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### Abstract

Integration of multiple technologies greatly increases the spatial and temporal scales over which ecological patterns and processes can be studied, and threats to protected ecosystems can be identified and mitigated. A range of technology options relevant to ecologists and conservation practitioners are described, including ways they can be linked to increase the dimensionality of data collection efforts. Remote sensing, ground-based, and data fusion technologies are broadly discussed in the context of ecological research and conservation efforts. Examples of technology integration across all of these domains are provided for large-scale protected area management and investigation of ecological dynamics. Most technologies are low-cost or open-source, and when deployed can reach economies of scale that reduce per-area costs dramatically. The large-scale, long-term data collection efforts presented here can generate new spatio-temporal understanding of threats faced by natural ecosystems and endangered species, leading to more effective conservation strategies.

<b>Keywords</b>	ecological dynamics; remote sensing; protected areas;
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1 Integrating Technologies for Scalable Ecology and Conservation

2

3 (Short title: Integrating Ecology and Conservation Technology)

4

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23 Keywords: drone; ecological dynamics; protected area management; radio tracking; remote

24 sensing; Wireless Sensor Networks

## 25Abstract

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27over which ecological patterns and processes can be studied, and threats to protected  
28ecosystems can be identified and mitigated. A range of technology options relevant to  
29ecologists and conservation practitioners are described, including ways they can be  
30linked to increase the dimensionality of data collection efforts. Remote sensing,  
31ground-based, and data fusion technologies are broadly discussed in the context of  
32ecological research and conservation efforts. Examples of technology integration  
33across all of these domains are provided for large-scale protected area management  
34and investigation of ecological dynamics. Most technologies are low-cost or open-  
35source, and when deployed can reach economies of scale that reduce per-area costs  
36dramatically. The large-scale, long-term data collection efforts presented here can  
37generate new spatio-temporal understanding of threats faced by natural ecosystems  
38and endangered species, leading to more effective conservation strategies.

### 391.      **Introduction**

40Ecologists and conservation practitioners have proven themselves adept at  
41incorporating emerging technologies into field data collection efforts (Pimm et al.,  
422015). The innovative use of technology is expanding the bounds of traditional  
43ecological inference and conservation strategies (Snaddon et al., 2013). Continuing to  
44expand efficient data collection in both time and space is crucial in the face of the  
45enormous pressure that global changes are exerting on natural ecosystems (Rockström  
46et al., 2009). Rapid habitat and biodiversity losses (Pimm et al., 2014), illegal wildlife  
47harvest and trade (Milner-Gulland and Bennett, 2003), and climate change (IPCC,  
482014) all affect ecosystems across the globe and increasingly require more than just  
49field surveys to understand, monitor, and report on their effects.

50        Traditional field inventory plots and other sampling strategies are, and will  
51continue to be, a crucial tool in the arsenal of ecologists for understanding local-scale  
52processes and the functioning of ecosystems. Yet field surveys are costly to set up and  
53maintain over many years (Berenguer et al., 2015), and they are extremely difficult to  
54utilize in remote regions of the world. Just as concerning, in heterogeneous  
55ecosystems field plots may actually provide biased estimates of ecological properties  
56and processes (Marvin et al., 2014). The technologies we discuss here can help to  
57overcome many of these shortcomings, especially when used in combination. Smart  
58deployment and use of these technologies can open up new ecological scales to  
59investigate the assembly, competition, dispersal, and migration of organisms and their  
60interactions with the surrounding environment. Additionally, combating illegal  
61activities such as poaching/hunting, logging, and encroachment require efficient  
62monitoring and tangible evidence for investigating and prosecuting offenders.

63 Preventing human-wildlife conflict, especially with large animals that can cause  
64 serious injury or death, often requires similar deployment of these technologies.

65        Here we provide descriptions and a synthesis of multiple technologies that can  
66 be deployed at different scales, with two hypothetical examples of how they can be  
67 integrated to increase the scale (both temporal and spatial) and dimensionality of  
68 ecological and conservation research. Increasing the resolution and area over which  
69 data are collected is important for identifying and mitigating threats to protected  
70 ecosystems, as well as understanding and uncovering ecological patterns and  
71 processes. Moreover, these data can be better integrated into dynamic global  
72 vegetation models (DGVMs) when the spatial and temporal scales accurately  
73 represent the process of interest (e.g., productivity, mortality). Most of the  
74 technologies discussed here or their associated data are low-cost, open-source, or  
75 freely available, and have proven applications for ecologists and conservation  
76 practitioners alike. The economies of scale achievable by these technologies can make  
77 any upfront expense for their purchase or development cost-effective. In Table 1, we  
78 provide example studies from each of the six main technologies that are described in  
79 more detail below. Our aim is simply to provoke discussion among researchers about  
80 the potential for integrating multiple technologies into their work, rather than  
81 providing a comprehensive critique of each emerging or established technology.

## 822.        **Remote sensing technology**

### 832.1.        **Satellite**

84 Satellite remote sensing platforms offer widespread geospatial coverage and, in many  
85 cases, long temporal records of Earth's biomes. However, most satellites (especially  
86 those satellite data providers offering free data access) lack the spatial resolution for  
87 organismic-level analysis, and often have limited spectral ranges, constraining their

88potential applications (Asner, 2015). While this is rapidly changing with the recent  
89revolution in the way Earth-observing satellites are designed, built, and deployed (see  
90discussion of cubesats below), the traditional large-platform satellites still have many  
91advantages. An interactive overview of many operational satellites can be found at  
92satsummit.github.io/landscape.

