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Batako, A Dynamic FEA analysis of the Super Lightweight External cryogenic fuel tank (SLWT) made of Aluminium alloy 2195 - graphene nano composite for launch vehicle aerospace application. Journal of Composites Science. ISSN 2504-477X (Accepted)

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# Dynamic FEA analysis of the Super Lightweight External cryogenic fuel tank (SLWT) made of Aluminium alloy 2195 - graphene nano composite for launch vehicle aerospace application

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Abstract: This research presents a comprehensive dynamic finite element analysis (FEA) of a cryo-11 genic fuel tank made from an innovative aluminium/lithium graphene nano-composite material, 12 assessing its suitability for aerospace launch vehicles carrying cryogenic hydrogen and oxygen. The 13 study focuses on the effects of light-weighting, utilizing 0.5 wt.% reinforced graphene in the AL-14 2195 matrix, a material poised to revolutionize the aerospace industry. Objectives include develop-15 ing a digital twin of the fuel tank, CAD modeling to aerospace standards, and conducting ANSYS 16 simulations under launch conditions to evaluate stress, strain, and deformation. Numerical results 17 reveal a significant weight reduction of approximately 19,420 kg and a notable maximum stress 18 reduction of 1.3% compared to traditional AL-2195 alloy tanks. The novelty of this research lies in 19 its pioneering analysis of aluminium/lithium-graphene composites for light-weighting in cryogenic 20 fuel tanks under space launch conditions. Conclusions affirm the composite's viability, advocating 21 for the development of lighter yet robust aerospace structures and fostering innovation in spacecraft 22 design and materials science. 23

#### 1. Introduction

As humanity embarks on ambitious missions to explore the uncharted territories of 25 Mars and the Moon, the demand for advanced materials capable of enhancing spacecraft 26 performance has come to the forefront of space exploration engineering. Central to this 27 endeavour is the imperative to increase payload capacity, a pivotal factor in enabling sus-28 tained human presence beyond Earth's orbit. In response to this challenge, researchers 29 have long relied on aluminium alloys for their exceptional combination of low density 30 and mechanical properties, making them the backbone of space exploration engineering 31 [1-7]. 32

The External Tank (ET) of the Space Shuttle, a crucial component, underwent signif-33 icant evolutionary changes throughout the progress of space exploration. Starting with 34 the standard-weight tank, it progressed to the lightweight tank (LWT) and ultimately to 35 the super lightweight tank (SLWT). The SLWT, first used on STS-91 in 1998, marked a 36 major technological advancement. It was constructed using the 2195 aluminium-lithium 37 alloy, which was both 40% stronger and 10% less dense than the previously used material. 38 This change resulted in a substantial weight reduction of 3,400 kg (7,500 lb), enhancing 39 the Shuttle's performance and payload capacity [8-13]. 40

However, the widespread adoption of aluminium-lithium (Al-Li) alloys has been 41 hindered by historical concerns surrounding anisotropic properties, poor toughness, and 42 thermal stability issues. In this context, aluminium alloy 2195 (AA 2195), characterized by 43 its composition of Al-4.0Cu-1Li-0.4Mg-0.4Ag-0.1Zr, has emerged as a third-generation al-44 loy with significant potential for cryogenic tankage applications in space launch systems 45 (SLS) and space transportation systems (STS). NASA's successful utilization of AA 2195 46 in super lightweight cryogenic tanks for space shuttles underscores its pivotal role in ad-47 vancing space exploration [14]. Despite the advancements achieved with aluminium al-48 loys, the emergence of graphene-based composite materials presents a new era of possi-49 bilities in lightweighting strategies for aerospace applications. Graphene, renowned for 50 its exceptional strength, conductivity, and lightweight properties, serves as an effective 51

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reinforcing agent in metal matrix composites (MMCs), offering superior mechanical performance and durability [15]. 53

In the context of cryogenic storage systems for aerospace applications, the liquid ox-54 ygen (LOX) and liquid hydrogen (LH2) tanks are subjected to intricate physical forces and 55 thermal conditions that must be meticulously managed to ensure optimal performance 56 and safety in the newly considered composite material for the tanks [10-15]. Gravitational 57 and hydrostatic forces play a crucial role in determining the behavior and distribution of 58 the cryogenic fluids within these tanks made of novel graphene reinforced composite ma-59 terial. Gravitational forces affect the overall pressure exerted by the liquid column, while 60 hydrostatic forces influence the pressure distribution at various depths, impacting the 61 structural integrity of the tank and the stability of the stored fluids [16]. 62

In addition to the mechanical forces, the thermal dynamics within LOX and LH<sub>2</sub> 63 tanks are of vital importance. These tanks must maintain extremely low temperatures to 64 keep the oxygen and hydrogen in their liquid states, typically around -183°C for LOX and 65 -253°C for LH2. The thermal management in the fuel tanks are effectively achieved by con-66 trolling heat transfer mechanisms such as conduction, convection, and radiation to mini-67 mize heat ingress from the external environment. This is often achieved through usage of 68 efficient structural materials, advanced insulation techniques and active cooling systems 69 to prevent vaporization and potential pressure build-up within the tanks [12-15]. 70

The interplay between these forces and thermal dynamics necessitates a comprehensive understanding of cryogenic fluid behavior under varying conditions. Engineers must account for factors such as stratification, thermal gradients, and fluid sloshing, which can affect the performance and safety of the propulsion system [16]. Consequently, the design and operation of LOX and LH<sub>2</sub> tanks involve sophisticated modelling and simulation techniques to predict and mitigate potential issues, ensuring reliable and efficient storage and transfer of these critical propellants in aerospace missions [17].

