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# Modeling and Machining of Integral Impeller based on NURBS Curve

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**Abstract:** NURBS curve is applied to model and machine of integral impeller to get better smooth streamline in this work. In order to get high precision surface modeling of impeller, complex surface modeling method for impeller is studied through inputting NURBS curves and surfaces obtained by MATLAB into CAXA Manufacturing Engineer, which solves the problem that cannot be designed NURBS curve and surface directly in the CAD software. Grooving and expanding groove tool paths are obtained according to the NURBS curve of top curve and root curve, and its interpolation step size and the row spacing are determined according to the curvature of the curve and interpolation period. Meanwhile, Five-axis side milling method is used to achieve the vane finish machining, and streamline processing method is adopted to realize the finish machining of the channel. All work is verified in a virtual simulation system of 5MC850-C machining center, and these simulation results show that machining accuracy error of the impeller is between -0.007 mm and 0.012 mm, meeting tolerance range of the impeller design.

**Keywords:** Five-axis linkage; Integral impeller; NURBS curve; Grooving curve; Expanding groove; Simulation verification

## 1. Introduction

Nowadays, integral impeller is widely used in energy field, defense and aerospace field, which plays an extremely important role in reducing weight, enhancing performance and improving reliability of the engine [1]. The structure of the integral impeller mainly includes hub and vanes, in which each vane consists of leading edge, trailing edge, pressure surface and suction surface. The hub and vanes profile are usually free-form surfaces, the vanes are very complex twisted with overlapped each other, and the channel is narrow [2]. Thence, the design of integral impeller must not only meet the requirements of high aerodynamics and surface accuracy, but also avoid collision and interference between the tool and the workpiece during the processing [3, 4]. Currently, the modeling and processing of integral impeller have been the research focus of domestic and foreign scholars. Non-Uniform Rational B-Spline (abbr. NURBS) can better control curvature and its variation of complex surface than the traditional grid modeling method, so it can create more realistic and vivid modeling. And ISO has used NURBS as the only mathematical method for defining

geometry of industrial products [5]. Therefore, it is of great significance to study integral impeller surface modeling and processing technology based on NURBS curves, use NURBS curves to generate impeller profiles and tool planning paths for impeller machining, and develop interpolation algorithms based on NURBS curves.

In traditional five-axis machining, a large number of small linear segments or arcs are used to represent the processing path, which increases the data processing quantity of the numerical control system and fails to realize the optimal smooth effect of the surface, and processing effect is often affected by the nonlinear error, resulting in poor machining surface quality[6,7]. In theory, non-linear errors can be eliminated using NURBS describe the tool center point and tool axis point trajectory, thus a higher and smoother feed speed can be obtained, frequent machine acceleration and deceleration can be reduced, and high-speed and high-precision machining can be achieved[8]. For five-axis CNC machining of an impeller, many studies have been performed on the tool path planning in recent years. Fan et al.[9] presented a novel five-axis rough machining tool path by mathematical analysis and comparing between free-form vane and ruled vane. Kim et al.[10] introduced a new method of machining impellers by integrating 3-axis and 5-axis machines, which can reduce significantly up to 17% of total machining time. Chen[11] put forward a method of the optimal tool orientation in a five-axis flank milling machine, claiming that the tool orientation can be ensured by a mathematical formula and CAD/CAM software Unigraphics (UG), and the tool path can be transformed into the NC code. The machined impeller surface geometry is used to verify accurately by using the 3D Coordinate Measuring instrument. Wang et al.[12] presented a method that knowledge engineering technology was introduced into the computer numerical control programming, and a standard process template was established for the processing of impeller parts. Han et al.[13] proposed a path planning method based on template path mapping for impeller channel, and the tool path calculation time is compared with the traditional equidistant offset method, resulting in 45% increase in computing efficiency.

Aiming at NURBS curve interpolation technology, Li et al.[14] introduced a third-order non-uniform rational b-spline interpolation method. This method can create a smooth transition between the hub and the blade shoulder and is implemented in an open structure computer numerical control controller. Wu et al.[15] proposed a tool preprocessing method for high-speed processing based on NURBS curve fitting technology in order to improve the processing quality while reducing the processing time. Liu et al.[16] put forward a NURBS tool path interpolation method for reducing the feed fluctuation by forming a quartic equation for the curve parameter increments. Yao et al.[17] proposed a method of eliminating non-linear errors by five-axis linkage double NURBS curve direct interpolation to control non-linear errors.

The aforementioned literatures reveal theoretical studies on the tool path planning and interpolation algorithms of integral impeller. However, few studies have applied NURBS curves to the modeling, tool path and interpolation synthetically, whereby the mathematical analysis should be carried out and calculation method must be proposed. There are two problems that must be addressed in this methodology: modeling, tool path planning and interpolation method of impeller based on NURBS curve surface, and the machining parameters of interpolation step and interpolation period that should be considered based on NUBRS tool path.

The objective of our work is to resolve the two above-mentioned issues in a scientific way. Firstly, impeller model is generated using NURBS curves and surfaces, tool paths are got based on the NURBS model of the impeller, and machining processing is realized by NURBS interpolation method. Secondly, rough machining method for separating grooving and expanding groove is presented to reduce and release residual stress and elastic potential energy better. Thirdly, a five-axis machining center virtual simulation system is established, and the design model, blank model and tool path file of impeller are imported into it for numerical control machining simulation verification. The results show that our work is feasible and the machining error was between  $-0.007mm$  and  $0.012mm$ , which can meet the design requirements.