93       Government-sponsored satellite sensors have the longest temporal data archive  
94of earth-observing images and are often freely available to the public. NASA's  
95Landsat program just passed its 44<sup>th</sup> year of continuous operation, providing an  
96incredible opportunity to analyze ecological and land use dynamics over very large  
97areas (e.g., Hansen et al., 2013). There are many other optical multispectral and active  
98sensors (e.g., radar, laser) that produce data at spatial resolutions ranging from 30 m  
99to 1 km, offering data products for understanding vegetation dynamics and biomass,  
100climate and weather patterns, and biophysical variables like surface temperature, soil  
101moisture, and CO<sub>2</sub> flux (e.g., Goetz et al., 2009). Increased cooperation between the  
102ecology and remote sensing communities could lead to improved biodiversity and  
103ecosystem monitoring opportunities through publically-funded satellites and sensors  
104(Skidmore et al., 2015).

105       Commercially operated sensors onboard traditional large satellite platforms  
106typically offer much higher spatial resolution data (1-5 m), but at high cost. A typical  
107archived (previously acquired) multispectral scene will cost at least \$20 km<sup>-1</sup> with a  
108minimum purchase of 25 km<sup>2</sup>, making large or frequent acquisitions of images  
109prohibitively expensive for many researchers. Commercial images are limited in their  
110spectral resolution, often composed of four to eight band images, also known as  
111multispectral images. Similar to government satellite sensors, these spectral ranges

112allow for visual analysis and the development of basic vegetation indices, but at (or  
113near) organismal spatial resolutions.

114       The ‘cubesat’ (also known as small satellite or smallsat) revolution currently  
115underway is providing new means to conduct earth observation and analysis. Cubesats  
116weigh less than 10 kg (often only 1 kg), are about the size of a shoebox (Fig. 1), and  
117are cheap (relative to large satellites) to design, build, and deploy. This allows for  
118large constellations (orbitally-synchronized satellites) to be put into low-earth orbit,  
119covering much larger areas of the globe simultaneously, but with less advanced  
120sensors than those on large satellite platforms. One such company, Planet (San  
121Francisco, CA, USA), is deploying a cubesat constellation with the goal of imaging  
122the entire Earth once per day at <5 m resolution. Another smallsat company, Skybox  
123Imaging (Mountain View, CA, USA), has HD video capability as well as multispectral  
124imagery at 2 m resolution, but presently on a much smaller constellation. With the  
125rapid advancement of smallsat technology and decreases in associated costs, the  
126potential for more advanced sensors on larger satellite constellations will undoubtedly  
127be realized over the coming years. Nearly real-time monitoring and analysis of  
128research and conservation sites is not far off.

129       Accessing government and free commercial data has become much easier with  
130new, web-based platforms that host these data. Almost all NASA-sponsored satellite  
131data can be accessed through [earthexplorer.usgs.gov](http://earthexplorer.usgs.gov) at no charge. A more advanced  
132image archive and search platform is Google Earth Engine (GEE), capable of rapid  
133and sophisticated analysis of satellite imagery using the Google’s cloud computing  
134systems at no cost. Many necessary preprocessing steps (e.g., atmospheric correction,  
135orthorectification) have already been applied to the imagery catalogue, and there are  
136even derived composite products (e.g., NDVI) available. While utilization of satellite

137imagery traditionally required specialized technicians to process and interpret, the  
138continued maturation of these platforms allows almost anyone to incorporate satellite  
139imagery into their projects on some level.

## 1402.2.     **Airborne**

141Over the past several decades airborne platforms have begun to fill a critical gap  
142between the measurements provided in field studies and those by satellite-based  
143sensors. At one extreme, field plots provide highly detailed measurements of the  
144physiology, taxonomy, growth, and mortality of individual organisms (Gentry, 1988),  
145while at the other extreme Earth observing satellites provide wall-to-wall coverage of  
146ecosystem type, structure, and land-cover change (e.g., Friedl et al., 2002).

147Advancements in sensor technology, image processing and analysis, and mission  
148planning now allow measurement of ecosystem properties in plot-level detail at  
149landscape-to-regional scales previously only possible with satellites, and at steadily  
150decreasing cost.

151         While airborne remote sensing has long been used in forestry and agriculture  
152(Colwell, 1964), a shift from basic analogue and digital photography to high-fidelity  
153hyperspectral, active radar and laser, and passive thermal instrumentation has changed  
154the field dramatically. The proliferation of these modern sensors mounted on aircraft  
155operated by government, commercial, and non-profit entities has revealed ecological  
156processes in great detail across spatial scales that have long eluded ecologists. Some  
157of these data or resulting products are made available to the public (e.g.,  
158earthexplorer.usgs.gov, cao.carnegiescience.edu).

159         One such system, the Carnegie Airborne Observatory (CAO) Airborne  
160Taxonomic Mapping System (AToMS, cao.carnegiescience.edu), is an airborne



platform that fuses data collected simultaneously by three different sensors (Asner et al., 2012). Two optical hyperspectral imagers (also known as imaging spectrometers) and a waveform light detection and ranging (LiDAR) scanner are a powerful combination. Together they have been used to reveal forest canopy chemistry, biological diversity, carbon stocks, ecosystem structure, and even elephant and lion behavior (Dahlin et al., 2013; Féret and Asner, 2014; e.g., Loarie et al., 2013). Other airborne platforms are being developed for temperate ecosystem monitoring (neoninc.org) and snow mapping (aso.jpl.nasa.gov). The economies of scale achieved by airborne remote sensing are reducing the per-area cost tremendously. For example, in a recent project fusing CAO airborne data with satellite imagery, the cost (including aircraft, sensors, logistics, and data processing) to map forest aboveground carbon stocks throughout 132 million ha of Perú was less than \$0.01 USD per ha (Asner et al., 2014).

### 4.3. Unmanned Aircraft Systems

The use of unmanned aircraft systems (UAS, also known as drones) is gradually gaining popularity and acceptance by the environmental community (e.g., Koh and Wich, 2012; Whitehead and Hugenholtz, 2014). The mainstreaming of this technology is partly driven by an increasingly challenging funding climate in the environmental sector: UAS present excellent cost-saving opportunities (compared with manual labor) in field-based applications such as the detection, monitoring and mapping of wildlife, their habitats and the wider landscape (Koh and Wich, 2012; Wich, 2015). These applications are relevant to species conservation, habitat protection and restoration, pest eradication, and watershed management. In addition, UAS can provide data at previously unavailable resolutions (e.g.,  $\leq 5$  cm), allowing for

185increasingly fine-grained analyses of ecological questions (Anderson and Gaston,  
1862013).

