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The Auriga Project: the properties and formation mechanisms of disc galaxies across cosmic time

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ABSTRACT

We introduce a suite of 30 cosmological magneto-hydrodynamical zoom simulations of the formation of galaxies in isolated Milky Way mass dark haloes. These were carried out with the moving mesh code AREPO, together with a comprehensive model for galaxy formation physics, including active galactic nuclei (AGN) feedback and magnetic fields, which produces realistic galaxy populations in large cosmological simulations. We demonstrate that our simulations reproduce a wide range of present-day observables, in particular, two-component disc-dominated galaxies with appropriate stellar masses, sizes, rotation curves, star formation rates and metallicities. We investigate the driving mechanisms that set present-day disc sizes/scalelengths, and find that they are related to the angular momentum of halo material. We show that the largest discs are produced by quiescent mergers that inspiral into the galaxy and deposit high-angular momentum material into the pre-existing disc, simultaneously increasing the spin of dark matter and gas in the halo. More violent mergers and strong AGN feedback play roles in limiting disc size by destroying pre-existing discs and by suppressing gas accretion on to the outer disc, respectively. The most important factor that leads to compact discs, however, is simply a low angular momentum for the halo. In these cases, AGN feedback plays an important role in limiting central star formation and the formation of a massive bulge.

Key words: galaxies: evolution-galaxies: kinematics and dynamics-galaxies: spiral-galaxies: structure.

1 INTRODUCTION

Much recent effort has been devoted to simulating the formation and evolution of disc galaxies like the Milky Way and M31 in their full cosmological context. For simulations in which baryonic physics is neglected (collisionless dark matter-only, DMO, simulations), the formation of haloes like that of the Milky Way has been studied in exquisite resolution using the 'zoom-in' technique (e.g. the Via Lactea and Aquarius simulations; see Diemand, Kuhlen & Madau 2007; Springel et al. 2008, respectively). However, it has proven exceedingly difficult to achieve comparably robust results for simulations that aim to follow detailed baryonic physics and build a comprehensive galaxy formation model. Early attempts suffered from the so-called overcooling problem, in which gas cooled

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too rapidly and flowed to the central regions of the galaxy (e.g. Katz & Gunn 1991). Owing to the high densities, the gas elements achieved numerical prescriptions for star formation, then transformed much of the gas mass into star particles in a short amount of time and resulted in very compact, bulge-dominated galaxies (e.g. Navarro & Steinmetz 2000) with too many stars with respect to their total mass (Guo et al. 2010).

Since this time, many studies have reported well-formed disc galaxies that match a number of key observables such as rotation curves and abundance matching predictions (e.g. Okamoto et al. 2005; Brooks et al. 2011; Guedes et al. 2011; Aumer et al. 2013; Stinson et al. 2013b; Marinacci, Pakmor & Springel 2014a; Wang et al. 2015). In large part, this success can be attributed to the modelling of stellar feedback, for example, by injecting energy released from supernovae (SNe) explosions into surrounding gas. The energy injected from SN may be either thermal (e.g. Kawata & Gibson 2003; Stinson et al. 2006; Scannapieco et al. 2008; Keller

et al. 2014), in which the temperature of surrounding gas cells is raised, or kinetic (e.g. Navarro & White 1994; Kawata 2001; Springel & Hernquist 2003; Oppenheimer & Davé 2006; Dalla Vecchia & Schaye 2008), in which gas elements are 'kicked' with some velocity given by the SN energy. In the former, many studies have found thermally heated gas quickly radiates and becomes dense once more (Katz 1992). Attempts to mitigate this effect include turning off cooling for a period after the energy injection (e.g. Pearce et al. 1999; Stinson et al. 2006, 2013b) and directly dumping the thermal energy into a single gas cell, thus allowing the dynamical effects to propagate forward into the Euler equations via the pressure while maintaining a high gas temperature for longer (e.g. Kawata & Gibson 2003; Dalla Vecchia & Schaye 2012). For the case in which energy is injected at least partially in the form of kinetic energy, excessive dissipation is less of a problem because it cannot be radiated away until it thermalizes. The adoption of any of these schemes ultimately removes low-angular momentum gas from the central regions of the galaxy (Governato et al. 2010; Brook et al. 2011) and prevents the overcooling of gas and the growth of massive stellar bulges. Currently, SN feedback is being studied further: in particular, their placement and ability to drive winds have been studied in stratified box simulations of the interstellar medium (ISM; e.g. Creasey, Theuns & Bower 2013; Walch & Naab 2015; Simpson et al. 2016; Sur, Scannapieco & Ostriker 2016).

In addition to stellar feedback, there are a variety of other forms of feedback that have been studied, including cosmic rays (e.g. Pakmor et al. 2016b; Pfrommer et al. 2017; Simpson et al. 2016), radiation pressure (e.g. Hopkins, Quataert & Murray 2012), early stellar feedback (Aumer et al. 2013; Stinson et al. 2013b) and active galactic nuclei (AGN) feedback from the growth of supermassive black holes (BH) at the galaxy centre (e.g. Springel, Di Matteo & Hernquist 2005; Sijacki et al. 2007; Dubois et al. 2013; Weinberger et al. 2017). The last of these is thought to become important for galaxies of total mass above $\sim 10^{12} \,\mathrm{M_{\odot}}$ (Benson et al. 2003), but it is reasonable to expect that it plays some role in Milky Way-mass galaxies as they lie at the lower end of this mass range. However, it remains much less explored than stellar feedback. Prompt stellar feedback was introduced by Stinson et al. (2013b) and Aumer et al. (2013), and is reported to be critical in preventing the early onset of star formation and thereby avoiding the growth of a central spheroidal component into a massive bulge. Others claim that very strong radiation pressure feedback from stars is of fundamental importance and regulates star formation in a bursty fashion (e.g. Okamoto 2013; Sparre et al. 2017), although it is unclear whether radiation pressure is able to play such an important role in reality, given the porous structure of the ambient ISM around star-forming regions (Krumholz & Thompson 2013).

While many studies have highlighted feedback as an essential ingredient for the formation of realistic disc galaxies, the numerical codes employed are also an important factor. A variety of methods have been used to follow the hydrodynamics: e.g. adaptive mesh refinement codes (e.g. Teyssier 2002; Bryan et al. 2014); smoothed particle hydrodynamics (SPH) codes (used in, e.g. Scannapieco et al. 2008; Guedes et al. 2011; Stinson et al. 2013b; Sawala et al. 2015) and moving mesh codes (Marinacci et al. 2014a). Even for a given hydrodynamic scheme, the differences in the galaxy formation physics and in their implementation have led to diverse models, each reporting different 'optimal' values for the parameters that control processes such as feedback. For example, a high-density threshold for star formation is often required in high-resolution simulations (Guedes et al. 2011), and very different values for star formation efficiency have been advocated in the literature, both low

(Agertz, Teyssier & Moore 2011) and high (Sales et al. 2010). Indeed, the lack of agreement on optimal parameters between different codes is consistent with the variable outcomes of simulations reported in the Aquila comparison project (Scannapieco et al. 2012), in which results varied widely between codes even for the same initial conditions (see Few et al. 2016, for a more recent example). For many codes, this reflects lack of robustness to changes in resolution, and the necessity to re-calibrate free parameters for different resolutions. The final outcome of the simulations appears to be dependent on details of the implementation of feedback and star formation (see Okamoto et al. 2005), a sensitivity which is exacerbated by resolution changes. This is particularly true for the cases in which the effects of non-linear feedback cycles, especially those driven by AGN, affect a wide range of physical scales (e.g. Springel et al. 2005; Sijacki et al. 2007; Dubois et al. 2013; Weinberger et al. 2017).

Part of the numerical uncertainties discussed above may be accounted for by the accuracy of the method employed to follow the hydrodynamics. As an example, traditional forms of SPH suffer from the formation of spurious dense gas clumps that may then artificially sink to the centres of haloes, and are unable to resolve important mixing processes brought about by the Kelvin-Helmholtz instability. Recent modifications to the standard SPH method, such as pressure-based SPH (Read, Hayfield & Agertz 2010; Saitoh & Makino 2013) and the inclusion of artificial thermal conductivity, have improved the situation somewhat, particularly with regard to the mixing and hydrodynamical instabilities (Agertz et al. 2011; Schaller et al. 2015b). Although SPH codes, by construction, follow fluid elements in the frame of their trajectory and naturally provide high resolution in dense regions, they have difficulty in resolving the effects of shocks, and viscosity and noise effects in low-density regions can lead to artificial numerical quenching of the cooling rate in large haloes (Bauer & Springel 2012).

In this paper, we present a suite of cosmological zoom simulations of galaxy formation in isolated haloes similar in mass to that of the Milky Way with the magneto-hydrodynamical simulation code AREPO (Springel 2010), which is a quasi-Lagrangian method that solves the fluid equations on a moving mesh. We include a comprehensive galaxy formation model capable of producing realistic populations of galaxies in a cosmological context (Vogelsberger et al. 2013; Genel et al. 2014). In particular, the models for star formation and feedback processes, which include both stellar and BH feedback, are physically well motivated and do not require re-tuning of parameters between resolution levels.

We build on the study of Marinacci et al. (2014a), who introduced an earlier version of the galaxy formation model in eight zoom simulations of the Aquarius haloes (Springel et al. 2008) with AREPO. We have now implemented magnetic fields into the galaxy formation model (see Pakmor & Springel 2013; Pakmor, Marinacci & Springel 2014), which, until recently, was not possible owing to the well-known difficulties in controlling amplification and divergence errors. Their inclusion represents a major step forward in computational galaxy formation. The suite of Auriga simulations that we present in this study comprises 30 haloes at our standard resolution (level 4 resolution in the nomenclature of the Aquarius project, and equivalent to the highest resolution simulation, Aquarius C-4, presented in the convergence study of Marinacci et al. 2014a), and three haloes at level 3 resolution. In addition, we make some modifications to the stellar feedback implementation with respect to Marinacci et al. (2014a), which we outline in Section 2. This paper thus constitutes one of the largest samples of cosmological zoom simulations to date with high resolution and a state-of-the-art galaxy formation model and hydrodynamic method (see also Wang et al. 2015).

In this paper, we introduce the Auriga Project: we describe the methodology, numerical details and properties of the complete simulation suite. We note that other studies, such as Grand et al. (2016a), Monachesi et al. (2016), Grand et al. (2016b) and Gómez et al. (2017), have already made use of a subset of the simulation suite, and that forthcoming studies will focus on topics including the properties of HI gas, magnetic fields, satellites, ex situ discs and stellar and X-ray haloes. A goal of this paper is to demonstrate that we are able to successfully simulate the formation and evolution of Milky Way-sized late-type galaxies, the properties of which match a wide range of observables, and resolve the typical morphological features of late-type galaxies such as bars and spiral arms. We further demonstrate that these properties are well converged across three levels of resolution (a factor of 64 in mass and 4 in spatial resolution), without the need to recalibrate model parameters. The relatively large simulation sample allows us to make a quantitative analysis of the formation histories of the simulated galaxies. In particular, we analyse the controlling mechanisms behind disc growth. We show that a high degree of specific angular momentum in the dark matter and gas is required to build radially extended disc galaxies that grow inside-out, whereas haloes with little angular momentum evolve into more compact, but still well-defined, discs. We determine that a key mechanism in providing the angular momentum to the gas and dark matter is the quiescent accretion of massive, gas-rich subhaloes, which occurs over a wide range of lookback times and imparts significant angular momentum to all components (including pre-existing stars) leading to the largest discs in the sample. In addition, we explore how disc properties are affected by AGN feedback, the importance of which remains uncertain in L* galaxies. We demonstrate that strong AGN feedback is effective in curtailing star formation, particularly in the central disc regions, and we comment on its impact on the radial extent of the disc.