Along with the thermal dynamics and forces involved on the tanks the other primary 78 challenge was the tank's weight. Initially, the EFT was designed as a standard-weight tank, 79 but the need to enhance the Shuttle's payload capacity led to the development of the Light-80 weight Tank (LWT) and subsequently the Super Lightweight Tank (SLWT). The SLWT 81 represented a significant technological advancement, utilizing the 2195 aluminium-lith-82 ium alloy, which was both stronger and less dense than the previous materials used. The 83 use of alternative lightweight composite materials for aerospace launch vehicle external 84 fuel tank structural components. The focus is on developing graphene-reinforced Alumin-85 ium metal matrix composites and studying their metallurgical and mechanical properties 86 for potential use in space exploration applications, particularly in the external fuel tank 87 structural applications of launch vehicles [8]. 88

Graphene, characterized by its distinctive two-dimensional arrangement of carbon 89 atoms forming a hexagonal lattice, has revolutionized multiple scientific fields [9-12]. This 90 material's exceptional blend of attributes, including outstanding electrical conductivity, 91 remarkable mechanical strength, and notable flexibility, has positioned it at the forefront 92 of research, particularly in aerospace engineering [13]. Its unique properties offer signifi-93 cant potential for innovation and advancement in aerospace and space exploration sector 94 [21]. Nonlinear behaviour in aerospace structures has attracted considerable interest 95 among researchers. When exposed to diverse loads and conditions, these structures fre-96 quently display behaviours that diverge from standard linear elastic responses [22]. Such 97 nonlinearities may stem from the materials used, the structural geometry, or a mix of both 98 factors. The Super Lightweight External Tank (SLWT), with its complex design and dy-99 namic operational environment, also exhibits these nonlinear behaviours. 100

The Super Lightweight External Tank (SLWT) demonstrates a variety of nonlinear 101 responses. Previous research [23-25] thoroughly explore this behaviour, which include bifurcation-type buckling, short-wavelength nonlinear bending, and nonlinear collapse. 103 Understanding each of these responses is vital, particularly in evaluating the SLWT's functionality across different stages of a Shuttle mission. This research also highlights the necessity of identifying and managing these nonlinearities to maintain the structural 106

integrity and safety of the SLWT by employing the composite materials properties as the 107 tank material property [26]. Finite-element models are crucial in forecasting and compre-108 hending the dynamic and nonlinear behaviours of the Super Lightweight External Tank 109 (SLWT). The significance of employing high-fidelity finite-element models for precise de-110 piction of the SLWT's reactions are found to be important. These models provide detailed 111 insights into the SLWT's behaviours, allowing for simulations under various scenarios and 112 the prediction of possible challenges [27]. 113

In the pursuit of more efficient and cost-effective aerospace launch vehicles, the ex-114ploration of lightweight materials has emerged as a pivotal area of research and develop-115 ment. The drive towards lightweighting not only enhances payload capacity and fuel ef-116 ficiency but also mitigates structural stresses during launch and operation. This impera-117 tive has led researchers to investigate alternate super lightweight materials capable of 118 withstanding the extreme conditions of space exploration. This paper delves into the ex-119 ploration of graphene-based composite materials as a means of achieving lightweighting 120 objectives in aerospace launch vehicles. Through a comprehensive design validation pro-121 cess at dynamic levels, the study aims to assess the feasibility and efficacy of these mate-122 rials in enhancing the performance and resilience of launch vehicle structures. By investi-123 gating the mechanical properties and structural behaviour of graphene-based composites 124 under launch conditions, this research endeavours to contribute to the advancement of 125 lightweighting strategies in aerospace engineering. 126

The subsequent sections will delve into the methodology employed for material char-127 acterization, CAD modelling conforming to aerospace standards, and dynamic finite ele-128 ment analysis (FEA) to evaluate the performance of graphene-based composite materials. 129 Furthermore, the paper will discuss the implications of these findings for the future design 130 and development of aerospace launch vehicles, emphasizing the potential for graphene 131 composites to redefine the standards of lightweighting in space exploration.

# 2. Functionality of the tank components and Methodology

Figure 1 presents a structured methodology for a comparative analysis of the dy-134 namic behaviour of a cryogenic fuel tank assembly constructed from AL 2195 and an AL 135 2195-Graphene composite. This study is conducted under conditions typical of aerospace 136 operations. The approach encompasses the use of our experimental data gathered for the 137 AL 2195-graphene composite, comprehensive modelling, simulation, and validation pro-138 cesses. A multi-faceted quantitative strategy is employed to reinforce the reliability and 139 precision of the validations carried out. This method integrates numerical data derived 140 from simulations with empirical evidence gathered from our previous technical docu-141 ments and experimental studies related to the Al-2195 graphene composite and pure Al 142 2195 material. This technique facilitates a comprehensive statistical examination of the 143 material characteristics and the performance of the fuel tanks in simulated scenarios. 144