187       Most UAS are fully autonomous aircrafts, with an on-board guidance system  
188flying the UAS along pre-programmed waypoints over an area of interest (Fig. 1).  
189They can be equipped with different camera systems for taking still RGB  
190photographs, RGB video footage, thermal images, multi-band images, and even  
191hyperspectral and LiDAR (Watts et al., 2012). UAS have monitored large mammals  
192with UHF (Ultra High Frequency) or RFID (Radio Frequency Identification  
193Technology) devices, substantially reducing costs compared to satellite and ground-  
194based collaring and tracking operations (South African National Parks, unpublished  
195data). UAS can be purchased off the shelf, or assembled from scratch as demonstrated  
196by Koh and Wich (2012) for an array of conservation issues, allowing considerable  
197flexibility in the choice of UAS. The latter approach is less-costly and allows  
198malfunctioning or damaged parts to be replaced in the field, which is essential for  
199remote areas. Some of the applications of conservation drones include mapping land  
200use, surveying biodiversity, and monitoring illegal activities (for a review see Wich,  
2012015).

202       For example, the photographs captured by a UAS can be stitched together to  
203produce a mosaic that provides detailed information on the type of land use,  
204agriculture, and settlements in the landscape (e.g., Whitehead et al., 2014). These  
205images can also be processed to produce three-dimensional models of the landscape,  
206such as terrain relief and forest canopy height (Dandois and Ellis, 2010) or they can  
207be used to obtain data on species diversity and forest gap size (e.g., Getzin et al.,  
2082012). Each photograph is automatically tagged with the UAS location coordinates  
209when the picture was taken, allowing accurate (1-2 m) geopositioning of the final

210imagery. The area mapped during one flight is a function of the ground resolution  
211required and the flight duration of the UAS. Covering an area of ~500 ha in a one  
212hour flight is feasible with a ground resolution of ~5 cm per pixel. Several small UAS  
213can now fly for approximately an hour, with increasing flight durations allowing  
214mapping of progressively larger areas, with several flights per day to expand the total  
215area mapped.

216       The use of UAS could lead to significant savings in terms of time, manpower,  
217and financial resources for conservation workers and researchers, but more  
218assessments of the total costs of using UAS need to be made (e.g., Vermeulen et al.,  
2192013). Such analyses should include the costs of personnel, computer hard and  
220software, and UAS maintenance. These potential cost savings would increase the  
221efficiency of monitoring and surveying forests and wildlife in the developing tropics.  
222UAS are a potential game-changer and could become a standard item in the toolbox of  
223field biologists everywhere.

### 2243.       **Ground deployed technology**

#### 2253.1      **GPS telemetry**

226Animal movement and the ecological and evolutionary processes driving such  
227behavior are fundamental characteristics of animal ecology and, when understood,  
228enable insight into many biological phenomena. Animals move in attempts to find  
229resources or to avoid risks, concurrently providing ecosystem services such as seed  
230and nutrient dispersal (Côtés and Uriarte, 2012) and acting as vectors for diseases  
231and parasites (Altizer et al., 2011). Data on animal movement provides insight into the  
232placement and maintenance of conservation corridors (Chetkiewicz et al., 2006) and  
233movement itself facilitates connectivity between patches of fragmented landscapes  
234(Mueller et al., 2014).

235 Technology to track animals and study their movement has undergone  
236 enormous advancement over the last several decades. Early reliance on VHF (very  
237 high-frequency) technology that required researchers to be in the field and in close  
238 proximity to tagged animals, possibly influencing their behavior, has being largely  
239 replaced with satellite telemetry using global positioning systems (GPS) that enable  
240 remote tracking and higher location accuracy (Cagnacci et al., 2010). Whereas before,  
241 telemetry data from wild animals were considered too sparse and inaccurate to enter  
242 the realms of cutting edge ecological research, smaller tags with longer battery life  
243 and vastly improved GPS technology (Fig. 1) have enabled large volumes of data to  
244 be collected from many more individuals and species (Kays et al., 2015). Recently,  
245 animal tags are being fitted with additional secondary sensors, allowing collection of  
246 physiological and environmental data. Accelerometers are being built into tags to  
247 measure fine-scale body movements, providing insight into energetics and behavior  
248 (e.g., Williams et al., 2014), while other electronic devices can be attached to record  
249 physiological measurements such as heart rate and internal temperature (e.g., Signer  
250 et al., 2010).

251 By making use of satellite or cell-phone communication networks, data from  
252 animal tags can be downloaded remotely in real time using mobile devices,  
253 circumnavigating difficulties around tag and data retrieval (and loss) and facilitating  
254 immediate responses to changes in animal locations (Kays et al., 2015). This provides  
255 much needed assistance to conservation managers who can receive alerts when  
256 problem animals leave predefined areas or acquire real time locations on endangered  
257 species that frequently come into contact with people (Wall et al., 2014). As the  
258 quality and type of tracking data have improved, so has the ability to measure the  
259 environment through which animals move. Remote sensing techniques provide

260extensive and continually improving measurements of ecosystems, and when  
261combined with high resolution telemetry data can be a powerful tool to understand  
262animal movement and habitat preference (Davies and Asner, 2014).