This paper is organized as follows: in Section 2, we outline the criteria of halo selection from the parent cosmological box, and we describe the simulation code and the galaxy formation model. In Section 3, we introduce the simulation suite and describe their present-day galaxy properties, including morphologies, density structure, mass distribution kinematics and size. In Section 4, we investigate the mechanisms responsible for the large variation in disc size, with particular focus on merger histories and feedback. In Section 5, we present star formation histories (SFHs) of all the haloes, and show how they shape galaxy observables such as colour, stellar age, metallicity and stellar mass. In Section 6, we present a resolution study of three of the simulated haloes across three levels of resolution. Finally, in Section 7, we discuss and summarize the impact of our findings.

2 SIMULATIONS

2.1 Overview

In this section, we describe the halo selection criteria, the generation of the initial conditions, the simulation code and the details of the galaxy formation model. The Auriga simulations¹ represent a significant improvement on the Aquarius hydrodynamic simulations presented in Marinacci et al. (2014a): Auriga comprises 30 haloes

simulated at high resolution, in comparison to the eight lower resolution Aquarius haloes. Moreover, magnetic fields are seeded and their evolution followed, and several improvements to the physics model and numerics have been made.

2.2 Halo selection

The host dark matter haloes in our set of zoomed galaxy simulations have been drawn from a parent DMO counterpart to the Eagle simulation of comoving side length 100 cMpc (L100N1504) introduced in Schaye et al. (2015) (see Appendix A for a list of halo ID numbers). This simulation is evolved from redshift 127 to the present day, using particles of fixed mass $1.15 \times 10^7 \,\mathrm{M_{\odot}}$. The linear phases for this parent simulation, and for all of the zoom simulations, are taken from the public Gaussian white noise field realization, PANPHASIA (Jenkins 2013). The adopted cosmological parameters are $\Omega_m=0.307,\,\Omega_b=0.048,\,\Omega_{\Lambda}=0.693$ and a Hubble constant of $H_0 = 100 h \,\mathrm{km \, s^{-1}} \,\mathrm{Mpc^{-1}}$, where h = 0.6777, taken from Planck Collaboration XVI (2014). Haloes were identified at redshift z = 0using 'Friends of Friends' (FOF) with the standard linking length (Davis et al. 1985). Our selection procedure made use of the position of the centre of potential of each FOF group, and the corresponding virial mass, M_{200} , defined as the mass contained inside the radius at which the mean enclosed mass volume density equals 200 times the critical density for closure. The selection criteria were a cut in halo mass of $1 < M_{200}/10^{12} M_{\odot} < 2$, and the requirement that each candidate halo be relatively 'isolated', at redshift zero.

To quantify their isolation, the 697 haloes within the chosen M_{200} range were ranked in order of their maximum value $\tau_{\rm iso, max}$ of the tidal isolation parameter $\tau_{\rm iso, i}$ with respect to the *i*th other FOF halo, where

$$\tau_{\rm iso,i} = (M_{200,i})/(M_{200}) \times (R_{200}/R_i)^3, \tag{1}$$

where M_{200} and R_{200} are the virial mass and radius of the halo of interest, and $M_{200, i}$ and R_i are the virial mass of, and distance to, the *i*th halo in the simulation, respectively (neglecting haloes with mass less than 3 per cent of that of the halo under consideration). As the virial mass of a halo is proportional to the cube of its virial radius, applying an upper limit to $\tau_{iso, max}$ is equivalent (for a given candidate halo) to requiring the distance to other haloes in the simulation to be a least certain number times their virial radii away.

The most isolated quartile (lowest quartile in $\tau_{iso, max}$) was selected to form a sample of 174 candidates for re-simulation. This sample has a range of a factor of 16 in $\tau_{iso, max}$. To be included in the sample, the centre of a target halo must be located outside of nine times the $R_{200, i}$ of any other halo that has a mass greater than 3 per cent of the target halo mass. The 30 haloes that have been re-simulated were randomly selected from the relatively isolated sample of 174 (their IDs are randomly ordered).

The initial conditions for the re-simulation follow the Zel'dovich (1970) approximation, the procedure for which is outlined in Jenkins (2010). Particles within a sphere of radius $4R_{200}$ of the halo centre at redshift zero were traced to their positions in the initial conditions, and used to identify the amoebae-shaped Lagrangian region from which the halo formed. This region was populated with particles of relatively low mass, thus sampling the target halo and its immediate environment at relatively high resolution. Particles of progressively higher mass were used at larger distances. Such particle sampling increases computational efficiency, while the correct representation of relevant external effects such as mass infall and the cosmological tidal field is maintained. It is also ensured that there are no heavy dark matter particles within R_{200} at redshift zero. Once the initial

dark matter particle distribution is set, gas is added by splitting each original dark matter particle into a dark matter particle and gas cell pair, with masses determined from the cosmological baryon mass fraction. The dark matter particle and gas cell in each pair are separated by a distance equal to half the mean inter-particle spacing, and the centre of mass and centre of mass velocity is retained.

The typical mass of a high-resolution dark matter particle is $\sim 3 \times 10^5$ M_{\odot}, and the baryonic mass resolution is $\sim 5 \times 10^4$ M_{\odot}. The comoving gravitational softening length for the star particles and high-resolution dark matter particles is set to 500 h^{-1} cpc. The physical gravitational softening length grows with the scalefactor until a maximum physical softening length of 369 pc is reached. This corresponds to z = 1, after which the softening is kept constant. The softening length of gas cells is scaled by the mean radius of the cell, which ensures that low-density gas cells are softened with higher values relative to high-density gas. The minimum comoving softening length of the gas is set to $500 h^{-1}$ cpc (minimum physical softening set to 369 pc at z = 1, as for star particles) and the maximum physical softening to 1.85 kpc. We note that the gas cell size is allowed to become less than the softening length in high-density regions, because each gas cell is designed to hold a pre-designated target mass.

The motivation for these choices of softening comes from Power et al. (2003), who performed detailed convergence studies of DMO simulations, and empirically derived optimal softening lengths for systems of given mass, size and particle number. Although the relaxation time-scale depends primarily on the mass resolution (or equivalently, the number of particles employed), the gravitational softening length enters also in the equation, albeit logarithmically, which makes the relaxation time-scale sensitive to the order of magnitude changes in softening. Power et al. (2003) found that the optimal softening length followed the scaling: $\epsilon \sim 4r_{200}\sqrt{m_p/M_{200}}$, which, for our simulations at redshift zero, corresponds to a few hundred parsecs. A softening length of an order magnitude larger or smaller than this optimal value was shown to either produce unrealistic central mass profiles or a growing significance of two-body interactions that give rise to excessive local dynamical scatter and violate the collisionless nature of the system, particularly for small progenitor haloes at high redshift.

2.3 Simulation code

The zoom re-simulations are performed with the *N*-body, magnetohydrodynamics (MHD) code AREPO (Springel 2010) that we describe briefly here. For further detailed description, we refer the reader to Springel (2010). AREPO is a moving-mesh code that follows MHD and collisionless dynamics in a cosmological context. Gravitational forces are calculated by a standard TreePM method (e.g. Springel 2005), which itself employs a fast Fourier Transform method for long range forces, and a hierarchical oct-tree algorithm (Barnes & Hut 1986) for short range forces, together with adaptive time-stepping.

To follow the MHD, AREPO utilizes a dynamic unstructured mesh constructed form a Voronoi tessellation of a set of mesh-generating points (the so-called Voronoi mesh), that allows for a finite-volume discretization of the MHD equations. The MHD equations are solved with a second-order Runge–Kutta integration scheme with high-accuracy least-squares spatial gradient estimators of primitive variables (Pakmor et al. 2016a) that improve on the estimators in the original version of AREPO (Springel 2010).

A unique feature of AREPO is that the mesh can be transformed through a mesh reconstruction at any time-step, which is not the case for standard grid-based methods. The mesh construction ensures that each cell contains a given target mass (specified to some tolerance), such that regions of high density are resolved with more cells than regions of low density. Furthermore, the mesh generating points are able to move with the fluid flow velocity, such that each cell of the newly constructed mesh moves approximately with the fluid. In this way, AREPO overcomes the Galilean non-invariance problem of standard Eulerian mesh codes and significantly reduces the advection errors that plague fixed mesh codes when applied to complex supersonic flows. The quasi-Lagrangian characteristic of the method makes it relatable to other Lagrangian methods such as SPH, although several limitations of the SPH method are eliminated, for example, there is no artificial viscosity, and the hydrodynamics of underdense regions are treated with higher accuracy.

2.4 Physics model

The ISM is described by the subgrid model first presented in Springel & Hernquist (2003), in which star-forming gas is treated as a two phase medium: a phase of cold, dense clouds embedded in a hot, ambient medium. The gas is assumed to be star-forming and thermally unstable for densities higher than a threshold density that we derive from the parameters of the two gas phases and the desired star formation time-scale to be n = 0.13 cm⁻³. The motivation for the ISM model comes from the assumption that at the onset of thermal instability, many small-scale processes that govern the mass fractions of molecular clouds and ambient gas, such as radiative cooling, thermal conduction, star formation and feedback, quickly establish a pressure equilibrium between the hot and cold phases. In this regime, the gas pressure is a function of density only. Owing to the occurrence of star formation and stellar feedback, the equilibrium temperature of the two-phase medium ought to be higher than that of a pure isothermal gas, as a result of energy injection from SNe, and is therefore governed by an effective equation of state at densities higher than the threshold density for star formation, which is 'stiffer' than an isothermal equation of state. The model therefore provides a representation of the ISM and star formation on scales below the resolution limit, which is physically motivated by and consistent with the important small-scale processes that operate in the ISM.

Once a gas cell enters the thermally unstable star-forming regime, star particles are formed stochastically according to a probability that scales exponentially with time in units of the star formation time-scale, which we set to $t_{\rm sf} = 2.2$ Gyr. The amount of gas mass converted to stellar mass depends on the mass of the gas cell selected for star formation: all mass is converted and the cell removed if the gas cell holds less than twice the target cell mass, defined as $m_{\rm target} = \bar{m}_{\rm b}$, where $\bar{m}_{\rm b} \sim 5 \times 10^4$ M_{\odot} is the mean cell mass (as quoted above). Otherwise, a mass of only $m_{\rm target}$ is converted and the cell retained with reduced mass.

We assume that each star particle represents a single stellar population (SSP), which is characterized by a given age and metallicity. The distribution of stellar masses contained in each SSP is given by a (Chabrier 2003) initial mass function (IMF), which allows the calculation of mass that leaves the main sequence at a given timestep. The mass-loss and metal return is calculated for SNII, SNIa and asymptotic giant branch (AGB) stars each time-step as the mass moving off the main sequence for each SSP. The yields used for this calculation are those reported in Karakas (2010) for AGB stars, and Portinari, Chiosi & Bressan (1998) for core collapse SN. The mass and metals are then distributed among nearby gas cells with a top-hat kernel. For a given SSP, the number of SNIa events per time-step is calculated by integrating the delay time distribution function (DTD):

$$N_{\rm Ia}(t,\,\Delta t) = \int_t^{t+\Delta t} g(t'-t_0) \mathrm{d}t',\tag{2}$$

where t_0 is the birth time of the SSP and Δt is an interval of time thereafter. The DTD takes the form

$$g(t) = \begin{cases} 0 & \text{if } t < \tau_{8M_{\bigodot}}, \\ N_0 \left(\frac{t}{\tau_{8M_{\bigodot}}}\right)^{-s} \frac{s-1}{\tau_{8M_{\bigodot}}} & \text{if } t > \tau_{8M_{\bigodot}}, \end{cases}$$
(3)

where the normalization N_0 is calculated to be $1.99N_{\rm SN}/M$ assuming the upper limit of a *Hubble* time for the DTD (as in Marinacci et al. 2014b), where the SN rate $N_{\rm SN}/M$ is taken to be $1.3 \times 10^{-3} \, {\rm SN/M_{\odot}}$ (Maoz, Mannucci & Brandt 2012). The power-law index is s = 1.12 and $\tau_{8M_{\odot}} = 40$ Myr, which corresponds to the main-sequence lifetime of a $8 \, {\rm M_{\odot}}$ star, and is the upper mass limit for SNIa. The amount of mass and metals returned from SNIa to the ISM is then calculated from SNIa yield tables (Thielemann et al. 2003; Travaglio et al. 2004) and distributed among neighbouring gas cells.