Each component of the cryogenic fuel tank assembly (LOX tank, Intertank, and LH2 145 tank) was modelled using SolidWorks 2023 as shown in figure 2. The models were con-146 structed to exact specifications based on the design parameters obtained from the NASA 147 technical report (Lockheed Martin Space System, 2008) and reflected the precise geometry 148 required for FEA. The individual parts will be assembled in SolidWorks to represent the 149 complete cryogenic fuel tank structure as it would be configured in a launch vehicle. The 150 fuel tank assembly ensured that all parts are correctly aligned and interfaced. Before pro-151 ceeding to the simulation phase, the SolidWorks model was validated by comparing it 152 with existing designs and by conducting preliminary checks for any geometrical incon-153 sistencies. A critical phase involved substituting the standard alloys with the innovative 154 Al 2195-Graphene Composite material. This change was vital to examine the improved 155 attributes offered by the composite. By transferring the model into ANSYS 2023, emphasis 156 was placed on the quality of the mesh and the boundary conditions, replicating real-life 157 situations such as gravitational and hydrostatic forces, along with the thermal dynamics 158 of LOX and LH<sub>2</sub> with the dimensions and scale of the model mentioned in table 1. 159

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SLWT Technical Specification	Full Scale Model (1:1)
Length	153.8 ft (46.9 m)
Diameter	27.6 ft (8.4 m)

The LOX tank depicted in Figures 3a, representing the Super Lightweight Fuel Tank 161 (SLWT) in Computer-Aided Design (CAD) modelling, is positioned atop the External 162 Tank (ET). It adopts an ogive shape aimed at minimizing aerodynamic drag and aero ther-163 modynamic heating [28]. This ogive nose section comprises a flat removable cover plate 164 and a nose cone, housing a detachable conical assembly that acts as an aerodynamic fair-165 ing for propulsion and electrical system components [28-31]. The leading portion of the 166 nose cone serves as a cast aluminium lightning rod. The LOX tank's capacity is measured 167 at 19,744 cubic feet (559.1 m3) at 22 psi (150 kPa) and -297 °F (90.4 K; -182.8 °C) (cryogenic), 168 according to Ferrick et al. (2008). The tank feeds into a 17 in (430 mm) diameter feed line 169 that conveys the liquid oxygen through the Intertank, then outside the ET to the aft right-170 hand ET/orbiter disconnect umbilical [32]. The 17 in (430 mm) diameter feed line permits 171 liquid oxygen to flow at approximately 2,787 lb./s (75,800 kg/min) with the RS-25s operat-172 ing at 104% or permits a maximum flow of 17,592 US gal/min (1.1099 m<sup>3</sup>/s) [33-35]. 173

Table 2. LOX Tank Technical Specification.

LOX Technical Specification	Full Scale Model (1:1)		
Length	54.6 ft (16.6m)		
Diameter	27.6 ft ( 8.4 m)		
Operation Pressure	34.7 – 36.7 Psi (absolute)		

The Intertank in Figure 3b is the structural connection between the LOX and LH<sub>2</sub> tanks of the Su-175 per lightweight (SLWT) external tank. Its primary functions include receiving and distributing all 176 thrust loads from the Solid Rocket Boosters (SRBs) and transferring loads between the tanks. The 177 two SRB forward attach fittings, located 180° apart on the Intertank structure, are critical for load 178 management [36]. A beam extends across the Intertank structure and is mechanically fastened to 179 these attach fittings. During Solid Rocket boosters (SRB) firing, this beam flexes under high stress 180 loads, transferring these loads to the fittings (Wingate, 2012). Adjacent to the SRB attach fittings is 181 a major ring frame. The loads from the fittings are transferred to this frame, which then distributes 182 the tangential loads to the Intertank skin. 183



Figure 1. Process Flow Chart.



Figure 2. CAD model of SLWT of Launch Vehicle Scale 1:1.

The thrust panels of the Intertank, two panels of its skin, distribute the concentrated 188 axial SRB thrust loads to the LOX and LH<sub>2</sub> tanks and to adjacent Intertank skin panels, 189 which are made up of six stringer-stiffened panels [37-41]. These structural components 190 are crucial for maintaining the integrity of the Intertank under the extreme conditions of 191 space launch. 192

Additionally, the Intertank functions as a protective compartment for housing oper-193ational instrumentation, which is vital for the successful operation of the Space Shuttle194[42]. The cryogenic moisture analysis of materials used in areas like the Intertank flange195is also an essential aspect of ensuring the safety and functionality of the ET (Nasa & Asrc196Aerospace Corp., 2018). Table 3 shows the Intertank Technical Specification.197

Table 2. Intertank Technical Specification.

Intertank Technical Specification	Full Scale Model (1:1)
Length	22.6 ft (6.9m)
Diameter	27.6 ft (8.4 m)

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**Figure 3.** CAD model, Cross-Sectional View and Render Sectional View of (a) Liquid Oxygen Tank [LO<sub>x</sub>], (b) Intertank and (c) Liquid hydrogen Tank [LH<sub>2</sub>] – Scale 1:1.