263 Further improvements to animal tracking technology can still be made, and  
264some caution is required in the use of the technology (Hebblewhite and Haydon,  
2652010). Tag size is still too large for placement on many small birds and mammals  
266(Kays et al., 2015), and although some studies have tracked insects (e.g., Ovaskainen  
267et al., 2008), they are largely excluded from animal movement studies. There are also  
268challenges around location accuracy, especially when attempting to match telemetry  
269data with high resolution remote sensing. Ethical considerations and potential  
270behavioral adjustments induced by tagging also need continual attention with  
271concerted efforts to reduce adverse effects. However, the knowledge that has been  
272gained through animal telemetry and the prospects for future discovery are enormous.  
273Kays et al. (2015) suggest that we are moving into a ‘golden age’ of animal tracking  
274science and are beginning to use animals to inform us about crucial changes to the  
275planet and to make predictions of future change, moving from simply studying  
276animals, to using animals to study the planet.

### 2773.2 Camera-trapping

278One of the most pressing problems faced by animal ecologists is choosing the most  
279appropriate method for surveying and monitoring populations (Breck, 2006).  
280Traditional methods such as live-trapping may increase the risk of injury to an animal  
281and cause behavioral avoidance (or attraction) to the traps. Direct observations at  
282points and along transect lines may also affect behavior due to the physical presence  
283of the researcher, and are often difficult due to dense vegetation or clumped  
284distributions of the target species. Terrain, remoteness, or weather conditions may

285preclude repeat visits by survey teams, making it difficult to replace baits or conduct  
286replicate counts.

287        Camera-traps solve many of these issues by collecting animal movements in  
288space and time through time-stamped photographs. Camera-traps do not require the  
289researcher to be present and can be hidden or camouflaged to produce relatively  
290unbiased samples. They can be established in any terrain or habitat and operate for as  
291long as the power source allows. Camera-trapping can be more efficient than other  
292survey methods, especially for rapid assessment of biodiversity (Silveira et al., 2003).

293        Modern digital camera-traps are remotely triggered by infrared sensors and are  
294much less obtrusive, although sound and light produced by cameras vary by make and  
295model (Meek et al., 2014). Camera traps can be set to take multiple photographs at  
296desired time intervals, thus allowing multiple records of individual animals, and  
297detection of family groups moving together. They can rapidly record and store  
298hundreds to thousands of digital images on a single SD card, thus facilitating rapid  
299sharing of data.

300        There is now a wide range of commercial camera-traps available to  
301researchers, varying in detection angle and distance, field of view, trigger speed,  
302recovery time, resolution, and price (Trolliet et al., 2014). There are a number of  
303considerations when choosing a particular camera-trap device (see Glen et al., 2013;  
304Kelly and Holub, 2008; Rovero and Zimmermann, 2013 for more detail). For  
305example, if the study objective is to generate a rapid inventory of species presence, a  
306low-cost (\$40-100) model that takes photographs sufficient to identify species should  
307suffice, although a non-intrusive infrared flash camera is preferable. However, if the  
308objective is to enumerate populations of marked individuals, a much more  
309sophisticated device with a high-resolution infrared camera is required.

310 The ecological applications of camera-trap data are diverse. Photos from  
311 single camera-traps can produce information on sex, age, breeding status and identity  
312 of individual animals, as well as other demographic parameters, and determine their  
313 activity patterns (e.g., Lynam et al., 2013). Photos from arrays of camera-traps can be  
314 used to measure movement and home range, and where individuals have identifiable  
315 coat patterns, camera-traps can be used to estimate population size (e.g., Burton et al.,  
316 2015). Using species detection/non-detection records and an occupancy modeling  
317 approach, it may be possible to predict the occurrence of rare species in a  
318 conservation area (MacKenzie et al., 2005). Camera-traps can help identify habitat  
319 preferences (e.g., Gray and Phan, 2011), although camera trap placement can bias  
320 results for different species (Harmsen et al., 2009), for example, if animals respond to  
321 human scent left on a device. Camera-traps have also been used for the study of  
322 ecological processes such as nest predation and plant-animal interactions (e.g., Pender  
323 et al., 2013).

324 An adaptation of the camera-trap design can make it possible to transmit  
325 images or video in real time via SMS or MMS across local 3G telephone networks.  
326 Such wireless cellular camera-traps can detect individual animals such as problem  
327 elephants, or poachers, alerting park authorities who can then respond appropriately.

### 3283.3 Wireless Sensor Networks

329 Wireless Sensor Networks (WSN) – composed of interconnected but spatially  
330 distributed autonomous monitoring devices – have great potential to aid in  
331 understanding ecological dynamics and protecting endangered species (Benson et al.,  
332 2010). Specially designed sensor networks can detect motion, sound, smell, and  
333 external environmental variables (e.g., temperature, humidity, light, etc.) in a non-  
334 invasive manner and in remote regions (Fig. 1). Distributed computing in WSN

335enables information to be collected remotely while processing only relevant data at a  
336specific location, reducing data storage overhead or allowing increased sampling  
337frequency. WSN have already been successfully used in military, industry,  
338commercial, civil, and healthcare applications (Arampatzis et al., 2005).

339       Recent research on sensor networks has focused on networking techniques and  
340networked information processing suitable for highly dynamic environments and  
341resource-constrained sensor nodes. Sensor nodes have decreased in size and are much  
342cheaper, resulting in the emergence of many new civilian applications from  
343environment monitoring to vehicular and body sensor networks. Sensors are routinely  
344deployed in very harsh conditions such as glaciers, on animals, or in very remote  
345locations (e.g., Martinez et al., 2005). Low-cost, off-the-shelf sensor parts can be  
346integrated with microcontrollers (e.g., Arduino) and microSD cards to create  
347standalone sensor nodes that can communicate (via radio transmitters) with each other  
348and/or a network hub. Soil moisture, tree growth, photosynthetically active radiation,  
349water flow, and animal activity are just a few variables that can be continuously  
350monitored remotely (Collins et al., 2006).