## 2. Modeling and machining of NURBS curve and surface

NURBS curve has the advantages of excellent local shape control force and geometric non-deformation, and is significantly convenient for engineering application. Therefore, NURBS curve and surface are used to realize the modeling vanes profile and hub surface, and NURBS curve interpolation is adopted to machine the channels and the vanes of the integral impeller.

### 2.1 Modeling of vane profile and hub surface

As mentioned earlier, the integral impeller is composed of the hub and the vanes, in which the vane top line and vane root line are given in the form of list points. The equations of vane top line and vane root line based on NURBS curve  $C(u)$  can be expressed as follows[18-20].

$$C(u) = \frac{\sum_{i=0}^n W_i N_{i,k}(u) P_i}{\sum_{i=0}^n W_i N_{i,k}(u)} \quad (1)$$

where  $n$  is the number of list points;  $k$  is the number of times of the NURBS curve, here  $k=3$ ;  $W_i$  ( $i=0,1,2,\dots,n$ ) is the weight factor of the  $i$ th control point  $P_i$ , here  $W_i > 1$ ;  $P_i$  is the  $i$ th 3D control vertex.  $N_{i,k}(u)$  is the  $i$ th B-spline basis function, which is defined as follows.

$$N_{i,0}(u) = \begin{cases} 1 & u \in [u_i, u_{i+1}) \\ 0 & other \end{cases}$$

$$N_{i,k}(u) = \frac{u - u_i}{u_{i+k} - u_i} N_{i,k-1}(u) + \frac{u_{i+k+1} - u}{u_{i+k+1} - u_{i+1}} N_{i+1,k-1}(u)$$

$$\frac{0}{0} = 0 \quad \text{regulations}$$

The vane profile uniformly distributed on the impeller hub is a non-developable ruled surface, which is produced by a rule line along two leading lines according to the equal parameter method, here the two leading lines are the vane top line and the vane root line on the same side of the vane. The hub surface is a rotating surface formed by a vane root line around the impeller axis. Therefore, the vane profile and the hub can be expressed as[21, 22]:

$$S(s, t) = \frac{\sum_{i=0}^m \sum_{j=0}^n N_{i,3}(s) N_{j,3}(t) w_{ij} G_{ij}}{\sum_{i=0}^m \sum_{j=0}^n N_{i,3}(s) N_{j,3}(t) w_{ij}} \quad (2)$$

where  $S(s, t)$  is the position vector of any point on NURBS surface,  $N_{i,3}(s)$  and  $N_{j,3}(t)$  are cubic b-spline basis functions along  $s$  and  $t$  directions, respectively,  $w_{ij}$  is the weight factor,  $G_{ij}$  is the control point.

NURBS surface is a segmented surface, which only local description information is involved in any of the surface slices. Therefore, the following expressions of NURBS surface slices in matrix form can be obtained by appropriate transformation of equation (2).

$$\begin{aligned} x(u, v) &= UM_u G_x M_v^T V^T / UM_u WM_v^T V^T \\ y(u, v) &= UM_u G_y M_v^T V^T / UM_u WM_v^T V^T \\ z(u, v) &= UM_u G_z M_v^T V^T / UM_u WM_v^T V^T \end{aligned} \quad (3)$$

where  $x(u, v)$ ,  $y(u, v)$  and  $z(u, v)$  are  $x$ ,  $y$  and  $z$  coordinates of any point  $S(u, v)$  on the surface,  $u$  and  $v$  are the transformed variables,  $U = [u^3 \ u^2 \ u]$ ,  $V = [v^3 \ v^2 \ v \ 1]$ .  $M_u$  and  $M_v$  are the node coefficient matrices of the surface slice, which are determined by the node vectors of  $u$ -direction and  $v$ -direction, respectively.  $W$  is the weight factor matrix of the surface slice.  $G_x$ ,  $G_y$  and  $G_z$  are the geometric coefficient matrix of the surface slice.

## 2.2 NC Machining of Impeller based on NURBS Curve

Conventional NC machining method of the free-form surface is to generate the tool position file describing tool path by off-line programming according to the geometric information of the surface and the machining process information. The NC program of the part is obtained through the post-processing, and after simulation verification the NC program is input NC machine tool for machining. This process mainly depends on the programmer, which not only has a large amount of programming workload and subjective factors but also has more redundant procedures and consumes more software and hardware resources. At the same time, because of the separation of tool path planning and trajectory generation, it is difficult to realize 3D real-time and accurate tool compensation, which causes machining and programming to be carried out alternately multiple times, and seriously affects NC machining efficiency and surface machining accuracy.

NURBS surface modeling and interpolation method of impeller model-based definition is proposed in our work, it consists of channel grooving, expanding groove tool path generation and direct interpolation based on NURBS curve modeling technology, calculate maximum tool radius according to curvature of curve, and design NUBRS curve interpolator to realize the machining of integral impeller. The flowchart of the method is shown in figure 1.