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The LH<sub>2</sub> tank, as depicted in Figures 3c, forms the lower section of the Super light-202 weight (SLWT) external tank and is a pivotal element in the shuttle's propulsion mecha-203 nism. This tank, composed of four cylindrical barrel sections, a forward dome, and an aft 204dome, plays a vital role in maintaining the structural integrity of the SLWT [43]. These 205 barrel sections are interconnected by five major ring frames, each essential in managing 206 various loads. The forward dome-to-barrel frame is particularly significant, as it distrib-207 utes loads of 3-4 MN (meganewtons) from the Intertank structure and acts as the connect-208 ing flange between the LH<sub>2</sub> tank and the Intertank [44]. The rear major ring frame is engi-209 neered to handle orbiter-induced loads of 2-3 MN from the rear orbiter support struts and 210 SRB-induced loads of 4-5 MN from the aft SRB support struts, underscoring the tank's 211 crucial role in handling the complex load dynamics during shuttle missions [45]. The other 212 three ring frames are responsible for distributing orbiter thrust loads of 2-3 MN and LOX 213 feedline support loads of 1-2 MN, demonstrating the sophisticated engineering involved 214 in space missions [46]. 215

The LH<sub>2</sub> tank's volume is a substantial 53,488 cubic feet (1,514.6 m<sup>3</sup>) at 29.3 psi (202 216 kPa) and -423 °F (-252.8 °C) in Table 4, indicative of the extreme conditions it must with-217 stand [40-45]. Both the forward and aft domes of the tank have a modified ellipsoidal 218 shape, with the forward dome featuring mounting provisions for various components 219 such as the LH<sub>2</sub> vent valve and the electrical feed-through fitting [47-50]. The LH2 tank 220 also incorporates a vortex baffle, designed to reduce swirl resulting from slosh and to pre-221 vent entrapment of gases in the delivered LH2 (Edwards et al., 2005). This baffle is strate-222 gically located at the siphon outlet just above the aft dome of the LH2 tank. The outlet 223 facilitates the transmission of liquid hydrogen from the tank through a 17-inch line to the224SLWT aft umbilical, with a feed line flow rate of 465 lb./s (12,700 kg/min) when the main225engines are at 104 %, or a maximum flow of 47,365 US gal/min (2.9883 m³/s) [25].226

Table 3.	LH <sub>2</sub>	Tank Specif	fication.
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LH2 Technical Specification	Full Scale Model (1:1)
Length	97.0 ft (29.6m)
Diameter	27.6 ft ( 8.4 m)
<b>Operation Pressure</b>	32-34 Psi ( 220-230 Kpa)
Operation temperature	-423 F (-253 °C)

To perform the meshing operation and to smoothly carry out the Dynamic FEA anal-228 ysis of the massive Super Lightweight External cryogenic fuel tank (SLWT) high perfor-229 mance computer (HPC) at Institute of Advanced Manufacturing Engineering was utilised. 230 As a resultant of fine meshing approximately 225,000 nodes were generated for which 231 usage of HPC was very vital for this study. Explicit Dynamic analysis is typically em-232 ployed for problems involving impacts or events that occur over very short time intervals. 233 In such scenarios, the time step size is usually very small to capture the rapid changes in 234 forces and deformations [51]. However, for validations that need to be analyzed over a 235 longer duration, Explicit Dynamic analysis may not be the most suitable approach. This 236 is because the small-time step size required for Explicit Dynamic analysis can lead to pro-237 hibitively long computation times when extended to longer periods. Moreover, Explicit 238 Dynamics might not efficiently handle the gradual and sustained loads or deformations 239 that are more characteristic of longer-duration events. 240

Structural Transient analysis, in contrast, aligns more effectively with situations requiring an understanding of structural responses over a longer duration. This method is particularly apt for simulations where loadings and responses develop more slowly, enabling the use of a larger, more manageable time step size. This approach does not sacrifice result accuracy, as seen in Figure 4. Consequently, Structural Transient analysis presents a more suitable and efficient option for this specific problem and the process flow is shown in figure 4.



Figure 4. Process flow for the simulation.

The input for the SLWT tank model was carried out using the following materials 250 property as shown in table 4. The material property data was extracted from the experi-251 mental testing carried out on the AA 2195 + 0.5 wt% of graphene composite. Few 252

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assumptions such as uniform dispersion of reinforced graphene are considered as homogeneous and the porosity percentage to be less than 1%. The AA 2195 + 0.5 wt% of graphene composite material property is applied to the outer body which was currently made of pure AA 2195 as its material. 256

	<b>Contents of Engineering Data</b>	Descrip	otion
S.No.	Material - Al 2195 + Graphene		
	Property	Value	Unit
1	Density	2697.6	Kg/m <sup>3</sup>
2	Coefficient of Thermal Expansion	2.30E-05	C-1
3	Young's modulus E	6.80E+10	Pa
4	Poisson's Ratio	0.31	-
5	Bulk Modulus	5.96E+10	Pa
6	Shear Modulus	2.60E+10	Pa
7	Ultimate tensile Strength UTS	5.67E+08	Pa
8	Ultimate Compressive Strength UCS	5.67E+08	Pa
9	Isotropic Thermal Conductivity	237.5	W/mC
10	Specific Heat Constant Pressure	875	J/KgC