351       WSN technology is used not only to monitor remote locations but also to  
352locate where events occur (Fig. 2). This is crucial for gathering evidence for illegal  
353activity or uncovering subtle ecological interactions. WSN technology can be used for  
354creating virtual fences, focal area monitoring, and/or behavior-specific surveillance.  
355In a virtual fence set-up, a series of sensors are placed around the protected boundary  
356of a target area and can identify an intrusion and its location, instantly communicating  
357this to network monitors. A WSN exploits the capabilities of fiber optics, passive  
358infrared, doppler radar, and other specialized sensor devices to create the virtual  
359fence. Although the application of WSN in wildlife research and management is still



360in its infancy, they have become successful in the establishment of early warning  
361systems and studying animal behavior. Alternatively, events such as gunfire  
362(poaching), felling of trees, human or animal trespassing, and vehicle movement,  
363among others, require monitoring of a focal area. This is best achieved with a WSN  
364capable of sensing the target event, processing the signal to identify and locate the  
365event, and communicating the event to a control station for initiation of a response if  
366necessary. Finally, behavior specific surveillance is possible, for example by  
367deploying sensor systems on natural trails for animal species that frequent trail  
368networks for hunting and movement.

369        WSN technology functions best when integrating camouflage, low power-  
370consuming devices, sophisticated signal processing software and hardware, and  
371suitable packaging that can withstand hostile environmental conditions. WSN is a fast  
372emerging field and ecologists and conservation practitioners alike can benefit  
373significantly from new understanding of their target species or environments. Once  
374deployed, this technology is a non-invasive method of wildlife research and  
375conservation, without the need to physically capture animals, as required for radio  
376collaring and tracking. WSN can provide important technological support for  
377managing wildlife populations, including reduction in human-wildlife conflict, and  
378uncovering the ecological dynamics of remote habitats. WSN tools have yet to be  
379fully integrated in many real world applications for wildlife management and  
380ecological research, partly due to lack of complete knowledge of such technology.  
381However, there has recently been appreciable change in the exploration of WSN for  
382conservation and research purposes, and a few experiments have already been taken  
383up in India and Africa (pers. comm., R Krishnamurthy).

#### 3844.        **Data fusion and processing**

#### 3854.1     **Mobile devices and apps**

386The explosion of smartphones, tablets, and their innumerable associated software  
387applications (“apps”) has already revolutionized many industries and scientific fields  
388around the world; the field of ecology is no exception. In their most basic form, these  
389devices can be used to record data in the field more efficiently and without the added  
390burden and mistakes associated with manual data re-entry – the device is simply  
391synced with a computer or cloud network for further viewing and analysis. Whether  
392using voice-to-text features or simply inputting numbers into a spreadsheet,  
393smartphones and tablets undoubtedly give a field ecologist an advantage. Most current  
394generations of phone and tablet devices have built in satellite navigation capability,  
395but have only half the accuracy of standalone satellite navigation (e.g., GPS, GNSS)  
396units (Olson et al., 2014), with further accuracy degradation in closed-canopy forests.  
397However, using a standalone satellite navigation receiver allows work in remote areas  
398and greatly increases positional accuracy under most conditions. These GPS (e.g.,  
399Bad Elf, Garmin GLO) and GNSS (e.g., EOS Arrow) receivers can link directly to the  
400device through Bluetooth or a direct physical connection, providing precise  
401navigation in the field. It may seem risky to expose an expensive piece of electronics  
402to harsh outdoor conditions, but either a simple plastic bag or a more expensive water-  
403and shock-proof case will adequately protect most devices. Some manufacturers even  
404offer ‘ruggedized’ versions of their products specifically for outdoor use.

405         However, navigating to and within field sites is just part of the task. Data  
406collection and organization are greatly enhanced by a number of apps, many of which  
407are free to download and use on multiple device platforms. The free app iGIS allows  
408caching of Google maps imagery for later use offline, uploads of custom base imagery  
409(e.g., topographic maps, orthophotos, high-resolution satellite images, classification

410maps), creation of shapefiles (point, line, and polygon vector files), and linking  
411photographs to geolocational data. While iGIS has a learning curve before the full  
412functionality is unlocked, other options might be worth the price given their  
413simplicity. GISpro may be expensive compared to most apps, but it unlocks a suite of  
414easy-to-use features that turns a device into a mobile GIS unit. Undoubtedly, as these  
415and other spatial data apps (e.g., WolfGIS, iGeoTrack) gain more usage among  
416ecologists, field data collection will be transformed.

417       Myriad other apps are available to field ecologists that go beyond the  
418collection of spatial data: real time weather and environmental conditions (e.g.,  
419Marine Weather Plus, RiverFlows), species identification (e.g., Plant-o-Matic, Map of  
420Life), and, with a separate sensor, plant water content and molecular identification  
421(SCiO). Numerous other apps are designed to enhance classroom learning, field  
422education, and citizen science (e.g., iNaturalist) (see Palumbo et al., 2012). A more  
423comprehensive list of apps relevant to field ecology can be found at  
424brunalab.org/apps, and custom apps can even be built to enhance the productivity of  
425field ecologists (Teacher et al., 2013).

## 4264.2     **Computation**

427Data collection is only the first step; processing and analyzing many gigabytes of data  
428from disparate sources requires new tools and techniques before ecological inference  
429or conservation planning can begin. Increasingly, scientists are finding it difficult to  
430avoid learning at least one programming language, and while the learning curve may  
431be steep, the flexibility and efficiency benefits can be enormous (see software-  
432carpentry.org for tutorials). As the scale of a project increases and the size of its  
433associated data soars, knowing which software language and computational tools to  
434rely on is important.

435 While the R language ([cran.r-project.org](http://cran.r-project.org)) has become the *de facto* standard for  
436 data analysis and visualization among many ecologists, it is neither built for handling  
437 and processing very large datasets, nor does it have full geospatial functionality.  
438 While there are packages that can speed up processing (`'renjin'`, `'Riposte'`), improve  
439 memory management (`'bigmemory'`), and smartly handle geospatial data (`'raster'`,  
440 `'rgdal'`), there are alternatives that are worth the time to learn. The Python language  
441 ([python.org](http://python.org)) offers increased speed, better memory management, and can function as  
442 an integration tool for your entire workflow. Extremely rapid processing and analysis  
443 of geospatial data can be accomplished with GDAL ([gdal.org](http://gdal.org)) and SAGA ([saga-  
gis.org](http://saga-<br/>444 gis.org)) commands called from Python. Moreover, while many of the following  
445 computational resources can be used within R, they interface with Python far more  
446 readily.