The number of SNII is calculated to be the number of stars in an SSP that lie in the mass range 8–100 M_☉. SNII events are assumed to occur instantaneously and are implemented such that an active gas cell (star-forming) is probabilistically chosen to either form a star or become a site for SNII (see Vogelsberger et al. 2013). SNII feedback is modelled by converting the gas cell into a wind particle that is launched in an isotropically random direction (as opposed to the bipolar wind model of Marinacci et al. 2014a, see also Weinberger et al. 2017). We set the wind velocity equal to 3.46 σ_{DM}^{1D} , where σ_{DM}^{1D} is the local 1D dark matter velocity dispersion (see e.g. Okamoto et al. 2010), which is calculated from the nearest 64 dark matter particles. Upon launch, a wind particle is loaded with $1 - \eta_w$ times the metal mass of the gas cell from which it is created, where $\eta_{\rm w} = 0.6$ is the metal loading parameter. The wind particle travels away from its launch site and interacts only gravitationally until either a gas cell with a density below 0.05 times the physical density threshold for star formation is reached, or the maximum travel time is exceeded. Once either of these criteria is met, the wind particle deposits its mass, metals, momentum and energy into the gas cell in which it is located. Following Marinacci et al. (2014a), the energy deposited is split into equal parts, kinetic and thermal, which produces smooth, regular winds in contrast to cold, purely kinetic winds. This parametrization of wind outflows is required in order to reproduce both the stellar mass and oxygen abundances of low-mass haloes (Puchwein & Springel 2013).

To facilitate comparison between our models and observations, we derive photometric properties for the star particles. Because we treat each star particle as an SSP of a given age, mass and metallicity, it is possible to use stellar population synthesis models to estimate their luminosity in a series of broad-bands. Our model currently tabulates luminosities for U, V, B, K, g, r, i and z bands from the Bruzual & Charlot (2003) catalogues. We caution that we do not model the effects of dust attenuation.

Primordial and metal-line cooling with self-shielding corrections is enabled. Following the model of Faucher-Giguère et al. (2009), a spatially uniform UV background field is included, which completes reionization at redshift $z \sim 6$ (for more details, see Vogelsberger et al. 2013).

BH are seeded with a seed mass of $10^5 \text{ M}_{\odot} h^{-1}$ in halo FOF groups of masses greater than $M_{\text{FOF}} = 5 \times 10^{10} \text{ M}_{\odot} h^{-1}$, and are

placed at the position of the most dense gas cell. These BH sink particles acquire mass from nearby gas cells or by merging with other BH particles. The BH mass growth from accretion and merger processes follows Springel et al. (2005). The mass growth from gas accretion is described by Eddington-limited Bondi–Hoyle–Lyttleton accretion (Bondi & Hoyle 1944; Bondi 1952) in addition to a term that models the radio mode accretion. This radio mode term comes from the assumption that the Intracluster medium (ICM) of the halo is in thermodynamic equilibrium, and therefore the thermal energy added to the ICM from the radio mode AGN feedback,

$$L_{\rm radio} = \epsilon_{\rm f} \epsilon_{\rm r} c^2 \dot{M}_{\rm radio},\tag{4}$$

is radiated away in X-ray losses, and is set equal to $R(T, z)L_X$, where L_X is the X-ray luminosity and R(T, z) is a scaling factor. The scaling factor is calculated from relations presented in Nulsen & Fabian (2000), in which the accretion rate, $\dot{M}'_{\rm BH}$, is inferred from the state of the gas at large distances from the BH, and the X-ray luminosity, L'_X , is assumed to depend on the observational scaling relation given by Pratt et al. (2009):

$$R(T,z) = \frac{\epsilon_{\rm f} \epsilon_{\rm r} c^2 \dot{M'}_{\rm BH}}{L'_{\rm X}},\tag{5}$$

where

$$\dot{M}'_{\rm BH} = \frac{2\pi Q(\gamma - 1)k_B, T_{\rm vir}}{\mu m_H \Lambda(T_{\rm vir})} G M'_{\rm BH} \left[\frac{\rho^2}{n_e n_H}\right] \mathcal{M}^{3/2},$$
$$M'_{\rm BH} = M_0 \left(\frac{\sigma}{\sigma_0}\right)^4,$$
(6)

and

$$L'_{\rm X} = \frac{H(z)}{H_0} C \left(\frac{T}{T_0}\right)^{2.7}.$$
(7)

Here, $\gamma = 5/3$ is the adiabatic index of the gas, $T_{\rm vir}$ is the virial temperature, \mathcal{M} is the Mach number of gas far from the BH, σ is the velocity dispersion of stars in the galactic bulge, Q = 2.5, $C = 6 \times 10^{44}$ erg s⁻¹ and $T_0 = 5$ keV. The Mach number is set to $\mathcal{M} = 0.0075$ because the BH–stellar mass relation is reproduced for this value in cosmological simulations. We adopt this parametrization because the accretion rate inferred in Nulsen & Fabian (2000) depends on the virial temperature, and therefore is insensitive to gas temperature variations that are required to create a self-regulated feedback process.

The total BH accretion rate is given by

$$\dot{M}_{\rm BH} = \min\left[\frac{4\pi G^2 M_{\rm BH}^2 \rho}{\left(c_{\rm s}^2 + v_{\rm BH}^2\right)^{3/2}} + \frac{R(T, z)L_{\rm X}}{\epsilon_{\rm f}\epsilon_{\rm r}c^2}, \dot{M}_{\rm Edd}\right],\tag{8}$$

where ρ and $c_{\rm s}$ are the density and sound speed of the surrounding gas, $v_{\rm BH}$ is the velocity of the BH relative to the gas, $\dot{M}_{\rm Edd}$ is the Eddington accretion rate and $L_{\rm X}$ is calculated from the thermal state and cooling time of the non-star-forming gas cells. We define the BH radiative efficiency parameter to be $\epsilon_{\rm r} = 0.2$ and the fraction of released energy that couples thermally to the gas to be $\epsilon_{\rm f} = 0.07$, respectively.

Feedback from BH is implemented in two continually active phases: a radio mode and a quasar mode. In both phases, the energy injected into the gas is given by

$$\dot{E} = \epsilon_{\rm f} \epsilon_{\rm r} \dot{M}_{\rm BH} c^2. \tag{9}$$

For the quasar mode, the thermal energy given by equation (9) is injected isotropically into neighbouring gas cells. For the radio mode, bubbles of gas are gently heated at randomly placed locations

following an inverse square distance profile around the BH, up to a maximum radius of $0.8 R_{vir}$. The bubbles are chosen to be 0.1 times the virial radius in size, from which the thermal energy budget for each bubble is estimated as

$$E_{\rm b} = \sum_{i} 0.05 m_i \overline{u}_{\rm ICM},\tag{10}$$

where \overline{u}_{ICM} is the mean thermal energy of gas inside the halo. The number of bubbles is then calculated from the total energy available for radio mode feedback based on the mass accretion rate on to the BH. In our simulations, both the quasar and radio feedback modes are active at all times.

Magnetic fields are implemented following the method described in Pakmor & Springel (2013). A homogeneous magnetic field of 10^{-14} (comoving) G is seeded at z = 127 in the simulation box Z'coordinate direction. The choice of direction and strength has been shown to have little effect on the evolution (Pakmor et al. 2014; Marinacci et al. 2015). The divergence cleaning scheme of Powell et al. (1999) is implemented to ensure that $\nabla \cdot \boldsymbol{B} \sim 0$. We note that the presence of magnetic fields has little effect on the global stellar disc properties discussed in this paper. A study of the magnetic field evolution will be presented in Pakmor et al. (in preparation).

3 DISC STRUCTURE

In Figs 1-3, we present the face-on and edge-on projections of all 30 simulated haloes at z = 0. The spin- (or z-)axis of star particles is found by calculating the dot product of the eigenvectors of the moment of inertia tensor of star particles within $0.1R_{200}$ with the angular momentum vectors of the same star particles in the X', Y', Z'simulation box coordinate reference frame. The eigenvector of the inertia tensor that is most closely aligned with the principal angular momentum axis is chosen as the z-axis. The images are a superposition of the K-, B- and U-band luminosities (mapped to the red, green and blue colour channels, respectively), which indicate the distribution of older (redder colours) and younger (bluer colours) star particles, respectively. In the majority of cases, a radially extended, young star-forming disc component typical of late-type disc galaxies is visible, in addition to clear non-axisymmetric structures such as bars and spiral arms. A red spheroidal bulge is a common feature of the simulations also, as can be clearly seen in the edge-on projections. The bulge component appears to be subdominant in many of the haloes; however, there are some notable exceptions. In particular, haloes Au 13 and Au 30 do not show extended discs, but rather a spheroidal morphology. Au 11 appears to be a special case owing to an imminent major merger.

Fig. 4 shows the stellar surface density profiles, for stellar mass within ± 5 kpc of the mid-plane in the vertical direction, for all simulations at z = 0. The profiles are simultaneously fit to the sum of a Sérsic (1963) and exponential profile using a non-linear least-squares method (as in Marinacci et al. 2014a). The total fitted profile is indicated by the black curve. The fit is carried out to the optical radius, defined to be the radius at which the B-band surface brightness drops below $\mu_B = 25$ mag arcsec⁻². In general, the stellar profiles are well fit by this bulge-disc decomposition, and exhibit a wide range of disc scalelengths, from 2.16 to 11.64 kpc, whereas the bulge effective radii, $R_{\rm eff}$, are typically between 1 and 2 kpc. The surface density at a radius of 8 kpc (similar to the solar radius) is in many cases a few tens of M_{\odot} pc⁻², which is similar to the value measured in the Milky Way (Flynn et al. 2006). We note that we applied this fitting procedure to the U, B and V surface brightness

 $\epsilon = \frac{L_z}{L_{z,\max}(E)},$ (11)

In addition to the surface density decomposition shown in Fig. 4,

we use a kinematic decomposition of the star particles to infer the

disc and bulge mass. The kinematic decomposition entails the calcu-

lation of the circularity parameter, ϵ , for all star particles according

to the procedure outlined in Abadi et al. (2003),

where L_z is the z-component of angular momentum of a given star particle and $L_{z,\max}(E)$ is the maximum angular momentum allowed for the orbital energy, E, of the same star particle. This ensures that a prograde circular orbit in the disc plane takes the value $\epsilon = 1$, retrograde circular orbits correspond to $\epsilon = -1$, and $\epsilon \sim 0$ indicates orbits with a very low z-component of angular momentum, which may be highly inclined to the disc spin axis and/or be highly eccentric.

From the distributions shown in Fig. 7, we calculate the D/Tvalues from two different methods: the first follows the assumption made in Abadi et al. (2003) that the bulge component has zero net rotation and is therefore centred around $\epsilon = 0$. The bulge mass can therefore be inferred by doubling the mass of the counter-rotating

In Fig. 5, we calculate the stellar half-luminosity radius measured in the r band, and plot it as a function of stellar mass at a series of redshifts. For z > 0, we compare our galaxy sizes to the corresponding observational relation for late-type disc galaxies derived from the CANDELS survey by van der Wel et al. (2014). We note that all of the Auriga galaxies qualify as late-type galaxies according to the criteria followed in van der Wel et al. (2014). On average, our simulated galaxies grow in size over time, and match the observations best at z > 1, with a clear trend of increasing disc size with increasing stellar mass at z = 3 (first panel) and 2 (second panel) close to the locus of the observations. At z = 1 (third panel), this trend weakens and the scatter in half-luminosity radius increases as several galaxies become very compact. At z = 0 (right-hand panel), we compare our simulated galaxies to the observational relation for late-type disc galaxies derived from the Galaxy And Mass Assembly (GAMA) survey by Lange et al. (2016). According to the classification criteria followed in Lange et al. (2016), 22 of the Auriga galaxies qualify as late-type galaxies, most of which lie within 0.2 dex scatter of the Lange et al. (2016) relation; 13 galaxies lie below the scatter. We note that those with the shortest scalelengths (see Fig. 6), which belong to this compact group of galaxies, are not the most compact at earlier times. Several (but not all, see Section 4) of the these galaxies have experienced a major merger at z < 1, and some even at around $z \sim 0.5$, which creates a massive bulge component and explains their transition to compact mass distributions. Bearing this in mind, the majority of simulated galaxies agree well with the observed sizes of late-type galaxies, as shown in Fig. 5.