Table 4: Composite materials property data used in this study

Figure 5 represents the meshed model of the SLWT structural assembly, the cross 259 section of the meshed assembly and the meshed LOX, Intertank and LH<sub>2</sub>. To effectively 260 connect all parts, Bonded Contact was utilized, which is instrumental in locking the de-261 grees of freedom (DOF) between the interconnected components. Prior to establishing 262 these bonded connections, it was essential to create imprints for all edges and faces in the 263 Space Claim section in ANSYS 2023. This preparatory step is crucial as it enhances the 264 effectiveness of the Bonded Contact, ensuring better contact and improved accuracy in the 265 simulation. This method simplifies the analysis while still providing accurate insights into 266 the structural integrity and performance under the applied loads and conditions [52-54]. 267

The meshing strategy for the LO<sub>2</sub> and LH<sub>2</sub> tanks, as well as internal components, was 268 meticulously planned and executed to ensure accuracy and computational efficiency in 269 the finite element analysis. Automatic meshing was employed for the LO2 tank, consider-270 ing its geometric characteristics, while a quadrilateral dominant meshing method was 271 chosen for the LH<sub>2</sub> tank due to its unique structural requirements. Internal components 272 such as anti-slosh baffles and strengthening beams were meshed using varied strategies 273 tailored to their specific geometries. The outcome of this comprehensive meshing process 274 yielded a detailed mesh comprising 389,302 nodes and 225,220 elements. This level of 275 mesh density was crucial for accurately capturing the structural responses of the tank as-276 sembly under simulated scenarios, ensuring reliability and precision in the finite element 277 analysis. 278

The use of multiple element types in the model aimed to enhance simulation preci-279 sion and computational efficiency. By selecting element types that best suited the geome-280 try of each component, the total element count was reduced, leading to decreased compu-281 tation time. Shell elements were predominantly utilized for thin-walled structures like 282 tanks and baffles, simplifying thickness modifications crucial for estimating structural in-283 tegrity. Additionally, solid elements were employed for complex geometries, such as re-284 inforcement beams, while beam elements were utilized for bar-like structures, reducing 285 calculation time significantly. This approach underscores the balance between achieving 286 detailed representation and maintaining computational feasibility in structural simulation 287 within the aerospace sector. By customizing the element types to suit the characteristics 288

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of each component, the model became more computationally manageable while ensuring 289 accuracy in predicting real-world behaviour. 290



Figure 5. Meshed model of the SLWT structure (a) the SLWT assembly, (b) the cross section of the292Meshed assemble and the (c) Meshed LOX, Intertank and LH2.293



Figure 6. process flow chart showing the boundary conditions adopted.



Figure 7. Schematic of the boundary conditions provided to the SLWT assembly like the launch297sequence and liquid fuel temperature.298

Figure 7 clearly represents the boundary conditions applied for the SLWT Assembly 299 that depicts the launch sequence of the launch vehicle. Figure 7 represents the location of 300 the Point Masses used to idealize inertial effects from a body. This can include the appli-301 cation of forces due to acceleration or other inertial loads which is mainly because of the 302 exhaust velocity (Ve) achieved due to combustion by combining LH2 and LOX fuel. The 303 relationship between mass point and gas flow rates are used to determine the velocity and 304 acceleration of the vehicle as represented in table 5. The equation used for calculation is 305 presented in equation 1, where k is the specific heat ratio, R\* is the universal gas constant 306 (8,314.4621 J/kmol-K in SI units, or 49,720 ft-lb/(slug-mol)-°R in U.S. units), Tc is the com-307 bustion temperature, M is the average molecular weight of the exhaust gases,  $P_c$  is the 308 combustion chamber pressure, and Pe is the pressure at the nozzle exit. 309

$$V_{e} = \sqrt{\left(\frac{2k}{k-1}\right) \left(\frac{R*T_{c}}{M}\right) \left(1 - \left(\frac{P_{e}}{P_{c}}\right)^{(K-1)/k}\right)}....(1)$$
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Adding inertial mass to a structure influences its modal and harmonic responses, 312 which are crucial for understanding the dynamic behaviour of the structure. Point Mass 313 1 of 6.26 x 105 Kg was applied on the outer surface of the LOX (Liquid Oxygen) Tank. Point 314 Mass 2 of 10.42 x 10<sup>5</sup> Kg was applied on the outer surface of the LH<sub>2</sub> (Liquid Hydrogen) 315 Tank. Utilizing Point Masses enables a more accurate depiction of the loads that the tanks 316 would encounter in actual scenarios, particularly considering inertial forces and the gas 317 flow rates during the flight [55]. The 17 in (430 mm) diameter feed line permits liquid 318 oxygen to flow at approximately 2,787 lb/s (75,800 kg/min). The liquid hydrogen feed line 319 flow rate is 465 lb/s (12,700 kg/min). The application of Point Masses circumvents the need 320 to model the entire mass distribution and flow rates of the tanks, thereby simplifying the 321 analysis while still capturing key dynamics during the flight [56]. 322



Figure 8. Point masses applied for the LOX and LH<sub>2</sub> tanks.