447 Machine learning (ML) algorithms (e.g., random forests, support vector  
448 machine, neural networks) are a powerful approach for analyzing large datasets with  
449 many (hundreds to thousands) dimensions. Rather than assuming a data model as in  
450 traditional statistical modeling, supervised ML techniques use algorithms to uncover  
451 relationships in the data through a learning process (Breiman, 2001). The advantages  
452 of ML algorithms include less reliance on statistical assumptions, no need for data  
453 reduction, and greater predictive accuracies while still generating inferences about the  
454 data (Hastie et al., 2009). The open source platform H2O ([h2o.ai](http://h2o.ai)) has a broad range of  
455 ML algorithms with highly efficient memory handling and the ability to easily scale-  
456 up analyses with parallel processing.

457 As the size and scale of a dataset increases, running analyses on a single  
458 computer processor becomes increasingly difficult. Most computers have multiple  
459 processors (CPUs) that are left idle when running an analysis. Parallel processing is a

460 technique that dramatically cuts processing time by using all available CPUs on a  
461 computer, or hundreds to thousands of CPUs on a computing cluster. Whether  
462 utilizing a personal computer or purchasing time on a high performance computing  
463 cluster (e.g., Amazon Web Services), the packages ‘foreach’ for R and  
464 ‘multiprocessing’ or ‘mpi4py’ for Python are good starting points.

## 4655.      **Integrated technologies for project scalability**

### 4665.1.    **Protected area management**

467 Protected areas are critical for long-term conservation of endangered species but their  
468 effectiveness depends on how well they are managed (Watson et al., 2013). Many  
469 parks suffer from funding shortages and insufficient numbers of rangers and guards,  
470 leaving them unable to adequately manage encroachment, fire, hunting/poaching, and  
471 other unsustainable resource harvesting (Bruner, 2001). However, even parks with  
472 relatively large staff may not meet targets set for reducing threats and protecting  
473 populations of endangered species (Venter et al., 2014). More must be done than  
474 simply putting extra boots on the ground. Here, we provide an example of an open-  
475 source software tool for improving effectiveness of protected areas through an  
476 adaptive management approach.

477        The primary form of field-based monitoring in parks around the world is  
478 ranger/staff patrols. Ranger patrols have various mandates including research and  
479 monitoring, community engagement, and implementing law enforcement. In each role  
480 ranger teams collect data using combinations of notebooks, datasheets, mobile  
481 devices, GPS and digital cameras. Patrol-based monitoring works by setting up a flow  
482 of data from the field useful for park management and patrol planning (Stokes, 2010).

483        A new technology that facilitates this process is the Spatial Monitoring and  
484 Reporting Tool (SMART), open-source software developed through collaboration

485among conservation agencies and organizations concerned with improving site-based  
486conservation area effectiveness (Fig. 3). Patrol teams can collect field data *via* an  
487Android or Windows Mobile-enabled smartphone, tablet or PDA, and upload and  
488manage the data through the SMART software. Users can create spatial queries and  
489summaries about patrol movements, human activities, wildlife, or significant habitat  
490features, and create custom reports. For example, how many foot patrols by a  
491particular team resulted in encounters with people involved in illegal timber cases?  
492Where did law enforcement teams record illegally killed elephant carcasses? A  
493planning module allows target setting for patrols, teams, stations, or the entire  
494conservation area, and monitor their progress towards achieving targets in real-time.  
495Observations of animal carcasses or other evidence of illegal activity derived from  
496local informants, researchers, tourists or the public can be added to the database and  
497linked to patrol plans. As of August 2015, SMART has been implemented at 213 sites  
498in 40 countries, with a number of national governments adopting SMART as a  
499standard for law enforcement monitoring ([smartconservationtools.org](http://smartconservationtools.org)).

500        Remote sensing tools can supplement SMART data, particularly where forest  
501loss or conversion is a primary threat. Landsat satellites acquire the same scene every  
50216 days, allowing images to be mosaicked to obtain cloud-free scenes. Each scene can  
503then be directly compared with scenes from the same or earlier seasons. When areas  
504of recent change are identified, the georeferenced image can be sent to law  
505enforcement teams to enable field inspection and follow up actions. These approaches  
506are useful for detecting deforestation on a range of scales from small (<10ha) to very  
507large (>10,000ha), and for certain kinds of degradation. They are, however, not  
508suitable for detecting low intensity forms of degradation such as firewood collection,  
509highly selective logging, or the gradual effects of over-burning in deciduous forest. If

510the suspected areas are very remote, a fixed-wing UAS can be sent to capture high-  
511resolution aerial photographs, helping authorities track down illegal loggers in  
512national parks and provide evidence for their conviction. Furthermore, UAS equipped  
513with a video camera can provide park rangers with real-time detection of wildlife  
514poacher campfire many kilometers away. Using a UAS facilitates rapid responses to  
515remote areas and a more comprehensive survey of the site than can be done from the  
516ground.

517        Dry season fires are a common feature of the ecology of tropical dry forests,  
518but are rare in denser evergreen and semi-evergreen forests. Therefore a cluster of fire  
519locations in a dense forest area may indicate fire being used during forest clearance.  
520FIRMS (Fire Information for Resource Management System) integrates remote  
521sensing and GIS technologies to deliver global MODIS (MODerate Resolution  
522Imaging Spectroradiometer) hotspot/active fire locations to natural resource managers  
523and other stakeholders. MODIS Rapid Response makes the data available on the web  
524within a few hours of satellite overpass ( $\geq 4$  times per day), while GEE provides daily  
5251 km resolution FIRMS maps.

