011; Roberts & Grierson, 2019), the moving background in this study appeared
7 to influence the movement from peak negative acceleration until the very end of the movement.
8 While peak negative acceleration is later than peak acceleration and peak velocity, it can still be
9 regarded as being a product of the pre-response arrangement of the initial movement before any
10 delayed processing of online visual feedback (Keele & Posner, 1968; Woodworth, 1899). Thus,
11 by definition, movement adjustments that unfold at this particular landmark may be attributed to
12 impulse control.

13 Surprisingly, there appeared even more differences between the moving background
14 conditions at the end of the movement, which may arguably indicate an increased influence
15 within a portion of the movement that is typically associated with limb-target control. This
16 outcome conflicts with previous accounts that examine the influence of the moving background
17 perturbation following a brief presentation of the target prior to movement onset (Gomi et al.,
18 2006). Likewise, the tendency to move in the same direction as the moving background has been
19 previously shown to decrease whenever the target is presented throughout the entire aiming
20 movement (Whitney et al., 2003). Along these lines, it should be recognised that the magnitude
21 of the pairwise differences at the end of the movement were still substantially smaller than those
22 previously identified at peak negative acceleration (see Figure 1). Thus, it appears that limb-
23 target control continues to unfold near the end of the movement in order to effectively diminish

1 at least some of the prior disruption that is caused by the moving background perturbation.
2 Moreover, it is possible that the differences found at the end of the movement were not
3 necessarily a direct result of the same visuomotor processes as those associated with impulse
4 control. For example, the effect of the moving background within early impulse control may
5 have downstream consequences for late limb-target control by contaminating the final portions
6 of the movement. This conjecture is consistent with recent suggestions that the impulse and
7 limb-target control processes are not as mutually exclusive as first thought, but alternatively
8 interact with one another (Grierson & Elliott, 2009; Elliott et al., 2017; Roberts, Lyons, Garcia,
9 Burgess, & Elliott, 2017).

10 The data presented here highlights that the influence of a moving background within
11 target-directed aiming is more closely aligned with the retinal motion explanation than the
12 misperception of limb velocity explanation. To this end, it is relevant to reconcile the current
13 findings within the context of the over-arching MPM framework. Because of the numerous
14 sources of evidence surrounding early impulse control, including visual (e.g., Grierson,
15 Gonzalez, & Elliott, 2009; Tremblay et al., 2013) and actual velocity-based (e.g., Grierson &
16 Elliott, 2009) perturbations, the present findings do not wholly contest this theoretical
17 perspective. Instead, it may be possible to incorporate the influence of surrounding
18 environmental cues into this model.

19 Specifically, upon review of the time-course of the previously reported manual-following
20 responses (~100-200 ms; Gomi et al., 2006; Whitney et al., 2003) alongside the current effects
21 yielded at peak negative acceleration (see also, Grierson & Elliott, 2009; Grierson et al., 2011;
22 Roberts & Grierson, 2019), we can reason that these particular movement adjustments are
23 associated with early impulse control. Thus, the forward model of the predicted sensory

1 consequences that mediate impulse control may also comprise the retinotopic coordinates of the
2 limb and surrounding environment – when the moving background unfolds and the visual field
3 momentarily shifts, then impulse control processes may try to adjust the direction of the limb
4 accordingly. Future research is required to more closely examine this possibility, and
5 subsequently explore the precise sources of information that comprise the forward model of
6 impulse control.

7 In conclusion, we have identified that the early-onset adjustments within target-directed
8 aiming following a moving background may be primarily attributed to the direction of retinal
9 motion. These effects on movement behaviour primarily manifest within early impulse control,
10 which may continue to indirectly influence late limb-target control. We suggest that the early
11 impulse control may additionally incorporate a representation of the surrounding environment, as
12 well as the previously stated response-produced feedback. Consequently, future attempts to access
13 the sensorimotor processes of impulse control should appropriately distinguish between
14 perturbations to the illusory surround and actual limb trajectory (e.g., Grierson et al., 2011).

15

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1 **Footnotes**

2 1) While there is some debate surrounding a potential asymmetry in the pattern of movement
3 adjustments for congruent and incongruent moving backgrounds (e.g., smaller magnitude
4 adjustments appear to unfold for a congruent compared to incongruent moving background;
5 Proteau & Masson, 1997; for a discussion, see Roberts & Grierson, 2019), it still stands that
6 both these contexts conceptually differ in their manipulation of the perceived limb velocity,
7 and with it, changes to the movement trajectory.