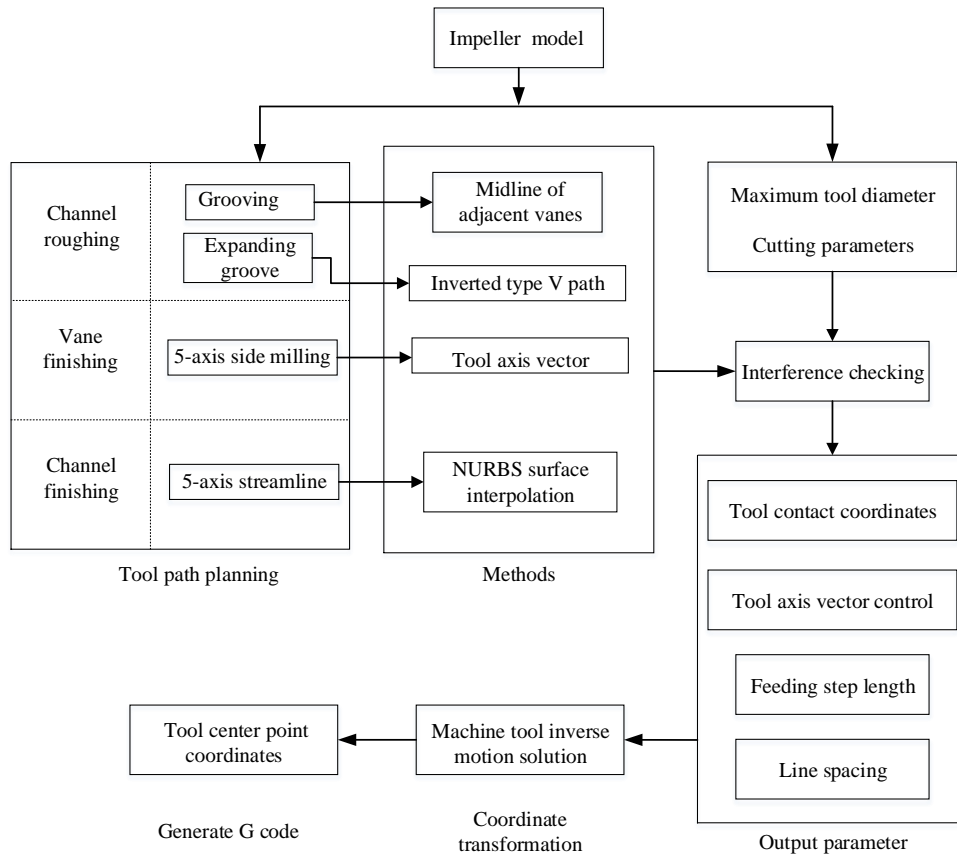


Fig. 1 Machining process of integral impeller

Because the integral impeller is forged, there is not only a large amount of machining allowance to be removed, but also residual stress and elastic potential energy need to be released before and during machining, so the machining technology of the integral impeller is particularly important to the machining accuracy and efficiency of the impeller. In order to remove the residual stress and elastic potential energy in the impeller blank at the earliest of process, rough machining process is proposed, in which the channel is grooved first, and then the groove is enlarged. Grooving line and expanding groove line are both NURBS curves, which are generated according to the NURBS curve of the vane profile. Five-axis side milling method is adopted for the finish machining of the vane profiles, and the non-developable ruled surface on both sides of vanes profile is realized by controlling the direction of the tool axis. Finish machining of the channel is implemented using a five-axis streamline processing mode, milling from the inlet to the outlet of the channel.

### 3 Planning of NC machining tool path

#### 3.1 Tool path planning of the channel rough machining

A uniform stratification processing strategy is adopted in the rough machining of channels. Tool path for each layer cutting is connected in a proper way, forming the whole machining tool path of the channel. Cross-section of channel is an approximate trapezoid with a narrower inlet and a wider outlet, thus, the inverted V-type tool path is used. First a through groove is processed in the middle of a channel, then inverted V-shaped expanding groove tool paths are planned on the two sides. The tool path of each layer is basically the same.

### 3.1.1 Grooving process of channel

Main purpose of grooving is to open the channel, release the forging stress and potential energy in the process of machining, and prepare for the subsequent machining such as expanding groove. This work is finished using flat end milling tool, grooving position is selected in the middle position of channel, and milling direction from inlet to outlet of impeller. Grooving machining includes determination of grooving line, calculation of feed step size and selection of diameter of milling tool.

Figure 2 shows a grooving tool path of one of the layer cuttings.  $E_1$  and  $E_2$  are two boundary-lines of channel rough machining, and are obtained by offsetting a distance away from designed vane curve  $V_1$  and  $V_2$ , the distance is the allowance for finish  $\eta$  respectively.  $OB$  is a grooving path located in the middle position of  $E_1$  and  $E_2$ , which can be expressed in formula (4).

$$C_{BO}(u) = \frac{\sum_{i=0}^n W_i N_{i,k}(u) P_{BO,i}}{\sum_{i=0}^n W_i N_{i,k}(u)} \quad (4)$$

where  $P_{BO,i}$  can be obtained by control point and data point  $p_{BO,i}$  relationship (15). Thus,  $p_{BO,i}$  data point is figured out [23, 24].

$$p_{BO,i} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} p_{V_1,i}$$

Where  $p_{V_1,i}$  is data points on  $V_1$ .  $\theta$  approximately equal to  $360/2n$ .  $n$  is the number of vanes.

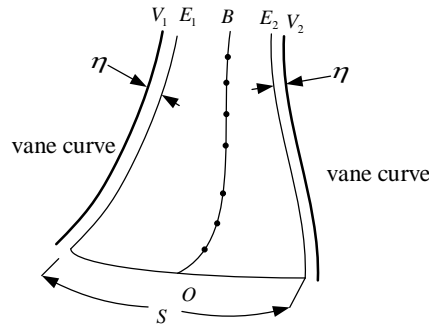


Fig. 2 Determination of grooving path

Feed step size is calculated to control moving distance of tool relative to workpiece in an interpolation period. Planned grooving tool path is located on machined surface with a time-independent geometric path, which is described into a series of tool contacts point according to machining accuracy, and machining of the whole tool path is completed by controlling tool movement from the  $j$ th tool contact point to the  $j+1$ th tool contact point in an interpolation cycle[25, 26].