In ANSYS simulations, incorporating standard gravity as a boundary condition is 325 fundamental for replicating real-world launch sequence scenarios accurately. This setup 326 significantly impacts the model's response to its weight, influencing both static and dy-327 namic analyses. By applying gravity, the simulation automatically considers the weight 328 of each component in the model, enabling a comprehensive assessment of the structure's 329 reaction to its own weight and any externally applied loads. The velocity boundary con-330 dition is strategically applied to the lower base of the LH<sub>2</sub> Tank, as shown in Figure 7. 331 Entering the velocity in a tabular format enables the specification of velocity values over 332 time. This approach is crucial for realistically simulating the changing conditions encoun-333 tered by the vehicle in the initial phase of launch [57]. The Initial Phase of launch is char-334 acterized by significant velocity and acceleration changes. The tabular data effectively cap-335 tures these variations, offering a detailed, phase-specific analysis. By simulating the veloc-336 ity changes over time, ANSYS can precisely calculate the resulting stresses and strains on 337 the LH<sub>2</sub> Tank, a critical factor in assessing the structural integrity and safety of the launch 338 vehicle. 339

Time (s)	Altitude (m)	Velocity (m/s)	Acceleration (m/s <sup>2</sup> )
0	-2	0	2.45
20	1244	139	18.62
40	5377	298	16.37
60	11,617	433	19.40
80	19,872	685	24.50
100	31,412	1026	24.01

Table 5. Accent Data of Stage-1 Profile.

The upper side of the LOX Tank is the focus for applying the drag force. This area is 341 crucial as it directly encounters airflow during ascent, bearing significant aerodynamic 342 forces. This application of drag force provides a true-to-life depiction of aerodynamic 343 forces on the vehicle, especially critical during the rapid acceleration of the initial launch 344 phase. LOX tank temperature is set at -183 °C to mirror the cryogenic state of liquid oxy-345 gen, crucial for a realistic thermal behavior simulation. LH2 is set at -253°C, reflecting the 346 extreme cryogenic nature associated with liquid hydrogen, vital for accurate thermal im-347 pact representation as shown in figure 9. 348

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D: With Thermal Thermal Condition 2 Time: 15. s 11/28/23 4:57 PM Thermal Condition 2: Bottom: -147.22 °C



**Figure 9.** Thermal boundary conditions on the LOX and LH<sub>2</sub> tanks applied for the dynamic simulation.

### 3. Results and Discussion

The graph provided in Figure 10a and 10b represents the stress-strain validated over 353 time for a launch vehicle's structure during its initial phase of motion and subsequent 354 stable movement. This graph can be related to the discussion about the stress-strain re-355 duction achieved by reinforcing AL 2195 with graphene. In the first stage of the graph, 356 which can be considered the launch phase, there's a spike in stress levels. This corresponds 357 to the time when the launch vehicle starts moving, and the structure is subjected to the 358 effects of inertia forces. This phase is critical because the initial motion induces a variety 359 of stresses due to acceleration and possibly vibrational loads as the vehicle lifts off. The 360 impact of these stresses would be most pronounced on the Inter Tank shell, where the 361 primary stress concentration was identified in the Ansys analysis. 362

As the launch vehicle transitions from the first stage to the second, the graph shows 363 that the stress levels off, indicating that the vehicle has reached a state of stable movement 364 with constant velocity (acceleration equals zero). During this stage, the dynamic loads 365 become more predictable, and the inertial effects that caused the initial stress peaks are no 366 longer present. Considering the Ansys analysis, we concluded that the graphene-rein-367 forced AL 2195 has a slightly lower maximum stress level than the standard AL 2195. This 368 property would be especially beneficial during the first stage, where the structure experi-369 ences the highest stress. The enhanced tensile strength and improved fracture behavior of 370 the graphene-reinforced composite would contribute to better performance under the dy-371 namic loading conditions experienced during launch. The convergence graph also sug-372 gests that after a certain time interval, specifically at 15 seconds, the behavior of the struc-373 ture under the given conditions does not change significantly over time. This implies that 374 the structure reaches a quasi-static state where the stress distribution remains constant 375 over time, and no further dynamic effects are introduced [58]. This steady-state behavior 376 supports the decision that further analysis beyond 15 seconds is unnecessary, as indicated 377 by the statement that results at 15 seconds would be the same at 100 seconds. 378

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Figure 10. Convergence graph for SLWT structure made of Al 2195 + 0.5Wt% graphene composite379(a) Stress over time and (b) strain over time.380

**Table 6.** Comparison of max stresses in all SLWT Component.

Max Von Misses Stresses (MPa)	AL 2195	AL 2195 + 0.5 Wt% Graphene
SLWT	26.285	25.937
LOX	12.174	10.917
Intertank	26.285	25.937
LH2	4.9023	4.8072

From figure 11 and table 6 it is clearly evident that maximum von misses stress recorded from the 382 Ansys transient analysis at 0.285s during the first phase of launch exhibits that SLWT structure made 383 of composite material exhibited lower stress conditions compared to the parent material Al 2195. 384 For the LOX tank there was a significant reduction of 10.33% in stress observed after the outer body 385 material changed to the composite material, indicating a significant improvement in the material's 386 ability to handle stress during the launch phase. Graphene as a reinforcement was acting as an ex-387 cellent loading bearing material controlling the dynamic stress levels in the entire structural com-388 ponent during the launch sequence. Subsequently, the Intertank and the LH2 tanks exhibited 1.32 % 389 and 1.94 % reduction in the von misses stress level [59-61]. 390



Figure 11. Von Misses Stresses of the two different materials used (a) Al 2195 and (b) Al 2195 + 0.5395wt% Graphene for SLWT, LOX, Intertank and LH2.396