In Fig. 6, we show the disc scalelengths of the simulated galaxies as a function of their stellar masses. We compare with the observations of disc galaxies presented in Gadotti (2009), who used dust-corrected stellar masses of galaxies selected from the Sloan Digitial Sky Survey (SDSS) Data Release 2 derived from Kauffmann et al. (2003). The simulation mean appears to lie close to the best-fitting line found from observations, and the significant variation of scalelength in the simulation suite is evident. In Section 4, we examine the physical processes that drive this scatter, therefore we highlight the six largest (smallest) discs in blue triangles (red squares) here and in subsequent plots in order to emphasize how the disc size relates to other variables.



Figure 1. The face-on and edge-on projected stellar density at z = 0 for simulations Au 1–12. The images are synthesized from a projection of the *K*-, *B*- and *U*-band luminosity of stars, which are shown by the red, green and blue colour channels, in logarithmic intervals, respectively. Younger (older) star particles are therefore represented by bluer (redder) colours. The plot dimensions are $50 \times 50 \times 25$ kpc³. For movies and images, go to http://auriga.h-its.org.

material. The disc is then assumed to make up the remaining part of the distribution. The D/T values inferred from this method are indicated in each panel (the bracketed values), and are typically around 0.7–0.8. However, Obreja et al. (2016) showed that D/Tvalues inferred from this method overestimate the D/T values inferred from Gaussian mixture models of dynamical variables by about 5–20 per cent. The second method assigns all star particles that satisfy $\epsilon > 0.7$ to the disc. This D/T value is typically lower than that of the first method because only the kinematically coldest star particles are considered to be part of the disc, which means that there is a large swathe of particles in the range $0 < \epsilon < 0.7$ that are assigned to a spheroidal component. The true value of D/T probably lies between the two values. From Fig. 7 we can infer that the majority of the simulated haloes host prominent disc components with relatively small bulges. However, there are notable exceptions that contain a large bulge, for example, Au 29 is almost completely

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Figure 2. As Fig. 1 for simulations Au 13–24.

dominated by a spheroidal stellar component, which is caused by a recent merger.

We examine the vertical structure of the discs by fitting their vertical density distribution of the disc at a series of radii. The fitting function we choose is defined by two exponentials and a break radius, which has the flexibility to fit density profiles that are well described by either a single or double exponential². To remove

 2 We note that fitting a single exponential produces similar scaleheight values in many cases.

the effect of warps, we bin star particles in a 2D Cartesian grid in the disc plane with cells of side length \sim 2 kpc, and calculate the mean vertical height in each cell. We then subtract the corresponding mean height from each particle such that the peak density is located in the disc mid-plane everywhere³. The radial profiles of the disc

³ We note that some of the Auriga discs are strongly warped (Gómez et al. 2017), which can give the false impression of flaring when the vertical density distribution is averaged over azimuth.



Figure 3. As Fig. 1 for simulations Au 25-30.

scaleheight for all galaxies are shown in Fig. 8. The star particles considered in this figure are those that are kinematically defined to be part of the disc, specifically those that satisfy $\epsilon > 0.7$. This sample is further subdivided into a young stellar age group, defined as star particles younger than 3 Gyr. Fig. 8 highlights that a common feature in the simulation sample is the presence of discs with scaleheights of about 1 kpc at radii less than ~ 8 kpc, which is thicker than the accepted value of \sim 300 pc for the thin disc of the Milky Way, and similar to the observed value of the Milky Way's thick disc (e.g. Jurić et al. 2008). The younger star population, as expected, is thinner than older star populations, and in many cases has scaleheights of \sim 200-300 pc within $R \sim 8$ kpc, which is similar to the thin disc of the Milky Way. Grand et al. (2016a) showed that this trend is a combination of dynamical scatter of star particles and upside-down formation of the disc through the cooling and accretion of star-forming gas. The thinning of the gas disc (and therefore newborn star particles) with time is likely caused by the decreasing merger activity and star formation rate (SFR, see fig. 8 of Marinacci et al. 2016). Another common feature is a flaring scaleheight profile for both old and young star particles. The latter is very similar to the flaring starforming gas distribution at z = 0, which suggests that a significant amount of disc flaring of a stellar population is set at birth.

In Fig. 9, we show the radial profiles of the radial, tangential and vertical velocity dispersions of all the star particles (not only those kinematically assigned to the disc). In most cases, the profiles rise, then drop too steeply in the innermost few kiloparsecs. Outside of

this region, the flaring disc dominates the stellar distribution and the profiles flatten out at radii larger than 10 kpc. The values of the velocity dispersion in all directions at the solar radius (mean values of $\sigma_{\rm R} \sim 60 \mbox{ km s}^{-1}$, $\sigma_Z \sim 50 \mbox{ km s}^{-1}$) are too high compared to the thin disc of the Milky Way: $\sigma_{\rm R} \sim 35 \mbox{ km s}^{-1}$; $\sigma_Z \sim 25 \mbox{ km s}^{-1}$ (see Bland-Hawthorn & Gerhard 2016, and references therein), although they are similar to those values inferred for the thick disc: $\sigma_{\rm R} \sim \sigma_Z \sim 50 \mbox{ km s}^{-1}$. The ratio between the radial and vertical velocity dispersions is in nearly all cases similar to the value $\sqrt{2}$ observed in the Milky Way.

Following Obreja et al. (2016), we exploit data from the DiskMass Integral Field Unit spectroscopic survey (Bershady et al. 2010) in order to compare the vertical structure of our simulated galaxies to external disc galaxies. Specifically, we make use of the results obtained by Martinsson et al. (2013) who analysed a subsample of disc-dominated galaxies from the DiskMass Survey and presented a correlation between their central vertical velocity dispersion, σ_{20} , and the flat part of their rotation curves. In Fig. 10, we show σ_{z0} calculated for all star particles as a function of the circular velocity at the optical radius, which, in most cases, coincides with the flatter, outer rotation curve. The simulations have systematically higher velocity dispersions than the observations. However, we note that the galaxy sample analysed in Martinsson et al. (2013) make up the kinematically coldest discs in the DiskMass survey, with no significant bulges or bars. We therefore calculate σ_{z0} for all disc star particles ($\epsilon > 0.7$), which brings most simulations with $\nu > 220$ km s⁻¹



Figure 4. Face-on stellar surface density profiles for stellar mass within ± 5 kpc of the mid-plane in the vertical direction for all simulations at z = 0. The profiles are simultaneously fit with a Sérsic (1963) (red curve) and exponential (blue curve) profile using a non-linear least-squares method. The total fitted profile is indicated by the black curve. The fit is carried out to the optical radius (vertical dashed line), defined to be the radius at which the *B*-band surface brightness drops below $\mu_B = 25$ mag arcsec⁻². The first (second) six panels with blue (red) labels represent the discs with the largest (smallest) scalelengths, and are grouped together to facilitate reference. The sample has a wide range of disc scalelengths, from 2.16 to 11.64 kpc.

in line with observations and most with v < 220 km s⁻¹ below the relation. We note that the largest (smallest) discs tend to have lower (higher) σ_{z0} . This conservative selection of disc star particles likely underestimates the true value of σ_{z0} for the disc, which probably

lies between the two sets of simulated points in Fig. 10. We conclude that the vertical thickness of the inner parts of our simulated galaxies is similar to observations, although, on average, the outer parts seem to be thicker compared to the Milky Way.

Table 1. Table of simulation parameters at z = 0. The columns are: (1) model name; (2) halo virial mass ^a; (3) halo virial radius^b; (4) stellar mass; (5) inferred stellar disc mass; (6) radial scalelength; (7) inferred stellar bulge mass; (8) bulge effective radius; (9) Sérsic index of the bulge; (10) disc to total mass ratio; (11) optical radius; (12) accreted stellar fraction within $0.1R_{200}$ and (13) gas fraction within $0.1R_{200}$.

Run	$\frac{M_{200}}{(10^{10}\mathrm{M_{\bigodot}})}$	$\frac{R_{200}}{(\text{kpc})}$	$\frac{M_{*}}{(10^{10}{ m M_{\odot}})}$	$\frac{M_{\rm d}}{(10^{10}{\rm M_{\odot}})}$	$\frac{R_{\rm d}}{(\rm kpc)}$	$\frac{M_{\rm b}}{(10^{10}{\rm M_{\bigodot}})}$	$\frac{R_{\rm eff}}{\rm (kpc)}$	п	D/T	$\frac{R_{\rm opt}}{(\rm kpc)}$	$f_{\rm acc}$	$f_{\rm gas}$
				Leve	el 4 resoluti	on						
Au1	93.38	206.03	2.75	1.07	5.44	1.59	1.35	1.41	0.40	20	0.29	0.41
Au2	191.47	261.76	7.05	6.38	11.64	2.34	2.06	1.53	0.73	37	0.13	0.17
Au3	145.78	239.02	7.75	6.29	7.26	2.04	1.49	0.99	0.76	31	0.14	0.19
Au4	140.89	236.31	7.10	3.66	3.93	2.01	1.74	1.35	0.65	24.50	0.37	0.33
Au5	118.55	223.09	6.72	4.51	3.58	1.81	0.84	0.87	0.71	21	0.10	0.27
Au6	104.39	213.83	4.75	3.32	5.95	1.65	2.85	2	0.67	26	0.11	0.19
Au7	112.04	218.94	4.88	2.46	5.14	2.05	1.73	1.74	0.55	25	0.34	0.39
Au8	108.06	216.31	2.99	2.46	6.57	0.65	2.15	1.33	0.79	25	0.16	0.23
Au9	104.97	214.22	6.10	3.60	3.37	2.17	1	0.95	0.62	19	0.06	0.21
Au10	104.71	214.06	5.94	2.38	2.60	3.15	1.08	1.18	0.43	16	0.04	0.24
Au11	164.94	249.05	6.91	1.13	3.06	2.75	1.05	1.35	0.29	16	0.46	0.22
Au12	109.28	217.12	6.01	4.32	3.29	1.13	0.89	0.76	0.79	19	0.21	0.31
Au13	118.90	223.33	6.19	1.68	3.38	3.80	1.40	1.55	0.31	15.50	0.14	0.17
Au14	165.72	249.44	10.39	6.36	4.19	3.18	1.14	1.59	0.67	26	0.17	0.28
Au15	122.25	225.40	3.93	2.77	5.32	1.05	2.22	2	0.73	23	0.18	0.40
Au16	150.33	241.48	5.41	5.06	9.03	1.18	1.83	1.39	0.81	36	0.11	0.22
Au17	102.84	212.77	7.61	2.56	4.19	4.64	1.21	0.83	0.36	16	0.03	0.19
Au18	122.07	225.29	8.04	5.21	3.72	2.46	1.23	0.95	0.68	21	0.05	0.13
Au19	120.90	224.57	5.32	3.53	4.81	1.43	1.42	2	0.71	24	0.23	0.26
Au20	124.92	227.03	4.74	2.25	8.02	2.35	2.17	1.89	0.49	30	0.36	0.33
Au21	145.09	238.65	7.72	6.01	4.61	1.24	1.19	1.06	0.83	24	0.23	0.28
Au22	92.62	205.48	6.02	2.85	2.25	2.71	1.01	0.93	0.51	13.50	0.03	0.11
Au23	157.54	245.27	9.02	5.55	4.99	3.19	1.71	1.44	0.63	25	0.11	0.20
Au24	149.18	240.86	6.55	3.76	5.57	2.19	0.95	0.97	0.63	30	0.12	0.16
Au25	122.11	225.31	3.14	2.48	6.70	0.93	2.95	1.88	0.73	21	0.04	0.34
Au26	156.38	244.69	10.97	4.70	3.14	5.46	1.12	1.02	0.46	18	0.13	0.12
Au27	174.55	253.81	9.61	7.23	4.29	1.74	0.95	1.07	0.81	26	0.14	0.22
Au28	160.54	246.83	10.45	6.76	2.16	2.36	0.95	1.11	0.74	17.50	0.20	0.14
Au29	154.24	243.55	9.03	4.08	3.20	2.61	1.19	1.15	0.61	19	0.37	0.21
Au30	110.83	218.15	4.25	1.45	5.01	2.43	1.90	1.22	0.37	17	0.47	0.27
				Leve	el 5 resoluti	on						
Au6	102.65	212.64	3.84	3.55	4.59	0.27	1.09	0.61	0.93	26	0.06	0.27
Au16	149.47	241.02	3.75	3.09	7.69	0.82	1.47	0.87	0.79	33	0.08	0.27
Au24	148.15	240.31	6.26	4.51	4.45	1.33	1.44	0.81	0.77	32	0.07	0.27
				Leve	el 3 resoluti	on						
Au6	101.48	211.83	6.08	4.34	3.20	1.20	0.75	1.47	0.78	26	0.12	0.14
Au16	150.43	241.53	7.85	6.47	6.37	1.41	0.53	1.60	0.82	33	0.09	0.14
Au24	146.79	239.57	7.77	5.70	6.52	1.87	0.62	1.91	0.75	32	0.12	0.14

^aDefined to be the mass inside a sphere in which the mean matter density is 200 times the critical density, $\rho_{crit} = 3H^2(z)/(8\pi G)$.^bDefined as the stellar mass within 0.1 times the virial radius.