Curvature of the machined curve  $P_i$  at the tool contact point  $C_{ij}$  can be expressed as[27]:

$$k_{ij} = \frac{\sum S'_w \times S''_{ww} \sum_{w=wj}}{\sum S'_w \sum_{w=wj}^3} \quad (5)$$

In formula (5)

$$\begin{aligned} S'_w &= S'_u U'_w + S'_v V'_w \\ S''_{ww} &= (S''_{uu} U'_w + S''_{uv} V'_w) U'_w + S''_u U''_{ww} + (S''_{vu} U'_w + S''_{vv} V'_w) V'_w + S''_v V''_{ww} \end{aligned}$$

Step size can be approximately as

$$\Delta l = 2 \left[ \left( \frac{1}{k_{ij}} \right)^2 - \left( \frac{1}{k_{ij}} - \varepsilon \right)^2 \right]^{0.5} \quad (6)$$

Corresponding reference  $W_{j+1}$  is

$$W_{j+1} = W_j + \frac{\Delta l}{\sum S'_w \sum_{w=wj}} \quad (7)$$

Large diameter flat end milling tools are used as far as possible in channel groove machining to improve efficiency, but it must be less than the shortest distance  $L_{min}$ , which is between the two adjacent vanes surfaces,  $L_{min}$  can be approximated by formula (8).

$$L_{min} \approx \min_{i, k, n} \left( \frac{2\pi R_k - Nm_k}{2N} \right) \quad (8)$$

where  $n$  is the number of data points of the vane root,  $R_k$  is the radius of impeller at  $k$  data point,  $m_k$  is the thickness of vane at  $k$  data point, and  $N$  is the number of vanes.

### 3.1.2 Expanding groove process of channel

Inverted V-shaped expanding groove tool paths are designed along two sides of grooving path, tool paths are shown in figure 3,  $A_i$  to  $C_i$  ( $i=1, \dots, n$ ) are expanding groove lines, and  $B_j$  ( $j=1, 2, \dots, m$ ) is intersection points of  $A_i$  to  $C_i$ . Points on the  $A_i$ ,  $B_j$  and  $C_i$  are the discrete points obtained by formula (7). The expanding groove tool path follows the order of  $A_i \rightarrow B_j \rightarrow C_i$ . The number of expanding groove lines is  $n_r$ :

$$n_r = \frac{S}{\sqrt{2R \times h}} \quad (9)$$

where  $S$  is arc length between boundary lines of channel rough machining in the side of outlet,  $R$  is tool radius, and  $h$  is the allowed limit of thickness residue in the depth direction of hub surface in outlet side.



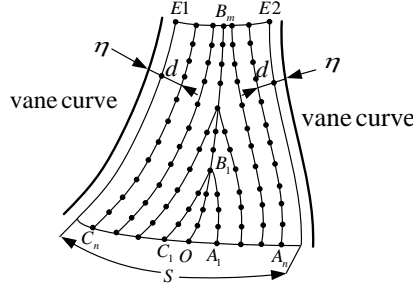


Fig. 3 Tool path of expanding groove

### 3.2 Tool path planning of vane finish machining

After rough machining of channel, there are some tool marks on vane profile and machining allowance is not uniform as well. Therefore, vane finish machining is carried out using five-axis side milling method, and its control points are tool location points.

Figure 4 shows one side of vane profile, where  $d_1$  is finish machining curve of vane top,  $d_2$  is finish machining curve of vane root. Point sets  $P_u$  and  $P_d$  are the discrete points of  $d_1$  and  $d_2$ , respectively, which are obtained by equal-parameter method. The connection curves of  $P_u$  and  $P_d$  are the generatrix of vane surface. The unit vector  $U_s$  along a generation line can be derived using equation (10).

$$U_s = \frac{P_u - P_d}{\|P_u - P_d\|} \quad (10)$$

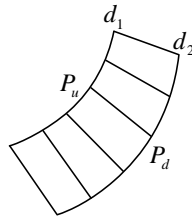


Fig. 4 Generatrix of vane finish machining surface

Tool location points are the coordinates of  $C_d$  point, which is obtained by offsetting a tool radius  $R$  along the normal direction of the  $P_d$  point as shown in Figure 5. Similarly, the coordinates of  $C_u$  point can be calculated as well.

$$\begin{aligned} C_d &= P_d \pm R \cdot N_d \\ C_u &= P_u \pm R \cdot N_u \end{aligned} \quad (11)$$

where  $N_d$  and  $N_u$  are the unit vectors along the normal directions of  $P_d$  and  $P_u$ , respectively.

Cutter axes vector is computed as follows:

$$T_t = \frac{C_u - C_d}{\|C_u - C_d\|} \quad (12)$$

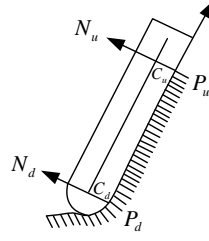


Fig.5 Cutter location and axis

### 3.3 Tool path planning of channel finish machining

Channel finish machining is carried out to improve machining precision and surface smoothness. Tool path is planned as one-way milling from inlet to outlet. Finish machining surface is described as a series of points according to the  $UV$  parameters orientation as shown in Figure 6. The tool path number  $n_f$  can be obtained using the equation (9). Cutter contact point  $O_{u,v}$  is calculated using equation (13):

$$O_{U,V} = O_{1,i} + \frac{O_{2,i} - O_{1,i}}{n_f} \cdot j \quad (13)$$

where  $j$  is the number of the cutting groove,  $j=0, 1, 2, \dots, n_f$ . The control method of the tool axis is the same as the channel rough machining.