526        These data can be downloaded and queried so that fire locations are only  
527shown within the areas previously mapped as dense forest, and far enough from the  
528nearest area of open forest or non-forest to account for low data resolution. The data  
529are then inspected to identify clusters of fires in the interior of dense forest, and  
530mobile ranger teams are directed to make an inspection and appropriate interventions  
531(Fig. 4).

532        WSN can provide significant support for surveillance and monitoring of  
533protected areas. They can be used to create virtual fences to detect intrusions by  
534humans, which can be covertly detected and reported to rangers who can decide on

535the appropriate response. WSN can also provide an early warning system for detecting  
536the movement of animals and allowing managers to potentially avoid human-animal  
537conflicts. This can build trust between protected area managers and local people, who  
538are often at odds with various management practices. Road networks in protected  
539areas can disrupt animal movement and lead to animal mortality from vehicle  
540collisions. WSN can be used as an early warning system to travelling vehicles,  
541avoiding or minimizing collisions. Finally, WSN can profile forest health and  
542potentially be used for population estimation if combined with other technologies.

543       Combining patrol and remote sensing monitoring tools, along with intelligence  
544derived from local informants is a model for protected area management that is  
545replicable and scalable across conservation sites. The core of the system is to conduct  
546regular field patrols with clearly defined strategic priorities, using local informant  
547networks to help guide activities. Camera-traps used by monitoring teams, especially  
548wireless models with capacity to instantly send recorded images of human intruders as  
549MMS or email attachments, can identify threat hotspots in order to optimally position  
550protection teams. Data on patrol activity should be analyzed using SMART to enable  
551effective management oversight of staff performance, patrol targeting, and threat  
552levels. Frequent inspection and comparison of Landsat images, while MODIS fire  
553hotspot data, are also recommended.

## 5545.2    **Ecological dynamics**

555Collection of long-term data is critical to uncovering patterns and processes in  
556ecology, but is usually limited in spatial scale, frequency, and/or duration. If  
557integrated properly, the technologies discussed in this article provide a way to begin  
558overcoming spatial and temporal limitations in ecological data collection. Here we



559 provide a generalized example of integrating each piece of technology to collect data  
560 from a remote forested ecosystem.

561       For a regional context, the surrounding land cover can be assessed using GEE  
562 to pull together a cloud-free mosaic of recent MODIS imagery. The GEE platform has  
563 built-in algorithms for creating a land-cover map that can set the broader context and  
564 assess potential threats for the area of study. A function could be built to examine  
565 forest gap dynamics by utilizing the long-running Landsat time-series. The 30 m  
566 resolution Landsat data (available as far back as 1982) can pick up large treefall gaps  
567 and storm blowdowns. The deployment of an airborne imaging system such as the  
568 CAO or the ASO (Airborne Snow Observatory), allowing an enormous improvement  
569 in spatial and spectral resolution, would be ideal for producing a detailed baseline  
570 understanding of the area. Plant functional and chemical diversity can be mapped *via*  
571 airborne imaging spectroscopy, while airborne LiDAR can produce 3D vegetation  
572 structure and accurate digital elevation models (Fig. 5). A combination of targeted  
573 deployment of a UAS and regular analysis of cubesat imagery provide additional  
574 platforms for temporal investigation. A UAS can be programmed to fly close to the  
575 forest canopy for increased imagery resolution. Forest phenology, tree species  
576 identification, and certain types of wildlife surveys could be accomplished with these  
577 technologies at far greater spatial scales and temporal frequencies than ground-based  
578 surveys alone. In fact, researchers have been able to detect orangutans and their nests,  
579 elephants, rhinoceros, forest buffaloes, and even turtle nests in UAS-acquired images  
580 (e.g., Wich, 2015).

581       The high upfront expense of airborne imaging makes it challenging to  
582 implement, but becomes cost-effective at scales around  $10^3 - 10^6$  ha. Similarly, any  
583 decision to deploy or utilize a remote sensing platform is context specific, and

584depends on the required scale, frequency, location, and type of data. In each case, the  
585relatively low cost of traditional field data collection should be calculated and  
586weighed against the generally more expensive but higher data yields of remote  
587sensing technology. Linking multiple platforms across different scales is an active  
588area of research (Joshi et al., 2016) that needs further development before wide  
589implementation by field ecologists and conservation practitioners.

590       With the exception of LiDAR, the sole use of remote sensing technologies will  
591not provide great insight into the below-canopy dynamics of a forest. Instead, ground-  
592based technologies can supplement remote sensing data across similar spatial and  
593temporal scales through innovative deployments. Using a mobile device equipped  
594with a GPS receiver, spatial features can be recorded in the field (e.g., hydrological  
595and geomorphological boundaries) and features identified in remote sensing imagery  
596can be verified (Barbosa et al., 2016; Marvin et al., 2016). Having multiple sources of  
597preprocessed imagery available on a mobile device streamlines the collection of notes,  
598the creation of vector (i.e., point, line, and polygon) data, and the capturing of  
599geotagged photos on fundamental characteristics of a site.

600       Once the basic spatial layout and features of a site are catalogued,  
601environmental data (e.g., rainfall, soil moisture, temperature, humidity, light) can be  
602captured using cheap sensors, allowing for a large, low-cost network of environmental  
603monitoring nodes. Even illegal logging can be detected in real time using re-purposed  
604cellphones (Gross, 2014). The extremely low power requirements for such sensors  
605may allow long-term, continuous operation *via* small solar panels – even in the forest  
606understory. More advanced sensors such as those with camera, audio, or video  
607capabilities might be more difficult to deploy in large numbers due to increased  
608expense and power requirements. When used in combination with camera traps and/or

609GPS tags on animals, these larger sensors can conduct wildlife community/population  
610surveys or acquire detailed data on species-specific behavior.