For the LOX (Liquid Oxygen) Tank, the reduction was from 12.174 MPa to 10.917 400 MPa, equating to a 10.33% decrease in stress. The Intertank showed a reduction from 401 26.285 MPa to 25.937 MPa, a more modest decrease of 1.32%. Lastly, the LH<sub>2</sub> (Liquid Hy-402 drogen) Tank experienced a stress decrease from 4.9023 MPa to 4.8072 MPa, resulting in a 403 1.94% reduction. The reductions in stress due to the addition of graphene by 0.5 % are 404 particularly noteworthy for the LOX tank, which saw over a 10% decrease. This suggests 405 a significant improvement in the material's resilience under the dynamic loading condi-406 tions of launch [62-63]. While the Intertank experienced the least stress reduction, it is also 407 where the highest stresses were observed. This reasonable improvement may still signifi-408 cantly enhance the Intertank's structural integrity during launch. The LH<sub>2</sub> tank's stress 409 reduction is quite less compared to the LOX tank, is still meaningful when considering 410the entire launch vehicle's stress profile as seen from figure 11. 411

The incorporation of graphene, which is known for its high tensile strength and ex-412 ceptional stiffness, has been shown to enhance the load-bearing capacity of the matrix Al 413 2195. From the authors' previous pilot research work [27], the addition of graphene im-414proved the material's ability to distribute stress more effectively due to its two-dimen-415 sional structure and extensive surface area. Furthermore, the tensile strength of the com-416 posite material reaching up to 508.5 MPa, a finding supported by various similar research 417 in the past as shown in figure 13 c and d, highlights the considerable impact of graphene 418on improving material strength. The microstructural enhancements brought about by gra-419 phene, such as acting as a barrier to dislocation movement and increasing yield strength, 420 are crucial in understanding the improvements in stress handling [27]. Additionally, the 421 reinforced AL 2195's modified fracture behavior indicates a more controlled fracture 422 mechanism that contributes to increased fracture toughness and decreased failure chances 423 under dynamic loading scenarios. The critical evaluation of these results against the 424 study's objectives validates the fact that graphene reinforcement positively affects the me-425 chanical properties of launch vehicle fuel tank structural materials. The stress reductions 426 in the SLWT components confirm the potential of graphene-reinforced composites to en-427 hance the safety and reliability of aerospace structures, especially during the extreme con-428 ditions of launch. 429

From figure 12 it is clearly evident that equivalent elastic strain recorded from the 430 Ansys transient analysis at 0.285s during the first phase of launch exhibits that SLWT 431 structure made of composite material exhibited lower strain levels compared to the parent 432 material Al 2195. For LOX Tank the total equivalent elastic strain reduced from 1.8271 × 433  $10^{-4}$  to  $1.6625 \times 10^{-4}$  (approx. 9% decrease) with graphene reinforcement. For the Intertank 434 the total Elastic strain remained at 3.8116 × 10<sup>-4</sup> for both parent material Al2195 and Al2195 435 +0.5 wt% graphene composite. Elastic strain increased from  $1.5077 \times 10^{-4}$  to  $1.6848 \times 10^{-4}$ 436 (approx. 11.74% increase) for the LH<sub>2</sub> tank validated for composite material. 437

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Figure 12. Equivalent Elastic Strain of the two different materials used (a) Al 2195 and (b) Al 2195 + 4470.5 wt% Graphene for SLWT, LOX, Intertank and LH2.448

The reduction in elastic strain in the LOX tank, combined with the increased yield 449 strength of the graphene-reinforced composite, points towards improved material perfor-450 mance under the dynamic loading conditions of launch as seen from the figure 13 c and 451 d. The unchanged strain in the Intertank could be attributed to its complex stress state, 452 which might be directly related to the type of material reinforcement used or design optimization of the component itself [17].

The observed increase in elastic strain in the LH2 tank, despite the addition of gra-455 phene, presents an interesting characteristic. It suggests a complex interface mechanism 456 between the graphene and the aluminum matrix, potentially influencing the material's 457 dynamic load response. This underscores the importance of thoroughly understanding 458 composite behavior under dynamic loading conditions. These results emphasize the crit-459 ical role of material selection and design optimization in aerospace engineering, where 460 each component's performance is vital. Future investigations into graphene-reinforced 461 composites should encompass a broad range of material properties and their interactions 462 under specific space launch conditions [13-16, 18, 27]. 463



Figure 13. Total deformation and the Strength comparison of the two different materials used (a) Al4672195 and (b) Al 2195 + 0.5 wt% Graphene for SLWT assembly, (c) and (d) tensile strength data.468

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From figure 13 it is clearly evident that composite material with reinforced graphene 469 exhibited minimal change in total deformation during the initial stage of launch sequence 470 which confirms that the composite material's inherent structural properties play a signif-471 icant role in deformation behavior under dynamic load conditions. The slight reduction 472 in elastic modulus and decrease in Poisson's ratio with the addition of graphene, while 473 theoretically contributing to a more elastic response, appear to have a negligible impact 474 on the overall deformation of the SLWT. This observation is aligned with our previous 475 experimental findings [18] where we have observed a strong influence of graphene addi-476 tion on the mechanical properties of aluminum composites. The near-unchanged total de-477 formation result could indicate that factors other than material stiffness and elasticity, 478 such as the geometric design of the SLWT or the specific loading conditions during launch, 479 might be more influential in determining the deformation behavior [27]. This perspective 480 is supported by various other researches and their analysis of the Space Shuttle's external 481 fuel tank, where the structural complexities and loading conditions were critical in under-482 standing the tank's behavior. 483