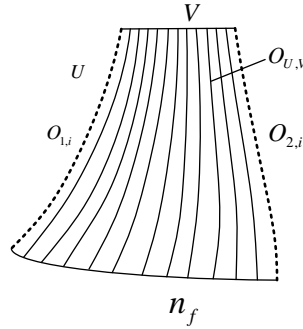


Fig. 6 Finish machining tool path

## 4. Case studies

A case is conducted for modeling and machining of integral impeller with eight vanes and eight channels surfaces. The top and root curve data point coordinates of vane pressure surface and suction surface of the integral impeller are listed in table 1 and table 2, respectively. The geometrical sizes of the impeller are summarized as follows: the impeller height is  $75mm$ , and the vane height  $56mm$  with its superior margin height  $17mm$ .

Table 1. Data point coordinates of vane top curve

Number	Pressure surface (mm)			Suction surface (mm)		
	x	y	z	x	y	z

1	15.0578	-38.5221	-0.0000	17.0533	-37.6813	-0.0000
2	9.7506	-40.4552	-3.9523	11.8545	-39.8895	-3.9523
3	4.9017	-41.9681	-8.5921	7.0914	-41.6541	-8.5921
4	0.0000	-43.9576	-13.7361	3.1003	-43.8554	-13.7361
5	-2.3747	-47.3994	-18.7416	0.1093	-47.4587	-18.7416
6	-4.8445	-52.5897	-22.4812	-2.0856	-52.7712	-22.4812
7	-7.3561	-58.6341	-24.5000	-4.2774	-58.9387	-24.5000

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**Table 2.** Data point coordinates of vane root curve

Number	Pressure surface (mm)			Suction surface (mm)		
	x	y	z	x	y	z
1	5.8562	-15.8937	-10.0000	8.5272	-14.6354	-10.0000
2	2.0282	-20.1342	-17.1110	5.2380	-19.5435	-17.0893
3	-0.6451	-25.5343	-23.7352	2.7895	-25.3057	-23.6533
4	-2.3108	-32.8384	-28.6366	1.1626	-32.7485	-28.5652
5	-3.5795	-41.2836	-31.3550	-0.2986	-41.2614	-31.3441
6	-5.1602	-50.0458	-32.4837	-1.6591	-50.1741	-32.4780
7	-8.0303	-58.5456	-32.5000	-3.9268	-58.9631	-32.5000

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#### 4.1 Modeling of integral impeller

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In order to use formula (1) to generate NURBS curves of vane top and vane root, the corresponding curve control points must be obtained using their data points. First of all, a parameter value  $\hat{u}_k$  is assigned to each data point  $p_i$ , and the corresponding parameter value of the first point and the end point is specified to be 0 and 1. Then the remaining parameter values  $\hat{u}_k$  are calculated one by one by the modified chord length parameter method:

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$$\hat{u}_k = \hat{u}_{k-1} + \frac{\|p_k - p_{k-1}\|}{\sum_{i=1}^m \|p_i - p_{i-1}\|} \quad k = 1, 2, \dots, m-1 \quad (14)$$

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The most important part of curve fitting is inverse calculation of control points. Select the node vector  $U = \{u_0, u_1, \dots, u_r\}$ , where  $r = n + p + 1$ , thus  $(m + 1) \times (m + 1)$  linear equations can be got.

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$$p_k = c(\hat{u}_k) = \sum_{i=0}^m N_{i,p}(\hat{u}_k) P_i \quad (k = 0, 1, \dots, m) \quad (15)$$

In the above formula, there are  $(m + 1)$  unknown control point  $P_i$ . Because coefficient matrix of this equation system has the characteristics of strictly diagonal dominance, a chase method is used to quickly solve the equation system to obtain control point data. Formula (15) can be solved when node vector  $U$  is known, the node vector  $U$  is solved as follows:

$$\begin{aligned}
 u_{j+p} &= \frac{1}{p} \sum_{i=j}^{j+p-1} \hat{u}_i (j=1, 2, \dots, n-p) \\
 u_0 &= u_1 = \dots = u_p = 0 \\
 u_{r-p} &= u_{r-p+1} = \dots = u_r = 1
 \end{aligned} \tag{16}$$

Take  $p = 3$ ,  $m = 7$ , and use data in table 1-2 to obtain control point data of corresponding data points through above calculation process. The four curves in Figure 7 are obtained by the cubic NURBS curve in MATLAB.

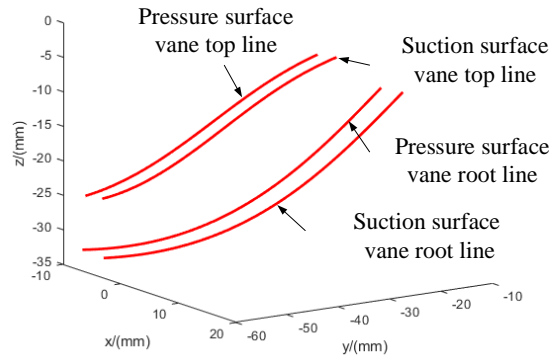


Fig. 7 Vane root and top NURBS curves

Vane surface is non-developable ruled surface, which is generated according to the equal parameter method by a rule line along two basic lines of a vane root line and a top line, so the scanning method is used, the parametric equation of vane ruled surface can be expressed by (17). The resulting vane surface is shown in figure 8.

$$S(u, v) = (1 - v)p(u) + vq(u) \tag{17}$$

where  $v$  is a parameter along the direction of rule line,  $u$  is a parameter along the direction of the basic line,  $S(u, v)$  is the ruled surface surrounded by  $u$  and  $v$ ,  $p(u)$  is vane top line,  $q(u)$  is vane root line.