In Fig. 11, we show the baryonic Tully–Fisher (BTF) relation for all the simulations. The baryonic mass is taken as the sum of all star particles and gas elements within an optical radius that contains the majority of stellar and cold gas material in the haloes. The circular velocity at the optical radius is measured, which is a large enough radius (in most cases) to be at the flatter, outer part of the rotation curve. For comparison, we include the observational BTF relation from McGaugh & Schombert (2015), who determine stellar masses using two methods: the first via spectral energy distribution fitting using population synthesis (consistent with a Chabrier IMF that we use in this paper) constrained by 3.6 μ m emission, and the second from the DiskMass data, which is independent of the IMF. We retain also the data presented in Marinacci et al. (2014a) that include the best fit of the data set determined in Dutton et al. (2011). The slope for the simulated galaxies is very similar to that of the set of observations shown in Fig. 11 and they lie well within the scatter. We tested different measures of the rotation velocity including taking the circular velocity at various observationally motivated radii and verified that there is no significant variation in the trends. We conclude that the consistency of the simulated haloes with the BTFR indicates that the Auriga haloes host rotationally dominated disc galaxies with rotational velocities in agreement with observed disc galaxies.

In Fig. 12, we show the circular velocity curves of the simulations decomposed into stellar, gas and dark matter components. In many cases, the stellar component reaches a peak in the inner regions and steadily decreases with increasing radius, and the dark matter component rises with increasing radius. In most cases, the stellar and dark matter contribution to the profile balance in the outer disc regions, producing a near-flat rotation curve that persists beyond



Figure 5. The stellar half-luminosity radius measured in the *r* band is plotted against stellar mass for all simulations, at a series of redshifts. The best-fitting curves presented in van der Wel et al. (2014) for CANDELS survey late-type galaxies are shown for z = 1-3, and the best-fitting (0.2 dex scatter) curve presented in Lange et al. (2016) for GAMA survey late-type galaxies are shown by the (light) blue line, for z = 0. The discs with the six largest (smallest) scalelengths (see Fig. 6) are indicated by the triangles with blue outline (squares with red outline).



Figure 6. Disc radial scalelength plotted against stellar mass for all simulations. The best-fitting Sloan Digitial Sky Survey (SDSS) Data Release 2 relation of Gadotti (2009) is shown by the blue line with a scatter of 0.2 dex indicated by the blue shaded region.

20 kpc. The gas component comprises star-forming and non-starforming gas, of which the former is rotationally supported, whereas the latter is warm or hot and rotates slowly. Together, the gas components contribute a few tens of km s⁻¹ to the circular velocity at large radii. Overall, the majority of cases exhibit circular velocity curves that compare well with the current observational data for the Milky Way compiled from the H I surveys and stellar kinematics. There are, however, exceptions such as Au 26 and Au 17 that exhibit high-velocity peaks in the inner region as a result of very centrally concentrated stellar distributions in the form of either a nuclear bulge that formed as a result of a late-time merger (e.g. Au 28) or a strong stellar bar (e.g. Au 17).

4 DISC SIZES

As we have shown above in Fig. 4, there is a substantial spread in radial scalelength among the simulated galaxies: from 2.16 to 11.64 kpc. This is evident in the present-day stellar projections shown in Fig. 1. In this section, we aim to determine the factors that control disc size by establishing the principal mechanism(s) that stimulate and suppress disc growth.

4.1 Angular momentum

First, we investigate how discs are affected by the angular momentum of the halo and its various constituents, a dependence which is theoretically expected to be correlated (Peebles 1969; Fall & Efstathiou 1980; Mo, Mao & White 1998; Bullock et al. 2001). In the top panel of Fig. 13, we show, for all simulations, the disc scalelength as a function of halo spin, defined as

$$\lambda = \frac{l_z}{\sqrt{2}V_{200}R_{200}},\tag{12}$$

where l_z is the specific angular momentum of the all the material inside the virial radius, R_{200} , and V_{200} is the circular velocity at R_{200} . A positive correlation is present: discs of larger radial scalelengths tend to be hosted by haloes of greater spin⁴. There is a significant scatter, some of which can be understood by consideration of some outlying haloes. For example, the encircled symbols represent Au 1 and Au 11, both of which have nearby massive companions (in the case of Au 11, it is a massive merger) at z = 0, which act to increase their spin parameters beyond their normal values. The radially extended disc galaxy with $\lambda \sim 0.2$ has a particularly large spin value, owing to a late quiescent merger, and a disc scalelength lower than the inferred correlation in the top panel of Fig. 13, owing to a low SFR at late times and at large radii, which prevents it from building up an extended disc.

The positive correlation between halo spin and disc scalelength at face value seems to contradict the conclusion reached in Scannapieco et al. (2009), who found no correlation between the presence of discs and halo spin parameter in the eight Aquarius simulations re-simulated with a modified version of the SPH code GADGET 2 (Springel 2005). However, the conclusions of Scannapieco et al. (2009) were based on a lack of correlation between disc masstotal mass ratio, D/T, and the halo spin. As we show in the bottom panel of Fig. 13, this is also the case for the Auriga simulations.

⁴ Herpich et al. (2015) found a qualitatively similar correlation for spin values between 0.02 and 0.1, using a simulation suite of isolated haloes that undergo spherical collapse.



Figure 7. The orbital circularity distribution for all simulations at z = 0. The spheroidal component (red hatches) is calculated assuming the bulge has no net rotation, and is therefore taken to be the material with negative ϵ mirrored about the $\epsilon = 0$ value (or twice the mass of the counter-rotating material). The disc (blue hatches) is then assumed to make up the remaining part of the distribution. The disc-to-total mass ratio (D/T) that results from this decomposition is indicated by the bracketed value in each panel. The unbracketed value represents the decomposition that follows from assuming the disc to be composed of those star particles satisfying $\epsilon > 0.7$, which is generally a smaller fraction than the bracketed value.

The reason is that D/T is sensitive to various factors, in particular to the interaction with subhaloes and mergers (even quiescent mergers if they occur at late times) that can easily drive down the ratio by perturbing disc star particles, and hence wash out a correlation. We

conclude that the discs of the Auriga simulations do correlate with halo spin as expected from theories of inside-out formation, and are, at the same time, not inconsistent with the results of Scannapieco et al. (2009).



Figure 8. The vertical scaleheight of all star particles (black) and star particles younger than 3 Gyr (blue) as a function of radius. The scaleheight at a given radius is calculated by fitting a function composed of two exponentials and a break radius (see the text for details). Each radial profile of vertical scaleheights is fit with an exponential function: $A \exp(-R/R_{\text{flare}})$, where a large value of $-R_{\text{flare}}^{-1}$ indicates a high degree of flaring of the vertical density distribution. These fits are indicated by the dashed lines.

4.2 Quiescent mergers

In this section, we investigate the impact of subhalo accretion on the spin (see also Vitvitska et al. 2002; D'Onghia & Navarro 2007; Sharma, Steinmetz & Bland-Hawthorn 2012) and size of our simulated discs. We first define a measure for the edge of the stellar disc, $R_{\rm edge}$, as the radius at which the stellar surface density drops below $1 \, {\rm M_{\odot} \, pc^{-2}}$, which is a good proxy for the optical radius of the disc (see Fig. 4). In the top panels of Fig. 14, we show the time evolution of $R_{\rm edge}$ for four of the most radially extended discs in the sample.



Figure 9. The radial (red), tangential (blue) and vertical (black) velocity dispersion profiles of all simulations at z = 0. The ratio between the radial and vertical velocity dispersions is indicated by the dashed grey curve, and is generally found to be between 1 and 1.5, close to the observational value of $\sim \sqrt{2}$ for the Milky Way in the solar neighbourhood. All dispersions are, however, larger than observed near the Sun.



Figure 10. The central vertical velocity dispersion of star particles as a function of the circular velocity at the optical radius for all simulated galaxies. The filled (empty) symbols indicate the velocity dispersion of all (disc) star particles within the central kiloparsec of the galaxies. Observational data and error bars (grey points) derived by Martinsson et al. (2013) represent a kinematically cold subsample of disc galaxies from the DiskMass survey.

Focusing on Au 2, we note two features: a sudden increase in R_{edge} at $t_{lookback} \sim 8$ Gyr after a period of almost no growth, followed by steady growth of R_{edge} until z = 0.

The cause of this increase of R_{edge} appears to be related to the accretion of gas-rich satellites. For example, in the third row of Fig. 14, we show the distance evolution of a subhalo that first comes within 200 kpc of the main halo at around $t_{lookback} \sim 8$ Gyr, and gradually approaches the latter until they merge at around $t_{lookback} \sim 6.5$ Gyr. The second row of Fig. 14 shows the evolution of the cosine of the



Figure 11. The Baryonic Tully–Fisher relation of all simulated galaxies. The mass includes all the stars and gas within an optical radius, R_{opt} , and the velocity is equal to $\sqrt{(GM(< R_{opt})/R_{opt})}$. The optical radius is large enough in most cases to probe the flat part of the rotation curve (in haloes that have flat rotation curves). The results of several observational studies, i.e. Verheijen (2001), Courteau et al. (2007) and Pizagno et al. (2007), are included for comparison. All the simulated galaxies fall comfortably within the scatter of the observational relations shown.

angle between the orbital angular momentum vector of subhaloes and the spin axis of the stellar disc of the main halo. It is clear that the subhalo at $d \sim 200$ kpc is not well aligned with the disc of the main halo ($\cos \alpha \sim 0.4$); however, as the subhalo sinks into the main halo, its orbit becomes increasingly more aligned with the disc. At $t_{lookback} \sim 8$ Gyr, when the subhalo is $d \sim 80$ kpc from the galaxy centre, the subhalo and disc are almost perfectly aligned (see also fig. 4 of Monachesi et al. 2016).