611       The deployment of sensors under a forest canopy, especially in closed canopy  
612tropical forests, makes remote acquisition of data difficult. Developing these sensors  
613as a WSN and using a UAS to periodically collect their data is a potential solution. In  
614this setup, the WSN transmits data among the sensors to a central data collection hub  
615placed either in a forest opening or in the forest canopy. A UAS could be dispatched  
616to fly over each hub and acquire the data, and programmed to transmit instructions  
617and code updates back to the WSN. Wider deployments of camera traps may be  
618enabled by using a UAS to download the pictures remotely. This approach would  
619drastically lessen the need for arduous trips to each sensor location for manual  
620downloads, with the added advantage of less human disturbance in sensitive areas.

621       All of the above examples allow for long-term (months-to-years) data  
622collection and observation of a single area of study. The low-cost and distributed  
623nature of a WSN combined with multi-resolution remote sensing data products allow  
624for a large ( $10^2$ - $10^5$  ha) area of study to be monitored in sufficient detail to offer new  
625insights into remote habitats.

## 6266.       **Conclusion**

627We offer a look at a range of established and emerging technologies that can be used  
628by ecologists and conservation practitioners to increase the spatial and temporal scales  
629at which they work. The spatial links between the data at each scale allows  
630researchers to increase the dimensionality of their datasets and perform spatially  
631explicit analyses and predictions. Most of the technology is low-cost and can be  
632readily used with some time investment into training and building. Collaborations

633with existing users and developers can speed up the process and lead to novel  
634applications or even altogether new technologies.

635       Of course, all of these technologies come with their obvious trade-offs and  
636challenges. Many advanced and high-resolution satellite sensors will be inaccessible  
637or remain very expensive to access. Airborne remote sensing of any type is not an  
638endeavor to be easily and quickly undertaken, and will likely require developing  
639partnerships with existing operators. UAS are often limited in their applications by the  
640payloads they can carry or the amount of time and/or distance they can fly. Lack of  
641access to reliable power sources will reduce the utility of any device that needs to  
642operate for very long periods while deployed in remote areas. The continued advance  
643in the performance of underlying technologies will solve many of these problems,  
644while other technologies may become less expensive as governments invest more in  
645technology research, commercialization, and transfer. It is critical for those  
646researchers and conservation practitioners new to these technologies to spend time  
647familiarizing themselves with all potential drawbacks. Every research and  
648conservation project is different, and it may be more cost-effective to invest in  
649additional personnel training and retention than a new technology deployment.

650       Finally, we do not mean to suggest that traditional field-based data collection  
651using transects or plots are no longer necessary or useful. Rare plant species  
652identification, soil and foliar chemical profiling, and microbial and genetic sampling  
653are all examples of crucial pieces of information needed to fully understand an  
654ecosystem, but are not currently accessible without manual, on-the-ground collection  
655by researchers. We encourage researchers to continue fully embracing and integrating  
656the technologies discussed here as a compliment to traditional methods when  
657designing their fieldwork. Deployment and refinement of these technologies will

658continue revolutionizing ecological and behavioral sciences, as well as conservation  
659management of natural systems and endangered species.

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**Fig 1. Images of some of the described technologies.** (Clockwise from top-left).

One type of fixed-wing UAS during a hand-held launch (Image: Jeff Kirby). Another type of fixed-wing UAS being prepared for deployment (Image: Sander van Anel). A multirotor UAS being inspected before deployment (Image: Jeff Kirby). A Planet cubesat with body measuring 10cm x 10cm x 10cm (Image: Planet). A tiger with GPS collar in India (Image: Ramesh Krishnamurthy). One node of a wireless sensor network used to detect illegal logging (Image: Rainforest Connection).

**Fig 2. Components and function of a hypothetical Wireless Sensor Network in**

**Addo National Elephant Park, South Africa.** An event is detected by a single sensor in the network, processed locally, and transmitted by radio among the network to a network hub. From there the event is sent to local users and a web server for remote users to monitor or analyze. Map data: Google, Digital Globe (2015).

**Fig 3. The SMART approach for turning ranger-based data into information**

**useful for park management and patrol planning.** Using an example from Cambodia, SMART creates flows of data in the form of point-based locations and observations from ranger patrols. After initial processing (debriefing and data entry), queries and data summaries, progress assessments, and reports can be output. Reports are interpreted by the site manager and fed-back to field enforcement teams.

**Fig 4. Deforestation in and around the Seima Protection Forest, Cambodia, from**

**Landsat analysis (1998-2011).** Forest fire locations in the buffer zone indicated by FIRMS (orange stars). Routes of ranger patrols that were conducted to investigate encroachment are indicated in black.

**Fig 5. Imagery from a variety of remote sensing platforms and sensors. a) True**

**color Landsat (source: Google Earth) image of a forested landscape in Madre de Dios,**



934Peru. b) Same as in a) but with CAO imaging spectroscopy overlay. c) Same as in a)  
935but with a CAO digital elevation model (elevation gain: blue to red) overlay. d)  
936Example true color image of Landsat 8 (30 m pixel resolution) from a forest in  
937Gabon. e) Example image of tree canopy chemical diversity derived from CAO  
938imaging spectroscopy (2 m pixel resolution) from a forest in Peru. f) Example true  
939color image from a UAS (10 cm pixel resolution) from a forest in Panama.

940**Table 1. Summary of select studies by technology type.**

<b>Technology</b>	<b>Country/ Region</b>	<b>Taxa/ Ecosystem</b>	<b>Application</b>	<b>Reference</b>
Satellite	Global	Forests	Forest cover change	(Hansen et al., 2013)
Airborne	Peru	Forests	Whole-country carbon density	(Asner et al., 2014)
UAS	Germany	Canopy trees	Assessment of flowering tree diversity	(Getzin et al., 2012)
GPS telemetry	South Africa & Kenya	Elephants	Real-time monitoring of elephant movements	(Wall et al., 2014)
Camera traps	Cambodia	Mammals	Habitat preference and activity patterns of 23 mammal species	(Gray and Phan, 2011)
WSN	New Mexico, United States	Shrubs	Microclimate variation in desert shrubs	(Collins et al., 2006)

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