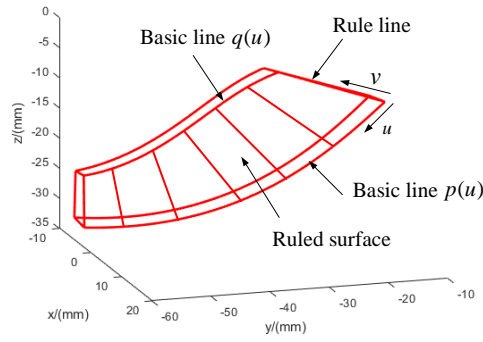


Fig.8 Non-developable ruled surface of Vane

Given the number of vanes is 8, the matrix is rotated according to the following spatial coordinates[28] to obtain the vanes array (see figure 9).

$$\begin{bmatrix} x_{rot} \\ y_{rot} \\ z_{rot} \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad (18)$$

where  $\theta$  is 45 degree.

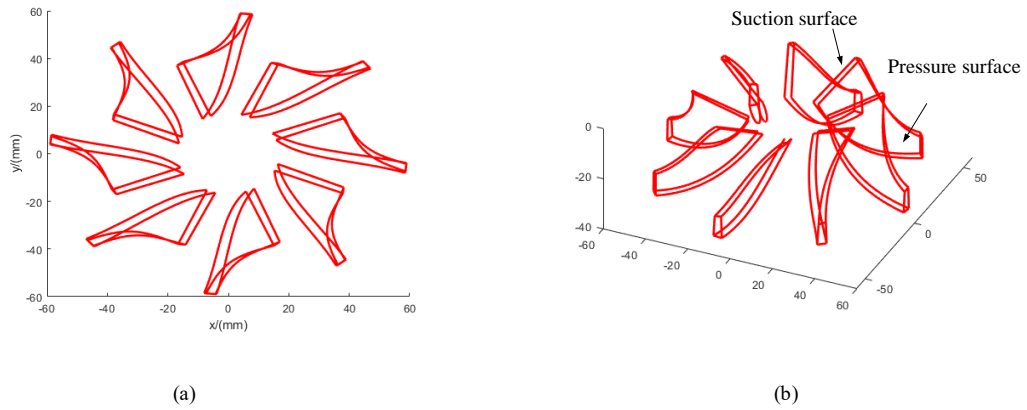


Fig. 9 Vanes generation: (a) Top view (b) Front view.

The scanning surface of the hub can be obtained by selecting a root curve to rotate 360 degrees around the Z axis, as shown in figure 10.

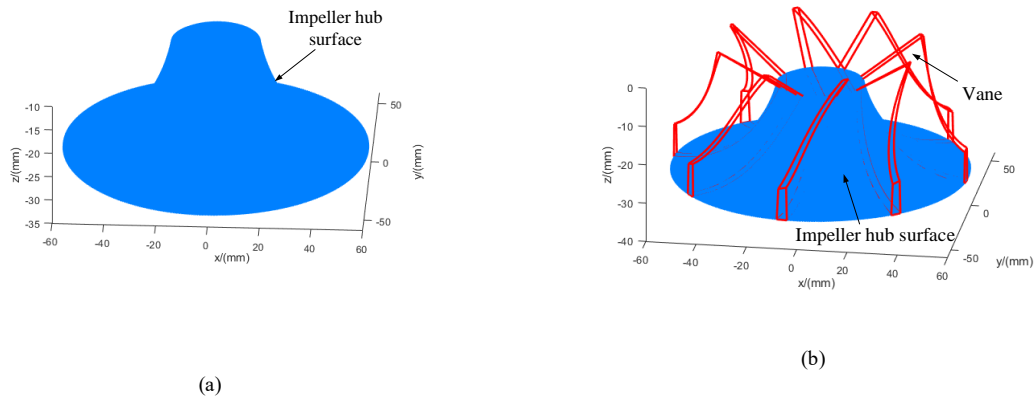


Fig. 10 Hub surface (a) Without vanes (b) With vanes

The data generated from MATLAB was imported into CAXA Manufacturing Engineer, and the resulting solid model is shown in figure 11.

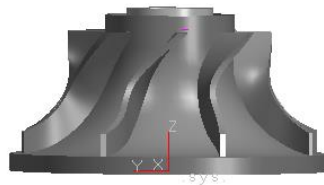


Fig.11 Integral impeller model

## 4.2 Machining of integral impeller

Machining of integral impeller is performed using the aforementioned tool path and processing parameters, including tool selection, parameter setting and implementation of tool path.

### 4.2.1 Selection of tools

In the case, flat end tools are used for grooving and expanding groove, and ball end tools are used for vane finish and channel finish. The tool material is made of kentanum. The tool diameters of the rough and finish machining are 10mm and 6mm, respectively.

### 4.2.2 Generation of Tool paths

The tool path for channel rough machining was first generated. On the base of impeller size and tool parameters, number of rough machining lines was calculated using equation (9) was  $n_r=11$ . One of them is a groove line, and the other 10 are expanding groove lines. The inverted V-type tool paths generated for rough machining of integral impeller channel were shown in Figure 12. Tool contact points and tool paths are shown in Figure 12 (a) and Figure 12 (b), respectively.



Fig.12 Generated tool path for channel roughing: (a) Tool contact points; (b) Tool paths.

The tool path for vane finish machining using the five-axis side milling machining method was generated. Vane allowance for finish machining was set at  $0.2mm$ , and channel allowance for finish machining was set at  $0.5mm$ . The maximum step size was set at  $1mm$ . The cut-in and cut-out length was set at  $15mm$  to avoid interference. The path was from top to bottom. The generated tool paths are shown in Figure 13. Tool location points and tool paths are shown in Figure 13 (a) and Figure 13 (b), respectively.



Fig.13 Generated tool paths for vane finishing. (a) Tool location points; (b) Tool path.