The influence of these well-aligned, quiescent mergers on the specific angular momentum, l_z , of the dark matter and gas in different radial shells is depicted in the fourth row of Fig. 14. For Au 2, l_z abruptly increases at around the time the subhalo falls into the main halo and crosses the radial shells; first, l_z of the dark matter and gas in the outermost region considered (50-80 kpc) increases, followed by the intermediate region (25-50 kpc) and finally the inner region (10-25 kpc). It is interesting to note that once the subhalo has been accreted, the dark matter retains a constant l_z after its pre-merger increase, whereas the l_z of the gas continues to rise in the intermediate radial region long after the merger has occurred. The explanation of this behaviour can be found from consideration of the angular momentum transfer from the dark matter to the gas component (recently studied in detail in Zjupa & Springel 2017, in the Illustris simulation). As the subhalo falls into the main halo, the gas component can be affected by the ram pressure in such a way as to offset the centre of mass of the gas and dark matter of the subhalo, and thus allow a torque to come into play and transfer orbital angular momentum from its dark matter to the gas. This is seen in Fig. 15 as the warm gas (which may also contain halo gas that has been spun up by the subhalo) with a high amount of rotation in the wake of the subhalo, and the slight depression in the dark matter l_z after the initial rise in Fig. 14. The high-angular momentum gas then cools and enters the inner regions to increase the l_7 there (seen



Figure 12. Total circular velocity curves for all simulations (black lines) and for the constituent components: stars (green dotted), dark matter (red dot–dashed) and gas (blue dashed). For comparison, a compilation of observational data for the Milky Way from Huang et al. (2016) is indicated. Different symbols refer to different sources; H I (grey pluses), red clump giant stars selected from LSS-GAC and APOGEE (magenta crosses) and halo K giant stars selected from SEGUE (cyan circles).

as the dip in the l_z of the gas in the outer region and increase in the l_z of the intermediate region)⁵.

In addition to the increase in l_z of the gas and dark matter, the stellar component is also affected; in the bottom row of Fig. 14, we show the evolution of l_z in a set of radial regions of the in situ star particles older than 10 Gyr, i.e. before the merger events in question occur. The clarity of the effect of the merging subhaloes is striking: the l_z of the old stars is almost constant at all times until a merger

⁵ The increasing gas specific angular momentum is consistent with the redistribution of angular momentum of gas to the inner regions and dark matter to the outer regions reported in Sharma et al. (2012).



Figure 13. The disc radial scalelength (top panel) and the kinematically defined disc mass-total stellar mass ratio, D/T (bottom panel), as a function of the halo spin parameter (see the text for definition), for each simulation. Square (triangle) symbols of red (blue) outline represent the six smallest (largest) discs in terms of scalelength. The symbols encircled in green highlight Au 1 and Au 11, both of which have massive companions that contribute to large spin values.

event occurs and increases very sharply their specific angular momentum. After this time, their l_z remains constant at a comparatively larger value. The trends described above for Au 2 are applicable also to Au 3 (second column of Fig. 14), Au 8 (third column of Fig. 14) and Au 20 (fourth column of Fig. 14), which confirm that these qualitative effects are not unique to one special case.

The dynamical effects of the merger on the main halo described above are well illustrated in Fig. 15, which shows the face-on and edge-on projections of the stars and gas in a 100 kpc side-length box centred on the main halo, at the time of the merger event. The subsequent cooling of the high-angular momentum gas leads to the build-up of fresh star-forming gas around the disc edges, which is consistent with the inside-out star formation that takes place in the large disc simulations shown (see Fig. 18). Indeed, the disc growth even in this small period shown in Fig. 15 is striking. We note that this mechanism for disc growth is not uncommon among the Auriga simulations: five out of the six largest discs have experienced quiescent mergers and subsequent disc growth. The exception is Au 25 that already has high angular momentum at $z \sim 3$. In addition, 6 out of the 10 discs that have intermediate scalelengths (between 4 and 6 kpc) have experienced quiescent mergers at some point of their evolution, either from a less massive subhalo or in combination with retrograde or violent mergers that act to reduce overall disc growth at late times.

In contrast, the smallest discs have no such quiescent gas-rich mergers, and in some cases instead undergo violent major mergers that act to destroy discs (see Sparre & Springel 2016). The comparatively small amount of angular momentum in the gas and dark matter that these haloes possess reinforces the idea that angular momentum, whether acquired from these quiescent mergers or otherwise, is critical to the build-up of large, radially extended discs.

4.3 AGN feedback

As described in Section 2, the galaxy formation model includes BH feedback in both a radio and a quasar mode. In this section, we investigate how AGN feedback shapes the distribution and size of the stellar disc. In Fig. 16, we show the mass growth of the BH (a good proxy for AGN feedback energy injection into the gas) since z = 1 as a function of the present-day disc scalelength. An anticorrelation between the two quantities is discernible, with some outliers such as Au 2, which lies far to the right of the other simulations. This trend might suggest that BH growth, and thus AGN feedback, is able to suppress the formation of disc stars at large radii, and hence lead to smaller discs. However, it is unclear from Fig. 16 whether it is the degree of feedback that drives disc size, or whether BH growth and disc size are both driven independently by another factor, for example, the angular momentum of halo gas: an important parameter that affects BH growth is the gas density in the central regions (localized around the BH), which will be higher for more compact discs that arise when low-angular momentum gas concentrates in the central regions. We note also that violent (major) mergers often cause star bursts and BH growth and result in small, compact stellar discs. For example, Au 4, 11, 28 and 29 all experience a major merger after z = 0.5, and end up with present day-accreted star fractions of about 30 per cent and disc scalelengths of less than 4 kpc.

In order to eliminate the effects of these factors, we re-ran Au 22 unchanged until z = 1, after which time we turned off all AGN feedback (while still allowing for the BH to swallow gas). We term this new simulation Au 22NOAGN. We focus on Au 22 because it has a quiet merger history and a significant amount of AGN feedback. In the top row of Fig. 17, we compare the circularity distributions of the two simulations. There are noticeable differences between them: the disc component is less well defined in Au 22NOAGN, resulting in a D/T ratio 0.27, to be compared to 0.39 in Au 22 (in both cases, we use the conservative definition, i.e. $\epsilon > 0.7$, to belong to the disc). The other disc fraction definition is smaller also in the simulation with no AGN feedback. Clearly, the central bulge is more dominant compared to Au 22. This is reflected in the surface density decomposition in the second row of Fig. 17, in which the central density is visibly higher in the simulation without AGN feedback. Interestingly, the extent of the disc component is greater in the simulation without AGN feedback, which exhibits a scalelength about 1.6 times larger than that of Au 22.



Figure 14. The evolutionary history of a selection of subhaloes and their impact on the disc size and specific angular momentum of halo components of four of the largest discs in the simulation suite. Top row: the evolution of the disc edge, R_{edge} , defined as the radius at which the surface density of the stellar component drops below $1 \text{ M}_{\odot}\text{pc}^{-2}$; second and third row: the evolution of the dot product of the angular momentum of the main halo stellar disc and that of the orbital angular momentum of subhaloes (top) and the distance of the subhaloes to the centre of the main halo (bottom). Points are colour coded according to the total mass of the subhaloes at a given time; fourth row: the evolution of the specific angular momentum of gas (solid lines) and dark matter (dashed lines) in different radial shells; fifth row: the same as the fourth row but for star particles born between $t_{lookback} = 10$ and 12 Gyr (note that the radial shells are different from those shown in the fourth row). These four haloes are clear cases in which a massive ($log_{10}[M/M_{\odot}] > 10$) subhalo inspirals into the main halo and quiescently merges in the disc plane. In particular, it is clear that subhaloes may not be completely aligned with the disc spin axis at distances larger than 100 kpc; however, they gradually torque the disc as their orbit shrinks, which increases the alignment between their orbital angular momentum vector with the spin axis prior to merging. Their effects on the specific angular momentum of the halo and disc are clearly evident in the fourth and fifth row (see the text for details).

The SFHs shown in the third row of Fig. 17 clearly show the effects of AGN feedback on the evolution of both bulge and disc: without AGN feedback, the SFR in the inner disc (R < 5 kpc) peaks at a value of nearly $30 \text{ M}_{\odot} \text{yr}^{-1}$ at around $t_{\text{lookback}} \sim 7$ Gyr, whereas

this is reduced to less than 20 $M_{\odot}yr^{-1}$ in Au 22. In this case, AGN feedback helps to reduce star formation in the inner regions and thus reduces the mass of the central bulge. The other noticeable difference in the SFHs is that the amount of star formation at large



Figure 15. Face-on and edge-on images of the star (top two rows) and gas (bottom two rows) distributions in Au 2 between z = 0.95 and 0.7, during which time a massive subhalo quiescently merges in the disc plane. In the stellar images, colour indicates stellar age, whereas in the gas images, it indicates gas temperature (blue: cold star-forming gas, $T < 2 \times 10^4$ K; green: warm gas, $2 \times 10^4 < T < 5 \times 10^5$ K and red: hot gas, $T > 5 \times 10^5$ K). Velocity vectors are shown in the gas projections. The in-plane trajectory of the subhalo orbit is evident in both the stars and the gas. The radial size of the disc grows noticeably during this time period, and is well correlated with the increase in specific angular momentum of the gas and dark matter in this halo. Note that the warm gas entrained in the wake of the subhalo (e.g. at $t_{lookback} = 7.74$ Gyr) has significant rotation. This indicates that the subhalo has deposited its gas with substantial residual angular momentum around the central galaxy, in addition to (perhaps) spinning up surrounding gas (alternatively, after stripping, it may mix with halo gas, thus increasing its specific angular momentum). Note also the strong non-axisymmetries developed in the stellar component, which may allow angular momentum to be transferred from the subhalo to the pre-existing stars (see Fig. 14).

radii (R > 5 kpc) is enhanced in Au 22NOAGN compared to Au 22. In particular, at $t_{lookback} \sim 5$ Gyr, when AGN activity is at its maximum, there is no star formation in the outer disc. However, during the same time period in Au 22NOAGN, a peak of about $5 \,\mathrm{M_{\odot}yr^{-1}}$ is reached in the outer regions. It is this star formation that likely leads to the larger radial disc scalelength reported in the panels above. The fourth row of Fig. 17 shows the edge-on projection of the gas temperature at $t_{lookback} = 5$ Gyr. The temperature of the halo gas is significantly higher for Au 22 than for Au 22NOAGN: in the latter, there is evidence of gas condensing on to the central galaxy, whereas in the former, halo gas is heated by strong AGN feedback and unable to cool and become star-forming. We thus conclude that strong AGN feedback is able to stifle the growth of the stellar disc. However, this is one of the likely several contributing factors to the

correlation shown in Fig. 16. For example, the angular momentum of gas is linked both to the BH growth and to the radial extent of star formation (see Section 5), and mergers can destroy, reduce or even increase the size of discs and create bursts of both star formation and AGN activity. A full quantitative explanation of the trend shown in Fig. 16 is therefore far from trivial and is beyond the scope of this paper.

5 EVOLUTION AND STELLAR POPULATIONS

In this section, we analyse the stellar mass growth history of the simulations and the resulting observational properties of stellar populations.



Figure 16. Growth in BH mass growth between z = 1 and 0 as a function of the disc radial scalelength at z = 0.

5.1 Star formation histories

In Fig. 18, we present SFHs for all the simulated galaxies. Here we consider all the star particles within 0.1 R_{200} of the main halo at z = 0 and determine the SFH by binning initial stellar mass (before stellar mass-loss occurs) by age into 140 Myr intervals, which is similar to the time resolution of the simulations. A common feature in most of the SFHs is that they peak at around a redshift between z = 2 and 1 ($t_{lookback} \sim 10-8$ Gyr), and gradually decline before reaching a roughly constant SFR of the order of a few solar masses per year. However, there are a variety of SFHs: (1) the peaks vary from about 5 M_☉ yr⁻¹ (Au 25) to more than 30 M_☉ yr⁻¹ (Au 28); (2) many simulated galaxies exhibit bursty SFHs; for example, Au 23 exhibits several sharp peaks between 4 and 10 Gyr lookback time.