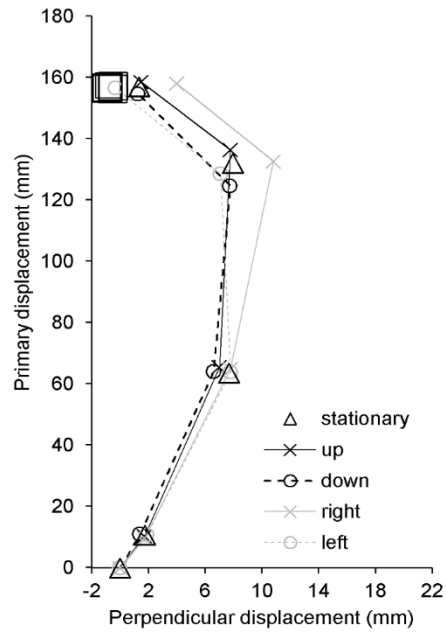
8 2) The current data are adapted from a previous study that was conducted with only the parallel
9 moving background directions (upward vs. downward), while participants aimed to targets
10 at upward and downward locations (see Roberts & Grierson, 2019). Thus, the previous
11 analysis only considered the congruent and incongruent moving background directions.
12 However, the present study additionally incorporates the perpendicular moving backgrounds
13 in the form of rightward and leftward directions. Because of the profound energy-
14 minimization processes that contaminate downward aiming movements (i.e., increased
15 undershooting to avoid energy-consuming overshoots against gravity), we primarily isolated
16 our analyses to the upward aiming movements. The visuomotor processes that potentially
17 discriminate these different aiming directions are of no theoretical value to the present study.

18 3) The within-participant spatial variability of calibrated target recordings revealed a range of
19 .57-5.72 mm and .86-5.39 mm for the horizontal and vertical locations, respectively.

1 **Figure captions**

2 **Figure 1.** Mean displacement in the primary (y-axis) and perpendicular (x-axis) directions of the
3 movement. Symbols within the legend indicate the separate moving background conditions.

1 **Figures**



2

3

Figure 1.

1 **Tables**

2 **Table 1.** Mean displacement (\pm SE) in the primary direction of the movement as a function of
 3 moving background and kinematic landmark.

	Stationary	Up	Down	Right	Left
PA	10.70 (.57)	10.39 (.68)	10.97 (.81)	9.83 (.66)	10.70 (.69)
PV	63.49 (1.40)	65.57 (1.51)	64.05 (1.43)	64.87 (1.92)	63.90 (1.46)
PD	132.00 (2.74)	136.44 (3.48)	124.63 (3.06)	132.70 (4.20)	128.52 (3.77)
END	156.99 (.57)	158.50 (.85)	154.62 (.75)	158.07 (.49)	156.56 (.42)

4

5 **Table 2.** Mean displacement (\pm SE) in the perpendicular direction of the movement as a function
 6 of moving background and kinematic landmark.

	Stationary	Up	Down	Right	Left
PA	1.75 (.65)	1.73 (.84)	1.40 (.54)	1.72 (.64)	1.87 (.72)
PV	7.67 (1.62)	6.98 (1.97)	6.60 (1.69)	7.76 (1.73)	7.77 (1.80)
PD	7.93 (1.17)	7.76 (1.65)	7.74 (1.32)	10.79 (1.48)	7.07 (1.70)
END	1.32 (.97)	1.49 (1.16)	1.27 (.92)	3.98 (1.36)	-0.32 (1.00)

7

1 **Table 3.** Mean absolute Z-scores (\pm SE) in the displacement of the primary/perpendicular
 2 directions for the congruent moving backgrounds across each of the kinematic landmarks. For
 3 reference, the marginal means for the incongruent moving backgrounds are also presented.

	Congruent				Incongruent
	Up	Down	Right	Left	
PA	.80 (.11)	.93 (.13)	.85 (.12)	.89 (.12)	.74 (.06)
PV	.74 (.15)	.87 (.11)	.76 (.12)	.69 (.11)	.77 (.06)
PD	.79 (.14)	1.17 (.11)	1.02 (.15)	.77 (.10)	.66 (.05)
END	.72 (.13)	1.08 (.12)	1.24 (.08)	.99 (.11)	.59 (.06)

4