According to the working conditions of the integral impeller, a set of streamlined tool path was adopted for finish machining of channel, which was milled from inlet to outlet of impeller with the vane side surface as limiting face and the hub surface as the face to be processed. To ensure machining precision, number of tool lines  $n_f$  is determined at 51 based on arc length  $S$  at the outlet of channel and formula (13). According to the step size formula (7), the calculated maximum step size is  $0.3mm$ . The generated tool paths of channel finish machining were shown in Figure 14.

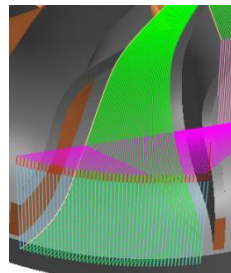


Fig.14 Generated tool paths for channel finishing

## 5 VERICUT-based simulation verification

VERICUT is a software for simulating CNC machining, which can display machining process dynamically. In addition to realizing accurate mapping of real CNC machine tools, the structure and functions of virtual CNC machine tools can be modified and improved for research requirement, even some new functions could be added.

### 5.1 Simulation system of machine tool

A simulation system of machine tool consists two parts of mechanical subsystem model and control subsystem model. 5MC850-C vertical machining center is a double turntable five-axis machining center, and there are NURBS curve interpolation functions in control subsystem. The maximum strokes of machine tool of X, Y, Z axis are 800mm, 500mm and 700mm, respectively. Rotation angles of A and C axis are  $-100^{\circ} \sim 100^{\circ}$  and  $-180^{\circ} \sim 180^{\circ}$ , respectively, and the range of spindle speed is 100~18000r/min. A virtual simulation system is established according to geometric dimensions and dependence relationships of 5MC850-C machine center, as shown in Figure 15.

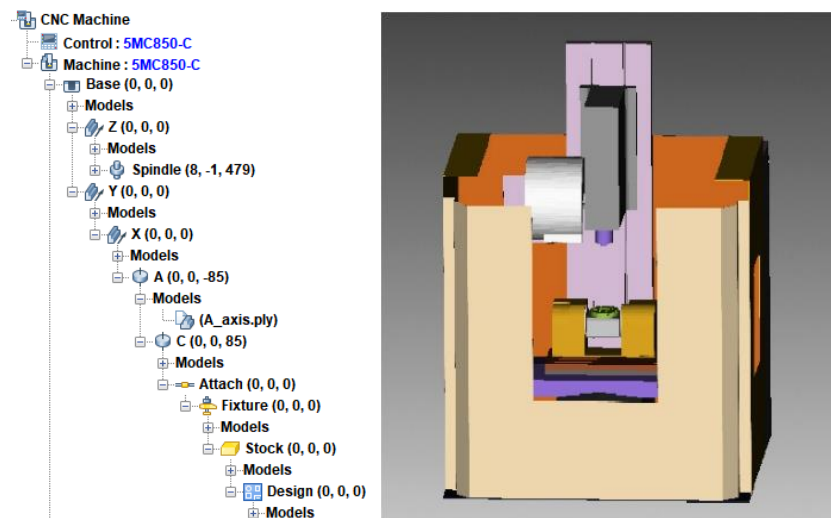
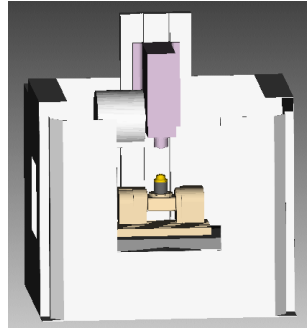


Fig.15 Simulation of machine center 5MC850-C

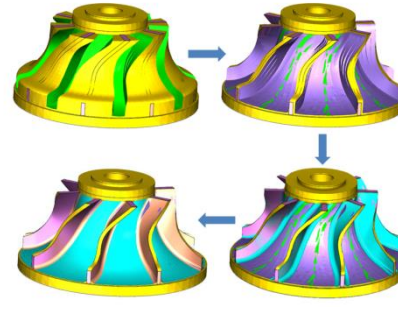
### 5.2 Machining simulation

The tool paths based on NURBS technology of the integral impeller are simulated in a virtual simulation system of 5MC850-C machining center to verify our study. Fig.16 (a) is a simulation processing screenshot, and Fig.16 (b) is a simulation screenshot of channel grooving—channel expanding groove—vane finishing—channel finishing.





(a)



(b)

**Fig.16** Simulated machining tool and simulation process. (a) Simulation machining; (b). Effect of the simulation machining.

After many times of human-computer interaction simulation, and the NC program verified by simulation is obtained. Table 3 shows some simulation parameters obtained from VERICUT after the integral impeller was simulated machined in virtual simulation system using the correct NC program. It can be calculated from the table, that the total time of integral impeller was 6 hours 38 minutes and 16 seconds, the non-machining time was 3 hours 26 minutes and 30 seconds, the total machining path length was 37.9 meters.