We subdivide the total SFHs to obtain SFHs for in situ star particles only. From these curves, it is evident that in the majority of cases accreted star particles are a negligible fraction of the total in the halo at z = 0, typically between 10 per cent and 30 per cent, usually as a result of a major merger that occurred at a time indicated by a burst of star formation (e.g. Au 29). We further subdivide the star particles born in situ into three groups according to their birth radius, $R_{\rm b}$, specifically: $R_{\rm b} < 5$ kpc, $5 < R_{\rm b} < 10$ kpc and $R_{\rm b} > 10$ kpc, where $R_{\rm b}$ is the birth radius. This information reveals two broad classes of SFH: inside-out formation that invariably leads to radially extended discs, particularly in haloes of high specific angular momentum, e.g. Au 2, 3 and 16; and star formation that remains centrally concentrated for most of the evolution, e.g. Au 10, 17 and 18. This leads to the more compact discs among the simulation suite (Fig. 4). In addition to the SFHs, Fig. 18 shows the BH mass growth rate, multiplied by a factor of 2.5×10^3 in order to make it visible on the same scale. The characteristics of the BH growth histories vary widely among the haloes: for example, Au 17 and Au 22 exhibit significant BH growth particularly during the period from $z \sim 1$ to 0.1, whereas Au 16 and Au 25 show almost no BH growth at all. We note that short periods of the BH growth are correlated with bursts of star formation and are, in many cases, caused by merger related activity. Haloes that exhibit long periods of



Figure 17. Comparison between the fiducial run of halo Au 22 (left-hand column) and the re-simulation with AGN feedback turned off for z < 1 (right-hand column). We show the orbital circularity distribution (top row) and the surface density profile of the star particles (second row) at z = 0, the SFHs (third row) and the edge-on projected gas temperature at $t_{lookback} = 5$ Gyr (fourth row). We note that the kinematically defined disc is more prominent in the fiducial run of Au 22, whereas the bulge is larger in the run without AGN feedback. The surface density profile indicates however that the disc scalelength is larger for the run without AGN feedback, in addition to the central surface density being larger. These effects are illustrated in the SFH of the simulations, in which SF is reduced in the outer disc regions during the time of high AGN activity, whereas the central star formation is greatly increased without the presence of AGN feedback.



Figure 18. SFHs for all simulations. The histories are shown for all star particles (black curves) and star particles born *in situ* (grey curves) that are present in the main halo at z = 0. In addition, the star particles born *in situ* are further split according to their birth radius, as indicated in the top-left panel. The BH mass growth rate (green curves) is shown to be multiplied by a factor of 2.5×10^3 .

significant BH growth tend to be those with more centrally concentrated SFHs (and more compact discs, see Section 4.3), both of which are related to the gas density in the central regions. We emphasize that a success of our simulations is the coexistence of massive BH and significant disc components, even after the periods of strong BH feedback. In order to put the SFH of the Auriga galaxies into an observational context, in Fig. 19, we calculate the SFR averaged over a period of 0.5 Gyr at z = 3, 2, 1 and 0, and compare these values with observed relations of SFR as a function of stellar mass. At all redshifts, particularly z > 0, the slope of the simulated galaxies matches well at least one set of observations: at z = 3, the slope is



Figure 19. The SFR as a function stellar mass for all simulated galaxies at a series of redshifts. In each panel, we also show observationally derived scalings for late-type galaxies (Daddi et al. 2007; Elbaz et al. 2007, 2011; Magdis et al. 2010; Karim et al. 2011). The Milky Way is represented by the green star in the right-hand panel. Observations from the SDSS MPA-JHU DR7 catalogue are shown as the blue cloud and red sequence according to the classification described in Marinacci et al. (2014a).

consistent with the slope derived from Lyman break galaxies obtained by Magdis et al. (2010), and at z = 2, the slope is consistent with the observations of Daddi et al. (2007), although steeper than the observations of Karim et al. (2011). The peak of star formation for most galaxies occurs between z = 1 and 2, consistent with Fig. 18. The magnitude of star formation in the simulated galaxies agrees well with the observations from z = 1 onwards, but at earlier times, the SFR is about a factor of 2, i.e. too low compared with observations (see also Aumer et al. 2013). In the right-hand panel of Fig. 19, we compare the z = 0 SFR of the simulated galaxies with nearby galaxies taken from SDSS MPA-JHU DR76, divided into blue and red sequences (as in Scannapieco et al. 2012; Marinacci et al. 2014a). The simulations lie in the blue cloud region with present-day SFRs between ~ 1 and $\sim 10 \text{ M}_{\odot} \text{ yr}^{-1}$, and are clustered around the value obtained for the Milky Way by Leitner & Kravtsov (2011).

5.2 Stellar properties

The SFH, together with the stellar evolution assumed by the simulations, determines the properties of the z = 0 stellar population, which we here compare to a variety of observations. In the left-hand panel of Fig. 20, we show the simulated galaxies in g - r colour versus *r*-magnitude space, which are both shaped by the integrated SFH. In the background, we show contours of blue and red nearby galaxies taken from SDSS MPA-JHU DR7. This verifies that the simulated galaxies are blue in colour, i.e. they are not part of the red sequence shown in the right-hand panel of Fig. 19.

Further implications of the late-time star formation necessary to maintain the galaxies in the blue cloud region populated by late-type spiral galaxies can be found in the mass-weighted mean stellar age of the star particles, shown in the middle panel of Fig. 20. The distribution of simulated galaxies is centred around a mean stellar age of \sim 5–7 Gyr, which is roughly the age range expected for galaxies like the Milky Way from the observations of Gallazzi et al. (2005), although the scatter from measurement uncertainties is large and easily contains that of the simulated galaxies, represented as the decimal logarithm of the mass-weighted mean iron abundance relative to the solar, compared to the observational results of Gallazzi et al. (2005). It is clear that the simulations reproduce the observed

⁶ http://www.mpa-garching.mpg.de/SDSS/DR7/

metal content for galaxies like the Milky Way. The SFHs of our simulated galaxies are thus able to broadly reproduce a variety of stellar properties.

5.3 Mass evolution

In order to see how our simulated galaxies grow in stellar mass, we show, in Fig. 21, the stellar mass-halo mass relation at redshifts 3, 2, 1 and 0. We define the stellar mass to be the sum over all star particles within 0.1 R_{200} and plot this mass against the dark matter mass contained within R_{200} . The simulated galaxies are then compared with the semi-empirically derived stellar to halo mass relation of Moster et al. (2013), who used abundance matching from simulated DMO haloes constrained to match the observed stellar mass function. At z = 0, most of the Auriga galaxies lie above this relation but within the 0.15 dex scatter assumed by Moster et al. (2013). A few have stellar masses above the 1σ scatter boundary. At earlier redshifts (first and second panels of Fig. 21), we note that the haloes evolve almost parallel to the Moster et al. (2013) relation; however, they lie noticeably above the relation at z = 3, which indicates an excess of early star formation at even earlier epochs. Although the AGN feedback in these simulations plays a role in suppressing early star formation, its effectiveness varies, as noted above, and in some cases is insufficient. This may indicate the need for additional sources of feedback such as early stellar feedback (e.g. Aumer et al. 2013; Stinson et al. 2013a; Hopkins et al. 2014; Wang et al. 2015). Stinson et al. (2013a) showed that early stellar feedback reduced the amount of early star formation in the central regions by heating gas and extending its distribution, which helped to prevent the formation of compact discs. The inclusion of such feedback in our model may help to bring our simulations into better agreement with abundance matching predictions, which will be investigated in future work.

Haloes that grow quiescently, including the largest discs (highlighted), appear to evolve smoothly along the relation, whereas those that experience major mergers can evolve more sporadically. Such discontinuous behaviour violates the assumptions made in abundance matching at constant galaxy comoving number density and the subsequent derivation of progenitor-descendent relations (see Torrey et al. 2016). This may become especially relevant at higher redshifts, when mergers are more frequent and abundance matching results more uncertain than for z = 0.



Figure 20. Left-hand panel: g - r colour plotted as a function of *r*-band absolute magnitude plotted over the same blue/red sequence of SDSS MPA-JHU DR7 galaxies shown in Fig. 19. Middle and right-hand panels: the mean stellar age plotted as a function of stellar mass (left), and the mass-metallicity relation (right) of all simulated galaxies. The observational relations presented in Gallazzi et al. (2005) are shown. The simulations are clustered about the mean (solid blue line) and lie within the scatter (blue shaded regions) for both relations.



Figure 21. The stellar mass–halo mass relation of the simulated galaxies at z = 3 (first panel), 2 (second panel), 1 (third panel) and 0 (fourth panel). The mean and scatter of the semi-empirical relations derived in Moster, Naab & White (2013) are indicated by the solid blue line and the shaded region, respectively. At z = 3, most haloes lie well above the relation, and tend to evolve in a direction slightly shallower than the relation such that they enter the region of 0.2 dex scatter (blue shaded regions) at around z = 1, and lie mostly within the scatter at z = 0. Some haloes have slightly too much stellar mass relative to the present-day abundance matching estimate, and it is interesting to note that these haloes tend to host the discs with the smallest scalelengths (red squares), whereas those that host the most radially extended discs scatter around the mean relation (blue triangles).

For a more detailed analysis of the build-up of the galaxy, we follow the growth of stellar mass in the inner and outer regions of the simulated galaxies in Fig. 22. For comparison, we show also the evolution of the corresponding quantities presented in Patel et al. (2013), who analysed the structural parameters of a set of star-forming galaxies, observed with Hubble Space Telescope Wide Field Camera 3 as part of the CANDELS survey (van der Wel et al. 2012). They assume that every galaxy remains close to the ridge of the star-forming main sequence as it grows, so that starforming galaxies of given present-day stellar mass formed from starforming galaxies of a well-defined and smaller stellar mass at earlier times. This allows them to link a sample of low-redshift disc galaxies from SDSS to representative sets of 'progenitors' at a sequence of earlier redshifts back to $z \sim 1.3$. In order to facilitate a fair comparison, we define the inner and outer regions in the same way as in the observed sample: inside and outside R = 2 kpc, which are proxies for the bulge and disc components. The simulation means of the total mass and the mass in the two regions evolve as observed if the observations are renormalized by a factor of 1.5, particularly the inner region. A renormalization of this type is expected because the results presented in Patel et al. (2013) are for galaxies selected to be around the stellar mass $10^{10.5} \sim 3 \times 10^{10}$ M_{\odot}, which is

about half the mass of our simulated galaxy average. After this renormalization, the most notable difference between the simulated galaxies and the observations is found in the outer region, which begins growing in mass earlier and continues growing later than observationally inferred. These discrepancies may be because the haloes in the Auriga simulation sample are selected to be isolated, and therefore may constitute a sample biased towards prominent discs that experience prolonged disc formation. However, we note that the assumption that all galaxies grow smoothly along the ridge of the star-forming main sequence cannot be precisely correct and is violated by mergers that are particularly frequent at early times, so that the observationally derived curves do not necessarily reflect the true mass growth of late-type star-forming galaxies.

6 RESOLUTION STUDY

In this section, we present a resolution study of our simulations. As discussed in the Introduction, convergence of galaxy properties across different levels of resolution is difficult to achieve in simulations of galaxy formation. In Marinacci et al. (2014a), one of the Aquarius simulations was tested across three levels of resolution and good convergence was obtained. The highest resolution level in



Figure 22. The growth history of the total stellar mass (black dashed curve) and that of the inner (red dashed curve) and outer (blue dashed curve) regions of the mass distribution, averaged over the simulation sample. The 1σ dispersion is indicated by the grey shaded region. The solid curves show the observationally inferred growth histories from Patel et al. (2013), multiplied by a factor of 1.5 in order to correspond to a final stellar mass similar to that of the Milky Way.

Table 2. Table of numerical resolution parameters at z = 0. The columns are: (1) resolution level; (2) dark matter particle mass; (3) typical baryonic element mass; (4) softening length of collisionless particles.

Resolution level	$\frac{m_{\rm DM}}{({\rm M_{\bigodot}})}$	$\frac{m_{\rm b}}{({\rm M}_{\bigodot})}$	$\frac{\epsilon}{(\text{pc})}$
4	3×10^{5}	5×10^{4}	369
5	2×10^{6}	4×10^5	738
3	4×10^4	6×10^3	184

that study is equivalent to that of the 30 simulations we have presented in this paper (known as level 4 in Aquarius nomenclature). This corresponds to a few million star particles in the main halo at z = 0. In this paper, we attain a new resolution level (level 3) for three of our haloes, which is a factor of 8 and 2 better in mass and spatial resolution, respectively. In order to assess convergence, we here compare some basic quantities for these three simulations across three levels of resolution (see Table 2), which span a mass (spatial) resolution range of 64 (4) and evaluate their convergence.