(a) AL- 2195		(b) AL-2195 Graphene			
Details of "Geometry"     ▼ <b>↓</b> Definition		+	Definition		
		+	Bounding Box		
+	+ Bounding Box  Properties Volume 6.4233e+010 mm <sup>3</sup>			Properties	
			Volume	64.233 m <sup>3</sup>	
	Mass	9.2357e+005 kg		Mass 🗌	9.0415e+005 kg
	Scale Factor Value	1.		Scale Factor	1.
	2D Tolerance	Default (1.e-005)		2D Tolerance	Default (1.e-005)
	Total Weig	ht: 9.2357E+005 KG		Total Weigh	t: 9.0415E+005 KG

**Table 7.** Comparative Analysis of weight Al 2195 vs AL-2195 + 0.5 Wt% Graphene composite.

A significant breakthrough in the study is the weight saving of 19,420 kg when 485 switching from standard AL 2195 to the graphene-reinforced Al 2195 composite. This 486 weight reduction is a substantial benefit in aerospace and space exploration applications, 487 where every kilogram saved can lead to increased payload capacity, fuel efficiency, and 488 overall mission performance. The statistical evaluation of stress measurements reveals 489 that both materials, AL-2195 and AL-2195 Graphene, exhibit similar levels of resilience 490 under dynamic launch conditions. The stress values for both materials fall within a com-491 parable range, indicating that the incorporation of graphene into AL-2195 does not 492 weaken the material's capacity to endure the stresses experienced during launch. 493

The strain analysis similarly showed that both materials exhibit a consistent magni-494 tude of strain over time. This consistency in strain, even with the reduced weight of the 495 graphene-reinforced composite, indicates that the material retains its structural integrity 496 and does not experience additional deformation, despite the significant weight reduction. 497 As for deformation, the data demonstrated that both materials experience a non-linear 498 increase in deformation over time, yet the AL 2195 + Graphene variant shows virtually 499 identical deformation profiles to the parent material AL 2195. This observation is particu-500 larly remarkable because it implies that the reduction in weight does not lead to increased 501 deformation, maintaining the structural performance required for SLWT cryogenic fuel 502 storage aerospace applications. 503

The slightly lower elastic modulus (68 GPa for AL 2195 + Graphene vs. 69 GPa for AL 504 2195) did not translate into a significant difference in deformation behavior, suggesting 505 that under the dynamic loading conditions of launch, other factors such as structural design and loading conditions play a more critical role. The slightly higher yield strength 507 (562 MPa for AL 2195 + Graphene vs. 560 MPa for AL 2195) and reduced density (2.6976 508 g/cm<sup>3</sup> for AL 2195 + Graphene vs. 2.712 g/cm<sup>3</sup> for AL 2195) of the graphene-reinforced 509 composite imply an improvement in material performance, particularly considering the 510

weight savings achieved without compromising the material's ability to withstand stress 511 and deformation. The achievement of reducing weight by 19,420 kg, while simultaneously 512 retaining structural integrity and performance, marks a significant milestone in the field 513 of aerospace material science. This accomplishment is in line with the sustainable objective 514 of advancing aerospace material technology, showcasing the potential of graphene-alu-515 minum composites for future spacecraft design and construction. 516

## 4. Conclusion

This research effectively conducted a dynamic finite element analysis (D-FEA) of a 518 liquid hydrogen cryogenic fuel tank made from an aluminum-graphene composite (AL-519 2195 with 0.5% graphene), focusing on its structural integrity and performance for aero-520 space launch vehicle applications. The study achieved its set objectives, confirming the 521 effectiveness and benefits of this innovative composite material. The analysis of the 2195 522 aluminum-graphene composite's material properties revealed notable improvements, es-523 pecially in yield strength, overall strength and more importantly a weight reduction of 524 19,420 kg which is 2.1% of the dead tank weight, while slightly reducing the elastic mod-525 ulus and density. Notably, this reduction in weight did not diminish the tank's strength 526 or performance, indicating successful material optimization for weight efficiency. These 527 results highlighted the composite's suitability for challenging aerospace applications, 528 showcasing its enhanced mechanical properties. The dynamic FEA yielded valuable data 529 on stress, strain, and total deformation responses under various loading nature under cry-530 ogenic conditions. The findings affirmed the aluminum-graphene composite's ability to 531 withstand the dynamic forces of launch while preserving its structural integrity which 532 matched the parent material 2195. 533

Acknowledgments: Authors would love to acknowledge Dr. Arivazhagan Anbalagan, Assistant 534 Professor at Institute of Advanced manufacturing Engineering (AME) and Dr. Marcos Kauffman, 535 Centre Director AME, Coventry University, Coventry, United Kingdom, for their invaluable sup-536 port in providing access and guidance to use the High-Performance Computer HPC for the Simula-537 tion and Validation. Additionally, the authors extend their gratitude to British Council for support-538 ing this project that facilitated the student involvement in this high esteemed research work. Au-539 thors also extend their gratitude to the School of Mechanical Engineering, Coventry University and 540 Vellore Institute of Technology for providing access to fabrication facility and Characterization fa-541 cilities used for experimental data acquisition that helped in validating the digital simulation of the 542 SLWT. 543

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