**Table 3** Simulation parameters

	Spindle speed (r/min)	Average feed rate (mm/min)	Total time (h:m:s)	Empty travel time (h:m:s)	Effective cutting time (h:m:s)	Distance (mm)
Channel grooving	4500	150	0:30:38	0:20:27	0:10:11	1600
Expanding groove	5000	200	1:28:31	0:40:24	0:48:07	13500
Vane finish	8000	250	1:00:28	0:40:15	0:20:13	4500
Channel finish	8000	250	3:38:39	1:55:24	1:43:15	18300

### 5.3 Result analysis

To verify feasibility of research method, dimensional accuracy of the machined impeller is checked by comparing simulation model with design model. Fig. 17 (a) shows the error distribution of the machined impeller surface, where it can be seen that there are gouge and excess at local locations, and the system indicates that there are 8 gouge points and 493 excess points on the simulated part model. Among them, gouge all occurs at the maximum variation of curvature of vane pressure surface, which main reason is that feed speed is higher when finishing machining vanes, and when the feed direction changes suddenly, the tool axis wobbles. Table 4 shows error values and coordinates of 8 gouge points, and the maximum error of  $0.0067mm$  is shown in Fig. 17 (b). Excess points are mainly distributed in the channel outlet end and the vane root shown in Fig. 17 (c). Because the channel is narrow at the inlet and wide at the outlet, when the channel is streamlined, the residual height between the tools causes excess at the channel outlet. The excess at the vane root appears mainly due to the influence of the tool radius. The range of gouge and excess values obtained from the VERICUT is shown in Fig. (d), where the excess range was  $0\sim0.012$  mm, and the gouge

range was 0~0.007mm, which proves the NC program is correct and can meet the tolerance range of the impeller design.

**Table 4** Machining errors and coordinates of gouge points

Number	Machining error(mm)	coordinates	Number	Machining error(mm)	coordinates
1	-0.0062	(-35.7723, 22.0651, -6.0591)	5	-0.0057	(35.3011, -22.4510, -6.0780)
2	-0.0055	(-40.4927, -10.5101, -5.9223)	6	-0.0061	(40.6245, -10.9631, -5.9037)
3	-0.0057	(-22.0673, -35.7725, -6.0109)	7	-0.0067	(21.0376, 36.9257, -5.9016)
4	-0.0058	(9.9652, -40.7563, -5.9063)	8	-0.0055	(-9.4253, 41.0213, -6.0452)

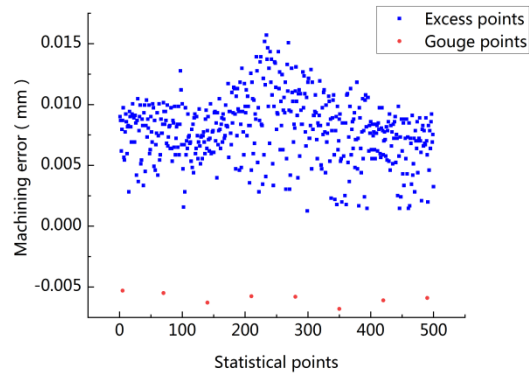
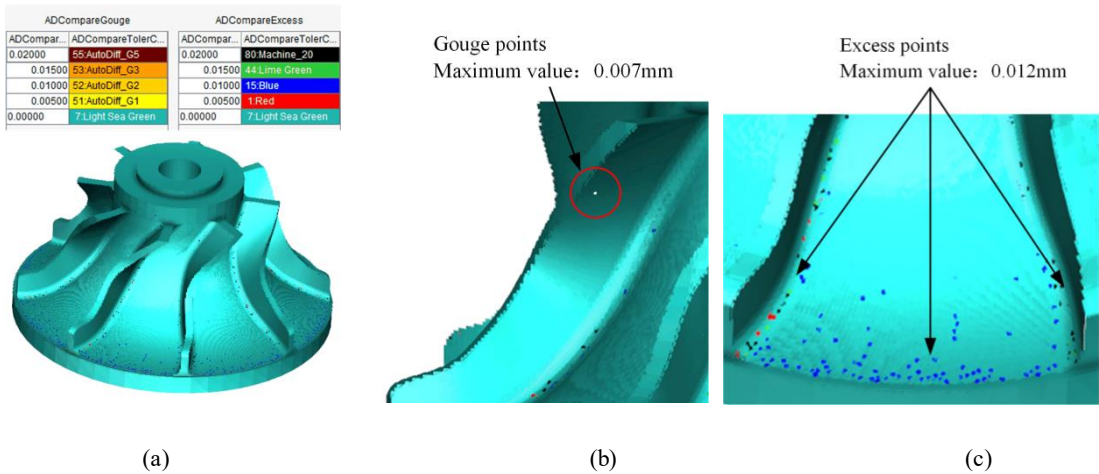


Fig. 17 Error distribution and error range. (a) The machining error distribution in impeller surface. (b) Maximum gouge point. (c) Excess points distribution in flow outlet and vane root. (d) Range of gouge and excess values

## 6. Conclusions

NURBS curve is gradually becoming the only data standard of CAD/CAM. It is of great significance to study the complex surface modeling and machining method based on NURBS unified curve model.

(1) The impeller surface modeling based on NURBS curves is realized by using MATLAB and CAXA Manufacturing Engineer software, which effectively solves the problem that NURBS curves and surfaces can not be directly designed in 3D CAD software.

(2) Flat end milling tools are used for rough machining of impeller, and grooving and expanding groove are separated in channel rough machining, which not only boosts the processing efficiency but also is more conducive to the release of residual stress and elastic potential energy of the blank, thus ensuring the processing quality.

(3) The tool path of grooving and expanding groove is the NURBS curve too, and interpolation step is determined jointly by the curvature of the curve and the interpolation cycle. Impeller modeling, tool path and interpolation are all based on NURBS technology, which can better achieve the unified model of design and manufacture.

(4) The verification of NC program and precision check based on simulation technology can not only greatly reduce the trial cutting time of NC machine tools, but also verify the innovative design method without actual machining equipment. And improve collaborative design ability.

At present, our work is only to study modeling and CNC machining technology of integral impeller based on NURBS curves and surfaces, and obtained NC program is verified in the virtual simulation system. Although our research work is all based on virtual environment and off-line, this is enough to prove our research results are executable from one aspect. Of course, how to apply the research conclusions to actual manufacturing is more important, it will be our next research work.

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