In Fig. 23, we present the surface density profiles (top), the orbital circularity distribution (middle) and the SFHs (bottom) for simulations Au 6, Au 16 and Au 24. We find that each halo is generally well converged across the three levels of resolution. In particular, the circularity distributions and the inferred disc-total mass ratios are very similar, which indicates that the disc and bulge kinematic structure do not change significantly. The surface density profiles do show some shifts; however, in the case of Au 6, the slope of the profile becomes slightly steeper at the highest resolution level than in the others, although those of Au 16 and Au 24 appear relatively stable. The SFHs show a weak trend towards increased star formation at higher resolution, although the SFH of Au 24 is barely changed. Despite this tendency, the SFH retains its shape in all haloes. The largest and most significant change with resolution is most easily seen in the circular velocity curves of the haloes, which we present in the top panels of Fig. 24. At the highest level of resolution, these curves become peaked near the centre, which reflects a more compact core. We investigated the origin of the relative excess of stellar density in the galaxy centre in the level 3 run: we examined the birth positions and ages of all star particles that are within 5 kpc of the galaxy centre at z = 0. We find that most of the excess originates from star particles born in the central regions but over a range of times. The excess apparently reflects variations in the highly nonlinear BH accretion and feedback loops that help regulate central star formation (as postulated by Marinacci et al. 2014a). It is notoriously difficult to obtain convergence for these processes.

To compare the vertical disc structure across resolution, we calculate the radial profile of the root mean square height for disc star particles, which, in this resolution study, is preferable to the vertical scaleheight owing to the poor particle sampling, and therefore poor density profile fitting, in the low-resolution level 5 simulations. In the bottom panels of Fig. 24, we show the radial profile of the root mean square height of the stellar disc component for all star particles (dotted lines) and for star particles younger than 3 Gyr (solid lines). There appears to be tentative indications in the total stellar disc population in Au 16, and to a lesser extent the young disc stars, that discs become vertically thinner with increasing resolution, which one may naïvely interpret as the softening length setting a lower limit on the disc scaleheight. However, this trend is not seen in Au 6 nor Au 24, which both show very similar height profiles despite the reduction in softening length by a factor of 4 from level 5 to level 3, which indicates that overall, the vertical disc structure is well converged.

To investigate further the concern that the reduction in softening lengths leads to thinner discs, we re-run simulation Au 6 with 10 times lower softening lengths (labelled Au 6lowsoft), and show the radial profile of the root mean square height of all stars and young stars in Fig. 25, in addition to that of the fiducial Au 6 simulation. The difference in vertical disc thickness between the two simulations is negligible for both young stars and all stars at all radii, which clearly demonstrates that lower softening lengths do not lead to thinner discs. Based on these results, we caution that the softening length ought not to be referred to as a resolution limit, given that gravity is not simply turned off below the softening length-scale.

We conclude from this study that our simulations are generally well converged across three resolution levels, the last of which is one level higher than probed in Marinacci et al. (2014a). We stress that this level of convergence is extremely difficult to achieve in simulations of galaxy formation, and it suggests that our models are numerically well posed in the sense that the evolution of the simulated galaxies depends on physical parameters only, not on numerical resolution.

7 DISCUSSION AND CONCLUSIONS

In this paper, we have introduced a suite of cosmological simulations of the formation of galaxies in isolated Milky Way-mass haloes using the zoom-in technique. The simulation code follows many aspects of galaxy formation, including BH accretion and feedback, stellar feedback, stellar evolution, chemical evolution, metallicitydependent cooling, star formation and magnetic fields, and has been shown to produce realistic galaxy populations in large-scale cosmological boxes (Vogelsberger et al. 2013; Genel et al. 2014). The most novel aspects of the simulations, with respect to previous studies,



Figure 23. Stellar surface density profiles (top row), orbital circularity distribution (middle row) and the SFH of haloes Au 6 (first column), Au 16 (middle column) and Au 24 (third column) at three different resolution levels.

are the large simulation sample, high resolution, the inclusion of magnetic fields that are seeded, grown and evolved in a fully cosmological context, and the BH model that has been used in only one simulation set previous to this study (Marinacci et al. 2014a). The suite comprises 30 simulations with typical baryonic mass resolution of around $5 \times 10^4 \text{ M}_{\odot}$, three of which have higher resolution counterparts with eight times better mass resolution. The sample size, resolution and galaxy formation model make these simulations some of the most advanced and comprehensive found in the literature.

We analysed the properties of the stellar components of these simulations, and found that they lie on the expected stellar mass–halo mass relation, and are consistent with other key observables such as flat rotation curves, the mass–metallicity relation and present-day SFRs. The simulated galaxies are, on average, slightly too massive in the stellar component, particularly at earlier times such as z = 3. This may indicate the need for early stellar feedback (see e.g. Aumer et al. 2013; Stinson et al. 2013a). Such feedback may bring down the stellar masses of our simulations and reduce the number of compact galaxies (see Fig. 5), which we will investigate in future work.



Figure 24. As Fig. 23, but for the radial profiles of the circular velocity (top row) and the root mean square height (bottom row) for all star particles (dotted lines) and for star particles younger than 3 Gyr (solid lines).



Figure 25. The radial profile of the root mean square height of simulation Au 6 and a re-run of the same halo with 10 times lower softening lengths.

The mass distributions of our simulated galaxies are realistic and produce rotationally supported discs: most of our simulations have flat rotation curves, with velocities that match the Tully–Fisher relation for Milky Way-mass galaxies. We note that in the past, it has proven to be difficult to reproduce flat circular velocity curves for galaxy discs in haloes in the virial mass range $1-2 \times 10^{12} M_{\odot}$ (see for example, Stinson et al. 2010; Mollitor, Nezri & Teyssier 2015; Wang et al. 2015), although a variety of recent models have achieved some success (Aumer et al. 2015a; Colin et al. 2016a). The circularity distributions indicate that at least two-thirds of the simulations have well-defined, rotationally supported disc components, with disc-total mass ratios of up to 0.6–0.7 for the most disc-dominated simulations. These are among the highest disc-total mass ratios in the literature, along with Aumer et al. (2013).

The vertical structure of our simulated discs appears to be somewhat thicker than expected from observations in the Milky Way, which may be related to energy from stellar feedback that acts to puff up the gas disc (see Marinacci et al. 2016). Roškar et al. (2014) reported a similar conclusion, although their feedback recipe included radiation feedback that destroyed the morphology of their disc in addition to thickening it. However, the inner discs of our simulations show some consistency with the observations of external galaxies. The SFR-stellar mass relation for the simulations is lower than observed by about a factor of 2 for z = 2-3, but similar to observations for z = 0-1. The simulations lie on a slope consistent with observed scaling relations for z = 1-3. The SFRs tend to peak at around redshift 1–2, followed by a steady decline until reaching a present-day SFR of the order of a few solar masses per year. The resulting present-day metallicities, mean stellar ages and colours are consistent with the observations of late-type, star-forming galaxies.

The radial distribution of star formation may be broadly categorized into either centrally concentrated or radially extended, inside-out formation. This variety of SFH in the suite translates into a wide range of disc sizes (with scalelengths that range from about 2 to 11 kpc), a diversity that grows in time from a smaller range of early-time disc sizes that were consistent with observations. We investigated the cause of this diversity and found that disc size correlates well with basic measures of halo spin, in agreement with theoretical expectations. We identified gas-rich quiescent mergers as a prominent mechanism by which the halo dark matter and gas acquire a high degree of specific angular momentum, which leads to high-angular momentum star-forming material condensing around the disc, and therefore to inside-out star formation and large disc scalelengths. In addition, a fraction of the orbital angular momentum of the satellite is transferred to the pre-existing stellar disc. In contrast, compact discs typically have no such quiescent merger and a low degree of halo angular momentum.

We investigated the effect of AGN on disc size and found that strong AGN feedback could reduce the size of the disc by injecting thermal energy into the halo and preventing the cooling and condensation of new star-forming gas around the disc. However, in terms of the disc size, this effect is mild and we conclude that the dominant effect is the addition of angular momentum from infalling gas and stars. The most important effect of AGN feedback is to suppress central star formation, which is particularly important in haloes that have low-angular momentum gas that leads to high gas densities in the galaxy centre. In these cases, the high gas density leads to strong AGN feedback that regulates star formation and prevents the formation of overly massive bulges. Thus, AGN feedback can play an important role in galaxies of Milky Way mass.

Overall, we believe that our simulations represent one of the best currently available models for the formation of galaxies like the Milky Way. The high fidelity of our model is supported by the strong convergence of many galaxy properties across three levels of resolution (4 if one extrapolates from Marinacci et al. 2014a), without the need to re-tune parameters. As pointed out in Marinacci et al. (2014a), this is a desirable trait that indicates that the results of the simulations reflect their physical assumptions rather than their numerical parameters. The simulations do not rely on resolution-dependent star formation density thresholds, high-star formation density thresholds (Governato et al. 2010; Agertz et al. 2011) or high resolution (Kaufmann et al. 2007) to curtail star formation and obtain physically meaningful results.

In this paper, we have presented an overview of the Auriga simulation suite, with a focus on the present properties and formation history of the stellar disc. We note that there are other studies that have already made use of a subset of these simulations. In particular, an analysis of dynamical heating mechanisms of stellar discs is presented in Grand et al. (2016a), and a study of the origin of disc warps is presented in Gómez et al. (2017) (see also Gómez et al. 2016). There are also studies that provide predictions that are directly comparable to observations: chemo-dynamical features associated with spiral structure are studied in Grand et al. (2016b), and an analysis of the stellar halo metal content is presented in Monachesi et al. (2016). Concerning the complete Auriga suite, the properties of the H I gas discs are presented in Marinacci et al. (2016). In the near future, we will present studies concerned with magnetic fields (Pakmor et al., in preparation), satellites (Simpson et al., in preparation), *ex situ* stellar discs (Gómez et al., in preparation), stellar halo properties (Monachesi et al., in preparation), the circumgalactic medium (Nelson et al., in preparation) and X-ray haloes (Campbell et al., in preparation). Together, these papers will provide a comprehensive picture of the Auriga simulations.

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APPENDIX A: PARENT BOX HALO IDENTIFICATION

The Auriga sample were selected from the DMO version of the EA-GLE Ref-L100N1504 cosmological volume (Schaye et al. 2015). In Table A1, we list the ID numbers of the Auriga simulations and provide a corresponding identification number for these haloes in the parent DMO and in the full hydrodynamic EAGLE cosmological box simulations.

The positions and properties of the corresponding central galaxies in the EAGLE Ref-L100N1504 simulation can be obtained by making an sqL query to the public Eagle Database, which is described in McAlpine et al. (2016). For example, to find the EAGLE counterpart to Au 3 in the Eagle data base, we would take the group number, 1449, from Table A1, and execute the following SQL query, to obtain the location and properties of the central galaxy associated with the FOF group at z = 0:

select * from ref10100n1504_subhalo
where snapnum=28 and subgroupnumber=0
and groupnumber = 1449

Amongst the properties this query returns are the Cartesian coordinates for the gravitational potential minimum of the central galaxy, which is located for Au 3 at $(x, y, z) = (10.204\,818, 98.302\,05, 72.666\,44)$ Mpc.

Table A1. Table of halo ID numbers at redshift zero. The left-hand column lists the Auriga IDs referred to in this paper. The middle and righthand columns list the corresponding FOF halo IDs in the parent EAGLE DMO cosmological volume and its hydrodynamical counterpart.

Auriga ID	EAGLE DMO	EAGLE REF
	group number	group number
1	931	949
2	942	897
3	1266	1449
4	1018	954
5	1468	1446
6	1574	1619
7	1257	1359
8	1606	1522
9	1495	1763
10	1679	1649
11	1101	1101
12	1538	1547
13	1355	1379
14	1212	1173
15	1436	1457
16	1231	1143
17	1689	1566
18	844	848
19	1432	1467
20	1164	1152
21	1110	983
22	1632	1692
23	1168	1285
24	938	1065
25	1440	1470
26	1026	1099
27	998	1071
28	1173	1224
29	997	1019
30	1429	1481

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